SURVEYING INSTRUMENTS

SET2BI SET3BI SET4BI

OPERATOR'S MANUAL



• [English]	CONTAINS NICKEL-CADMIUM BATTERY. MUST BE RECYCLED OR DISPOSED OF PROPERLY.
• [Deutsch]	MIT NICH AKKU. EFORDERT RECYCLING ODER FACHGERECHTE ENTSORGUNG.
• [Français]	CONTIENT UNE BATTERIE AU CADMIUM NICKEL. DOIT ÊTRE RECYCLÉE OU DONNÉE A UN ORGANISME DE RETRAITEMENT.
• [italiano]	CONTIENE NICI BATTERIA. DEVE QUINDI ESSERE RICICLATA O ELIMINATA IN MODO APPROPRIATO.
• [Nederlands]	BEVAT EEN NICH BATTERIJ. DIENT GERECYCLEERD TE WORDEN OF OP EEN CORRECTE MANIER VERNIETIGD TE WORDEN.
• [Español]	CONTIENE UNA NICO BATERÍA. DEBE RECICLARSE O ELIMINARSE ADECUADAMENTE.
• [Português]	CONTEM BATERIA DE NÍQUEL CÁDMIO. DEVERÁ SER RECICLADA OU DECARTADA CONVENIENTEMENTE.
• [Svensk]	INNEHÅLLER NICd BATTERI. BÖR ÅTERVINNAS ELLER FÖRSTÖRAS PÅ ETT SÄKERT SÄTT.
• [Suomi]	SISÄLTÄÄ NIKKELI-KADMIUM AKUN. HÄVITETTÄESSÄ KÄSITELTÄVÄ ONGELMAJÄTTEENÄ.
• [Norsk]	NICd BATTERIER MÅ RESIRKULERES ELLER KASTES PÅ EN FORSVARLIG MÅTE.
• [Dansk]	INDEHOLDER NICH BATTERI. SKAL GENVINDES ELLER KASSERES PÅ FORSVARLIG MÅDE.
• [Ελληνικα]	ΠΕΡΙΕΧΕΙ ΜΠΑΤΑΡΙΑ ΝΙΚΕΛΙΟΥ-ΚΑΔΜΙΟΥ. ΠΡΕΠΕΙ ΝΑ ΑΝΑΚΥΚΛΩΝΕΤΑΙ Η ΝΑ ΚΑΤΑΣΤΡΕΦΕΤΑΙ ΜΕ ΤΟΝ ΚΑΤΑΛΛΗΛΟ ΤΡΟΠΟ.

For U.S.A. ATTENTION:

The product that you have purchased contains a rechargeable battery. The battery is recyclable. At the end of it's useful life, under various state and local laws, it may be illegal to dispose of this battery into the municipal waste stream. Check with your local solid waste officials for details in your area for recycling options or proper disposal. Use the standard battery charger.

Die Schweiz:	Nach Gebrauch der Verkaufsstelle zurückgeben.
La Suisse:	Après usage à rapporter au point de vente.
Swizzera:	Ritornare la pila usate al negozio.

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SURVEYING INSTRUMENTS

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SET2B近 SET3B近 SET4B近 Electronic Total Station

5

OPERATOR'S MANUAL

Congratulations on your purchase of the SET BII Series! Before using the instrument, please read this operator's manual and verify that all equipment is included, refer to P. 196 "STANDARD EQUIPMENT".

A version



QUICK GUIDE TO THIS MANUAL			
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- </mportant>

The battery has not been charged at the factory. Please charge the battery fully before using.

- <Important>



Tribrach clamp locking screw

When the new SET B is shipped, the tribrach clamp is fixed with a screw.

Loosen it and leave it loose.

And if the SET B is again shipped, fix the tribrach clamp with the screw to stop the tribrach becoming detached from the instrument.

The specifications and general appearance of the instrument may be altered at any time and may differ from those appearing in catalogues and this operator's manual.



< SET BII ADVANCED MEASUREMENT FUNCTIONS >

- Resection measurement
- Traverse-style coordinate measurement
- Offset measurement
- REM measurement

- Missing line measurement
- Setting-out measurement

< COORDINATE DATA CAN BE STORED IN AN INTERNAL MEMORY >

- 100 coordinate data can be stored in an internal memory for about a week.
- These coordinate data can be used as instrument station coordinates, backsight station coordinates, known station coordinates (for the resection measurement), and setting-out coordinates.
- These coordinate data can be displayed.

< TILT ANGLE COMPENSATION >

- Dual axis tilt sensor
- The index error of the tilt angle can be eliminated

< COLLIMATION PROGRAM >

 The collimation error between the centre of the telescope reticle and the sighting line can be calculated, and the correction value specified is set. (for angle measurement of high accuracy.)

< DATA OUTPUT >

 The SET B RS232C-compatible data output connector allows 2way communication with an external device. INTRODUCTION

1. PRECAUTIONS	_ℬ P.5
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5. DISPLAY SYMBOLS	-∕æ P.13

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- Never place the SET B directly on the ground. Avoid damaging the tripod head and centring screw with sand or dust.
- Do not aim the telescope at the sun. Avoid damaging the LED of the EDM.

- Protect the SET B with an umbrella. against direct sunlight, rain and humidity.
- Never carry the SET B on the tripod to another site.
 - Handle the SET B with care. Avoid heavy shocks or vibration.
 - When the operator leaves the SET B, the vinyl cover should be placed on the instrument.
- Always switch the power off before removing the standard battery.
 - Remove the standard battery from the SET B before putting it in the case.
- When the SET B is placed in the carrying case, follow the layout plan.
- Make sure that the SET B and the protective lining of the carrying case are dry before closing the case. The case is hermetically sealed and if moisture is trapped inside, damage to the instrument could occur.

2. PARTS OF THE INSTRUMENT



- Handle
- e Handle securing screw
- Instrument height mark
- Ø Sub display
- 6 Main display
- 6 Lower clamp
- Lower clamp cover
- O Tribrach clamp
- Oircular level

- Circular level adjusting screws
- Base plate
- Develling foot screw
- Tribrach
- Horizontal circle positioning ring
- Keyboard
 Keyboard
- Objective lens



- Tubular compass slot
- Battery BDC25
- Optical plummet focussing ring
- Ø Optical plummet eyepiece
- Ø Power switch
- Horizontal clamp
- Horizontal fine motion screw
- Data output connector
- External power source connector

- Plate level
- Plate level adjusting screw
- Ø Vertical clamp
- Ø Vertical fine motion screw
- Telescope transitting knob
- Telescope eyepiece
- Telescope reticle adjustment cover

- Telescope focussing ring
- Ø Peep sight

Shift functions \leftarrow Numeric input \leftarrow Main functions \leftarrow

. KEY FUNCTIONS

Shift functions \leftarrow Numeric input \leftarrow Main functions \leftarrow

Shift functions \leftarrow Numeric input \leftarrow Main functions \leftarrow



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<Main functions>



<Shift functions>









- < ITT +>: Hold/Release Horizontal angle
 (Data input mode): Input "2"
 Program mode: Resection/Correction/ Set Instrument station coordinates and azimuth angle
 - < 🔛 +>: Offset measurement
 - (Data input mode): Input "9"

Measure Height difference



- O < STATE + > : Set Azimuth angle from Instrument station and Backsight station coordinates
- (Data input mode): Input "6"
- Missing line measurement



n

No

CE·CA

Yes

• (Data input mode): Input "3"

 Transfer to Theodolite mode / Display tilt angle (when instrument is in Theodolite mode and: "Tilt correction" parameter is on)

- < SHEFT + > : Return signal check(stop: SHEFT)
 Display and Reticle illumination ON/OFF
 - Input "No"
 - (Data Input mode): Clear input data
- Stop measurement and transfer to Basic mode/ Exit from mode
 - Input "Yes"
 - (Data input mode): Input data into memory
- Select/Release Shift mode





<Sub display>

ppm/P.C./MODE

	-
	a Barris
V1	

ppm(.	Atmospheric correction value)
P.C.(F	rism constant correction value)
1+	: Tilt angle compensation on

SHFT : Shift

AMBOLS

- : Setting-out measurement mode
- MENU : Menu mode
- PROG : Program mode
- REC : Record mode
- RCL : Recall mode
- Stn : Instrument station coordinates BS
 - : Backsight station coordinates
 - : Coordinate setting-out data

<Main display>

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SO

- : Select options S Н : Zenith angle (Z 0°) ZA v VA : Vertical angle (H 0°) Ht Vertical angle (H 0°±90°) D HAR : Horizontal angle right HAL : Horizontal angle left HARp: Horizontal angle repetition HAh : Horizontal angle hold dHA : Horizontal angle from setting-out data х : Tilt angle in sighting direction Y : Tilt angle in horizontal axis direction
- : Slope distance
- : Horizontal distance
- : Height difference
- : REM value/Instrument height/Target height
- : Distance setting-out data/ Offset distance



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PREPARATION FOR MEASUREMENT 6 MOUNTING THE BATTERY - **₽.17** æ P.18 7. SETTING UP THE INSTRUMENT 7.1 Centring (Levelling (7.2 æ P.21 POWER ON 8. 9. PREPARATION FOR MEASUREMENT *ॠ* P.23 Indexing the vertical and horizontal circles @ 9.1

- 9.2 Focussing and target sighting @
- 9.3 Display and reticle illumination @
- 9.4 Setting the Instrument options @



- MOUNTING THE BATTERY
- Charge the battery fully before measurement. g P.177
- Note: Turn off the power supply switch **@**before replacing the battery.



/ cover

Battery release

└─── Guide pin

BDC25/25A



< Mounting the battery >

- 1) Close the battery release button cover.
- Match the battery guide with the hole in the instrument battery recess.
- Press the top of the battery until a click is heard.

< Removing the battery >

- 1) Open the battery release cover.
- 2) Press the release button downward.
- 3) Remove the battery.
- If the power is to be turned on immediately after replacing the battery, please refer to P. 21.

- SETTING UP THE INSTRUMENT
- Mount the battery in the instrument before performing this operation, because the instrument will tilt slightly if the battery is mounted after levelling.

7.1 Centring

Set up the tripod

© Level © Firmly fixed © Survey point

Install the instrument



Focus on the surveying point

- Make sure the legs are spaced at equal intervals and the head is approximately level.
- Set the tripod so that the head is positioned over the surveying point.
- Make sure the tripod shoes are firmly fixed in the ground.
- 4) Place the instrument on the tripod head.
- Supporting it with one hand, tighten the centring screw on the bottom of the unit to make sure it is secured to the tripod.

- Turn the optical plummet focussing ring to focus on the surveying point.

7.2 Levelling

Centre the surveying point in the reticle

- Coptical plummet
- Adjust the levelling foot screws @ to centre the surveying point in the optical plummet reticle.

Centre the bubble in the circular level



- Observe the off-centre direction of the bubble in the circular level , and shorten the nearest tripod leg, or extend the leg farthest from that direction to centre the bubble.
- One more tripod leg must be adjusted to centre the bubble.

Centre the bubble in the plate level





- 5) Centre the air bubble, using levelling screws A and B.
 - Note: The bubble moves towards a clockwise rotated foot screw.

Turn 90° and centre the bubble



6) Turn the upper part of the instrument through 90°.

The plate level is now perpendicular to a line between levelling screws A and B.

7) Centre the air bubble, using levelling screw C.

Turn another 90° and check bubble position

8)



Turn the upper part of the instrument a further 90° and check to see if the bubble is in the centre of the plate level **@**.

If the bubble is off-centre, perform the following:

- ① Adjust levelling screws A and B in equal and opposite directions, to remove half of the bubble displacement.
- ② Turn the upper part a further 90°, and use levelling screw C to remove half of the displacement in this direction.

Or try the adjustment described on P.149, under "22.1 Plate level".

Check to see if bubble is in same position in any direction

 Turn the instrument and check to see if the air bubble is in the same position for any position of the upper part.

If it is not, repeat the levelling procedure.

Focus on the centre of the reticle again



- 10) Loosen the centring screw slightly.
- 11) Looking through the optical plummet eyepiece, slide the instrument over the tripod head until the surveying point is exactly centred in the reticle.
- Retighten the centring screw securely.

Check plate level bubble again

13) Check again to make sure the bubble in the plate level is centred. (If not, repeat the procedures starting from step 4).)



 When the power is turned on, a self-check is run to make sure the instrument is operating normally.

(Turn on the power)

WEBON



- Turn on the power switch @ after completing sections 6 and 7.
- The instrument name, instrument number, and software version are displayed for several seconds, an audio tone sounds, and the instrument performs self-diagnostic checks.

On successful completion of the checks, "Self check ok" is displayed for 2 secs.

- Note: After power-off for more than 1 week, the previously stored data have been cleared from the short-term memory and "Memory cleared" is displayed.
- The remaining battery power is then displayed for 3 seconds as a numeric value.

(BDC25, Coarse meas. mode, Single meas., Temperature 25°C.)

If the battery is at the "low" level, the message "Battery is low" will be displayed, and an audio tone sounds. Turn the power off and charge the battery.

If the battery power becomes low during surveying, the same message will be displayed.

ZA	0	SET	
HAR	0	SET	
		.	
Out of	rang	 e	
Out of X	rang >⊥	 e <	

- 4) This display indicates that the instrument is ready for vertical and horizontal circle indexing.
- If the parameter horizontal indexing is set to "Manual", a horizontal angle of 0° is displayed, when the power is turned on.

If this error message is displayed, the instrument tilt sensor is indicating that the instrument is offlevel. Relevel the instrument once again, using the plate level bubble.

 When "Face 1" is displayed for the vertical angle, please refer to P.183 (Appendix 1: Manually indexing the vertical circle).

[Note: Changing the brightness of the display]

• If the display appears too dim or too bright, the keyboard can be used to adjust the brightness level (6 levels).

For a brighter display \to Press (BHF) and (FC) at the same time .

For a dimmer display \rightarrow Press sign and sign at the same time .

[Note: Power-saving cut-off]

• SET B switches off automatically 30 minutes after the last key operation.

— Instrument parameter No.12 ᡒ P.167

 Parameter No.12 can be changed so that the SET B will not switch off automatically after 30 minutes.



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EPARATION FOR MEASUREMENT

9.1 Indexing the vertical and horizontal circles

(H and V circle indexing parameters - "Auto")

Vertical circle indexing

- Loosen the vertical clamp @ and transit the telescope completely. (Indexing occurs when the objective lens crosses the horizontal plane in face left.)
- 2) An audio tone sounds, and the vertical angle (ZA) is displayed.

Vertical indexing has been completed.

- 3) Loosen the horizontal clamp @ and rotate the upper part of the instrument completely.
 (Indexing occurs when the plate level @ passes the 0 mark of the
 - horizontal positioning ring.)4) The audio tone sounds, and the horizontal angle (HAR) is displayed.

Horizontal indexing has been completed.

Note: Each time the instrument is switched on, the vertical and horizontal indexes must be redetermined.





° 04' 30"

350° 39' 00"

Horizontal circle indexing

91° 04' 30"

0 SET

ZA HAR

ΖA

HAR



[Note: Horizontal angle back-up]

- The parameter No.9 default setting allows for the memorization of the previous horizontal 0 position at power-off for about 1 week. ("Memory cleared" is displayed after more than 1 week of power off.) H and V circles are each provided with a 0 index. When next switching on the SET B and indexing the horizontal circle again, the horizontal angle is recovered at the previously-memorized 0 position. This feature is useful when the battery voltage becomes low during measurement or after automatic power-off has occurred.
 - 🗕 Instrument parameter No. 9 🚁 P. 167
 - Parameter No.9 can be used to change the horizontal circle indexing method. Options are indexing by rotating the upper part or indexing and zero setting at power-on.

[Note: Automatic tilt angle compensation]



- When the ⊥+ symbol is shown on the subdisplay, the vertical and horizontal angles are automatically compensated for small tilt errors using the 2-axis tilt sensor.
- Read the compensated angle after the displayed angle value becomes steady.
- The formula used for calculation of the compensation value applied to the horizontal angle uses the tilt and vertical angles as shown below:

Compensated Heasured + Tilt in angle Y horizontal angle + horizontal angle + tan(Vertical angle)

Therefore, when the SET B is not perfectly levelled, changing the vertical angle by rotating the telescope will cause the displayed (compensated) horizontal angle value to change. (The displayed horizontal angle value will not change during telescope rotation when the instrument is correctly levelled.)

- When the measured vertical angles are within ±1° of the zenith or nadir, tilt compensation is not applied to the horizontal angle. In this situation, the displayed horizontal angle value flashes to show that the tilt compensation is not being applied.
 - --- Instrument parameter No.3 🖅 P.167
 - Parameter No.3 can be used to switch off and on the automatic tilt angle compensation; for example, the automatic compensation should be switched off if the display is unsteady due to vibration or strong wind.

[Note: Levelling using the tilt angle display]

For levelling, the tilt angle X and Y values can be displayed for use as a 2-axis (X,Y) tilt sensor. The tilt angle values are used to automatically correct the vertical and horizontal angles for error due to the non-verticality of the vertical axis. The measurement range is $\pm 3'$. The "Tilt correction (Dual axis)" parameter must be set to "Yes".



Tilt angle display

Tilt an	gle		
х	0°	01'	20"
Y	-0°	00'	40"

 X: Levelling foot screws AB
 Y: Levelling foot screw C (in above illustration)

Tilt	angle minimum display unit
	SET2B:1"
	SĖT3B:1"
	SET4B:5"





To Theodolite mode To Basic mode

- In Theodolite mode, turn the upper part of the instrument until the telescope is parallel to a line between levelling foot screws A and B and tighten the horizontal fine motion screw @.
- 2) Press 📑
- 3) The X and Y tilt angles are displayed.
 - X : Tilt angle in sighting axis direction
 - Y : Tilt angle in horizontal axis direction
- Set both tilt angles to 0° by turning the levelling screws A and B for the X direction and C for the Y direction.
- "Out of range" indicates that the tilt angle exceeds the ±3' measurement range.
- 5) To exit from the tilt angle display, press it to return to Theodolite mode or press it to go to Basic mode.

9.2 Focussing and target sighting

Focus on the reticle



Sight the target

Line the target with the white arrow in the peep sight

- Turn the eyepiece clockwise, then counterclockwise little by little until just before the reticle image goes out of focus.

Using this procedure, frequent reticle refocussing is not necessary, since your eye is focussed at infinity.

- Loosen the vertical @ and horizontal @ clamps, and use the peep sight @ to bring the target into the field of view.
- 4) Tighten both clamps.
- 5) Turn the focussing ring @ to focus on the target.
- Turn the vertical @ and horizontal
 @ fine motion screws to align the target object with the reticle.

The last adjustment of each fine motion screw should be in the clockwise direction.



< Target centre>



<Prism centre>

- The relation between the target and the reticle is shown in the illustration at the left.
- First, align the measuring point precisely with the centre of the target.

Then align the reticle precisely with the centre of the target.

- Note: Observe to the same point of the reticle when the telescope face is changed.

[Note:Parallax]

 This is the relative displacement of the target image with respect to the reticle when the observer's head is moved slightly before the eyepiece.

Parallax will introduce reading errors and must be removed before observations are taken. Parallax can be removed by refocussing.

9.3 Display and reticle illumination

(Illuminate the display and reticle)

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Press the 🔅 to turn the display and reticle illumination on and off.



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- Instrument parameter No.13 🚁 P.167
- Parameter No.13 can be used to switch ON/OFF the 30-second illumination automatic cut-off facility.





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9.4 Setting the Instrument options

- Confirm that these parameters, indispensable for measurement, are set according to your required measurement.
- Data storage period : Until next changing (Power-off possible)
- To confirm or change the parameter options, please refer to P.167 "23. CHANGING INSTRUMENT PARAMETERS".

No.		Parameter		Options
3	Tilt co	It correction		Correction YES* / Correction NO
4	Coord	inate forma	t	N, E, Z*/E, N, Z
5	Vertic	al angle forr	mat	Zenith angle (zenith 0°) * /
				Vertical angle (horizontal 0°) /
				Vertical angle (horizontal 0° ± 90°)
6	Angle resolution		SET2B	1" (0.2 mgon) * / 5" (1 mgon)
	SE		SET3B	1″ (0.2 mgon) * / 5″ (1 mgon)
			SET4B	5" (1 mgon) * / 10" (2 mgon)
10	C + R (+ R correction		No correction * /
				Yes K = 0.142
				YesK= 0.20 🚓 P. 191
11	1 D	Distance unit		metres*/feet
	2 A	Angle unit Temperature/Pressure units		360°* / 400gon
	3 T			°C & hPa */°C & mmHg/°F & hPa/
	u			°F & mmHg/ °F & inchHg

* Factory setting

 For other parameters, please refer to P.167 "23. CHANGING IN-STRUMENT PARAMETERS".



MEASUREMENT

10 ANGLE MEASUREMENT

- Measure the horizontal angle between two points @ 10.1 <Horizontal angle 0>
- Set Horizontal circle to a required value @ 10.2
- Horizontal angle display @ 10.3 <Angle right/left/repetition/hold>

11. DISTANCE MEASUREMENT

- Measurement mode selection @ 11.1
- 11.2 Prism constant input @
- 11.3 Atmospheric correction @
- 11.4 Returned signal checking @
- Slope distance/Horizontal distance/ 11.5 Height difference measurement @
- Review of measured data 6 11.6

12. COORDINATE MEASUREMENT

- 12.1 Measurement mode selection 60
- Instrument height and target height input @ 12.2
- 12.3 Instrument station coordinates and backsight station coordinates input @
- 12.4 Setting the azimuth angle from Instrument and backsight station coordinates @
- 3-Dimensional coordinate measurement @ 12.5

☞ P.42

æ P.56

~ P.33





🗑 , ฎ , 🔹 • Measure the angle between two points.



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10.2 Set Horizontal circle to a required value

• Set the horizontal circle of the target direction to a required value.



Sight target R
 Using the horizontal clamp on an



) Using the horizontal clamp @ and fine motion screw @. Sight target R.

From Theodolite mode or Basic mode to H Angle Input mode



 In Theodolite mode or Basic mode, press .

> The display appears as at left, and "HAR" flashes to prompt for the input of the horizontal angle value.



Input "60.002".

ENT SHFT

ZA	90°	30'	00"
HAR	60°	00'	20"

 4) Press me to finish inputting. The instrument returns to Theodolite mode. Here, the horizontal angle for target R has been set to 60° 00'20".

10.3 Horizontal angle display < Horizontal angle right/left/repetition/hold >

2











The following preparations are required for Distance measurement.

EMEAQUE

- 11.1 Measurement mode selection
- 11.2 Prism constant input
- 11.3 Atmospheric correction
- 11.4 Return signal checking
- 11.1 Measurement mode selection
 - Select the measurement mode from the following according to your required measurement.

Measurement mode		Measurement time (slope distance)	Units
	Single	4.7 secs	
Fine meas.	Repeat	First 4.7 secs & every 3.2 secs	1mm
Coarse meas.	Single	1.7 secs	
	Repeat	First 1.7 secs & every 0.7 secs	
Tracking meas.		First 1.6 secs & every 0.3 secs	10mm







11.2 Prism constant input

- Each reflecting prism type has a different prism constant value. Here, we will input the constant correction value for the reflecting prism being used.
- The prism constant correction values for reflecting prisms made by Sokkia are as follows:

AP01

AP01S+AP01

CP01



30 mm \rightarrow lnput"-30". 40 mm \rightarrow lnput "-40". 0 mm \rightarrow lnput "0"



🗑 🖉 🖉 🔹 🔹 Set a prism constant of 40 mm (correction value: -40)





A prism constant correction value of –40 is input.



3. ppm

-

4) Press ENT .

The correction value is input, and the instrument returns to Preparation mode.

The entered value is displayed on the second line of the sub-display.

CE-CA : To Basic mode

 To return to Basic mode after this, press



11.3 Atmospheric correction

- **Note**: To obtain the average refractive index of the air throughout the measured light path, you should use the average atmospheric pressure and temperature. Take care when calculating the correction factor in mountainous terrain.

P.189, Appendix 3

- The SET B is designed so that the correction factor is 0 ppm for a temperature of +15°C (+59°F) and an atmospheric pressure of 1013 hPa (29.9 inch Hg).
- By inputting the temperature and pressure values, the correction value is calculated and set into the memory. The formula used is as follows:

ppm = 278.96 - $\frac{0.2904 \times P (hPa)}{1+0.003661 \times T (^{\circ}C)}$

- To input ppm value, read the correction factor from the table on P.202.
- For precise distance measurement, relative humidity should be taken into account together with atmospheric pressure and ambient temperature. See P.189.



Source of and Atmospheric pressure of 1010 mbar



Select the input of Temperature and (atmospheric) Pressure



	15	°C
Ρ.	1013	hPa

3) Press 2

The previously stored values are displayed.

"T" flashes to prompt for the input of the temperature.



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N 755 CQED





Input Temperature and Pressure



 Input "20" and press [ENT].

> The temperature "20°C" is input. "P" flashes to prompt for the input of the pressure.

5) Input "1010" and press []]. The pressure "1010 hPa" is input, and the instrument returns to Basic mode.

> The atmospheric value coefficient is calculated, and is displayed on the first line of the subdisplay.

11.4 Return signal checking

- Especially for long distances, it is useful to check that the returned signal is adequate for measurement.
- Note: When the light intensity coming back from the reflecting prism is very high (short distance) an asterisk "*" may be displayed, even for a slight mis-sighting. Therefore make sure that the target centre is sighted correctly.

L. K



---- Instrument parameter No. 14 gr P.167 ------Parameter No. 14 can be used to switch on / off the returned signal audio tone.

<u>11.5 Slope distance / Horizontal distance /</u> Height difference measurement

• The slope distance, the horizontal distance, and the height difference are measured simultaneously with the angle.

CheckI before measurement :	
1 SET B is set up correctly over the surveying	<i>a</i> ₽ P.18
2. The V and H circles have been indexed. 3. The instrument parameters and the units	.சு. P.23 சு. P.29
have been set. 4. The distance measurement mode is selected. 5. The prism constant correction value is set. 6. The atmospheric correction is set.	☞ P.42 ☞ P.45 ☞ P.48
 The centre of the target is correctly sighted and the return signal is adequate for measurement. 	<i>3</i> ₽ P.52

Start the measurement from Theodolite mode or Basic mode

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an an Al	
s	234.567m
ZA	81°12'30"
HAR	12°23'40"

1) In Theodolite mode or Basic mode,

press 🏹 , 🛃 or 🛃 .

This accesses the Distance measurement mode, and the distance measurement is started. The display appears as at left and flashes. (The illustration at the left shows an example of slope distance measurement.)

After about 4.7 seconds (Fine measurement mode), the distance value, the vertical angle and the horizontal angle are displayed.

Stop the measurement

: Stop



After 2 minutes

S	Timeout
ZA	81°12'30"
HAR	12°23'40"

	f/m	
ENT	5	: Change
_		metre ↔ feet

s	769.57 ft		
ZA	81°12'30"		
HAR	12°23'40"		

- 2) Press' (2) . (The display does not change.)
 - If the single measurement mode has been selected, measurement stops automatically.
- Note: If "Signal off" is displayed, the return signal strength has become inadequate for measurement. Verify the target sighting. If within 2 minutes the return signal becomes sufficient, the measurement is restarted.

After 2 minutes, the measurement is stopped automatically and the display appears as at left:

In this case, sight the target again and restart the measurement. (The same display appears during measurement if the return signal is too weak. Press to stop measurement and sight the target again.)

 Press ENT SHE



to change the distance unit for 5 seconds.

11.6 Review of measured data

• The distance and angle measured most recently are stored in the memory until the power is turned off. The stored slope distance, horizontal distance and height difference can be displayed in Recall mode as follows.



 The SET B calculates the 3-Dimensional coordinates of the prism position. To calculate the Z (Height) coordinate, first enter the instrument and target heights, then the Instrument station coordinates.

COORDINATE MEAS



- By inputting the Backsight station coordinates, sighting the backsight station and pressing a key on the SET B keyboard, the horizontal angle can be set to the azimuth value.
- The following preparations are required for Coordinate measurement.
 - 12.1 Measurement mode selection
 - 12.2 Instrument height and target height input
 - 12.3 Instrument station coordinates and Backsight station coordinates input
 - 12.4 Setting of azimuth angle from the instrument and backsight station coordinates.
- 12.1 Measurement mode selection
- Select the measurement mode from the following according to your required measurement.

See P.42 "11.1 Measurement mode selection " for key operation.

Measurement mode		Measurement time (slope distance)	Units
	Single	5.1secs	
Fine meas.	Repeat	First 5.1 secs & every 3.3 secs	
Coarse meas.	Single	2.4 secs	
	Repeat	First 2.4 secs & every 0.7 secs	
Tracking meas.		First 2.2 secs & every 0.7 secs	10mm



12.2 Instrument height and target height input

- As preparation for coordinate measurement, the instrument height (the height difference between the surveying point and the instrument station height mark ③) and target height (the height difference between the surveying point and the centre of the target) should be input to the SET B before the measurement.
- The heights of the instrument and the target are measured manually beforehand, using a measuring tape, etc.



 ● Input Instrument height of 1.567 m and Target height of 1.234 m

From Theodolite mode or Basic mode to Instrument Height Input mode



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12.3 Instrument station coordinates and Backsight station coordinates input

- The coordinates of the instrument setting surveying point (instrument station) and those of a point whose coordinates are already known (backsight station) can be input to the SET B.
- The coordinates of the backsight station are input in order to set the horizontal angle in the X-axis direction to 0°.
 If the azimuth angle is already known, the following steps are carried out:
 - 1) Input only the coordinates of the instrument station.
 - 2) Sight the backsight station.
 - angle to the azimuth value.

Then skip the instructions in Section 12.4 and go directly to Section 12.5.

• To recall the instrument station coordinates and backsight station coordinates from coordinate data stored in the memory, please refer to P.118.





2 2















 Instrument station coordinates are e.g. N = 31.1, E = 21.2, and Z = 1.3, and Backsight station coordinates are N = 10.1, E = 20.2, and Z = 3.3



Input "31.1" and 3) press [] .

> The N coordinate is input. "E" flashes to prompt for the input of the E coordinate.

: Input N coordinate

31,100

0.000

0.000

Ν

Ē

z



4) Input "21.2" and press

The E coordinate is input. "Z" flashes to prompt for the input of the Z coordinate.

5) Input "1.3" and press

The Z coordinate is input, and the instrument returns to Coordinate input mode.





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The displayed value is retained, so simply press "Z" flashes to prompt for the in-

Input "3.3" and

The Z coordinate is input, and the instrument returns to Coordinate 57

to return to Basic

mode.


12.4 Setting the azimuth angle from Instrument and Backsight station coordinates



• With the SET B, the azimuth angle of the backsight can be automatically calculated from the input instrument station and backsight station coordinates. This means the horizontal angle is set to zero in the N direction.



12.5 3- Dimensional coordinate measurement

 The coordinates of the target are calculated using the following formulas and the results are then displayed. It is first necessary to input the Instrument and prism heights, Instrument and Backsight station coordinates and calculate or input the azimuth angle (see previous pages).

> N1 = N0 + S x sin θ z x cos θ h E1 = E0 + S x sin θ z x sin θ h Z1 = Z0 + Mh + S x cos θ z -Ph

Instrument station coordinates: (No, Eo, Zo)

Slope distance	: S
Zenith angle	:θz
Azimuth angle	: θh
Instrument height	: Mh
Target height	: Ph



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CheckI before measurement:	na alter de la service la constante de la service
 SET B is set up correctly over the surveying point. 	<i>a</i> ₽ P.18
2. The V and H circles have been indexed,	- P.23
The instrument parameters and the units have been set.	<i>a</i> ₽.29
4. The distance measurement mode is selected.	_ 3 ₽ P.42
5. The prism constant correction value is set.	<i>3</i> ₽.45
6. The atmospheric correction is set.	- ₽.48
The centre of the target is correctly sighted and the return signal is adequate for measure	P.52
 The instrument height and target height have been input. 	<i>⊴</i> ₽ P.57
The instrument station and the backsight station coordinates have been input.	<i>⊴</i> ₽ P.60
10.The azimuth angle is set.	<i>3</i> ₽ P.65

Sight the target

Sight the centre of the reflecting 1) prism correctly. (It is also recommended to check the returned * *

3

signal by pressing page 52.)



In Theodolite mode or Basic mode, start the coordinate measurement



N	123.456
E	345.678
Z	3.456

Stop the measurement



: Stop the measurement



: Start next measurement

Review the

measured data

- CE-CA
- 🚠 : To Theodolite mode

In Theodolite mode or Basic 2) mode, press 🔛 . This accesses Coordinate Measure-

ment mode, and measurement of the 3-Dimensional coordinates is started. The display appears as at left and flashes.

After about 5.1 seconds (Fine measurement mode), the 3-Dimensional coordinates are displayed.



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- Press (display does not 3) change).
 - If the single measurement mode has been selected, the measurement stops automatically.
 - Press 🏹 , 🛃 , 🚰 or 🛃 to start the next measurement. ICE-CA Pressing returns to Basic mode, or press 📩 to go to Theodolite mode.
- To measure the next target point, check the prism constant correction, ppm values, and target height.
- If and are pressed, the last measured coordinate data can be displayed. a P.55





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ADVANCED MEASUREMENT FUNCTIONS

13. RESECTION MEASUREMENT	_ℬ ₽.71
※ ラント	
14. TRAVERSE-STYLE COORDINATE MEASUREMENT	_≇ ₽.80
[19] · · · · · · · · · · · · · · · · · · ·	
15. OFFSET MEASUREMENT	<i>₃</i> ₽ ₽.84
16. REM MEASUREMENT	<i>₃₽</i> .90
17. MISSING LINE MEASUREMENT	<i>₃</i> ₽.94
 17.1 Measurement mode selection ⁽¹⁾ 17.2 Measuring the distance between two or model 17.3 Change of the initial starting position ⁽¹⁾ 	ore points 🤀
18. SETTING-OUT MEASUREMENT	<i>₃</i> ₽.100
18.1 Horizontal angle and distance setting-out measurement	

18.2 Coordinates setting-out measurement 🕲



• The "Resection measurement" is used to determine the instrument station coordinates by observing 2 or more known stations.



- SET B can calculate the instrument station coordinates by method of least squares by observing 2 to 5 known stations.
 - To calculate the instrument station coordinates;
 - when measuring distances, observe at least 2 known stations.
 - or

when unable to measure distances, observe at least 3 known stations.

However, the greater the number of known stations and the greater the number of measured distances, the more precise the results will be.

- The Z coordinate can be calculated by inputting the Z coordinate of at least 1 known station and measuring the distances of 2 or more points. (The Z coordinate cannot be determined using only angle measurement.) Before the resection measurement, input the instrument height.
- Note: For the Resection measurement of highest accuracy, please adjust the collimation error beforehand. See P.184 "Appendix 2: For Angle measurement of the highest accuracy, <Adjusting the collimation error by collimation program>".
- To recall the known station's coordinates from coordinate data stored in the memory, please refer to P.118.



 It is best to avoid a situation where the unknown station (Instrument station) lies on the same circle as the known stations (in the case of 3 more known stations). Nullification of calculation will result. The figure below describes the better arrangement.



- Unknown station (Instrument station)
 Known station
- Note: When calculating the instrument station coordinates by only measuring the angles of three known stations, if a station is on the same circle as the known stations, the calculated station coordinate will not be correct.



If this situation is expected, the following action is suggested.

- 1) If possible move the station to the near centre of the triangle or
- Observe other known stations which are not on the circle or
- Measure the distance of one of 3 stations along with the angles.



• If the angle between 2 known stations is narrow, the observing condition is not sufficient to calculate the instrument station coordinates. When the distances between the instrument station and the known stations are long, it is difficult to determine that the angles are narrow thereby avoiding that the instrument station being on the same circle as the known points.









• The instrument station coordinates will be determined
 from the following data:

Instrument height:	1.5m
Known Station A:	Point number = 1 N = 2042.104, E = 1376.491, Z = 116.720. Measure angle and distance Target height is 1.5 m
Known Station B:	Point number = 2 N = 1608.521, E = 2426.262, Z = 251.200. Measure angle
Known Station C:	Point number = 3 N = 862.988, E = 1554.186, Z = 101.240 Measure angle and distance Target height is 1.5 m





Target number "1" is input. "N" flashes to prompt for the input of the N coordinate.

Input the coordinates for Known

N =	2042.104	SHFT
E =	1376.491	ENT SHFT
7 -	116 72	ENT

The display then asks whether to measure its distance or not.

- The display appears as at left. "Ht" flashes to prompt for the input of the target height. If measuring angle only,
- Press , , store , stor When the data for the first station has been input, "No." flashes to prompt for the input of the point number of the next known sta-

(The previously stored value +1 is

The displayed value is retained, so simply press

The point number "2" is input. and "N" flashes to prompt for the input of the N coordinate.







12) Press ENT .

The display appears as at left. "Ht" flashes to prompt for the input of the target height.

(The previously stored target height is displayed.)

If measuring angle only,



13) Press SHET .

When the data for the third station has been input, if the conditions for calculating the instrument station coordinate have been satisfied, the display asks whether you want to observe any further stations. (Observation can be carried out up to 5 stations.)

14) Press .

The display asks whether you want to observe the first station

(Known Station A).

Observe Known Stations A to C

Sight Known Station A





15) Sight the centre of the reflecting prism of Known Point A correctly.
 Press .

The horizontal distance measurement is started.

н	820.570m	
ZA	81°59'20"	
HAR	0°00'00"	
Pt.	2	
measure ?		
Yes / No (exit)		

Sight Known Station B



Sight Known Station C



When the measurement has been finished, the measured values are displayed, and the display asks whether you want to observe the second station (Known Station B).

16) Sight the centre of the reflecting prism of Known Station B correctly, and press

2

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The measurement is started. When the measurement has been finished, the measured values are displayed, and the display asks whether you want to observe the third station (Known Station C).

17) Sight the centre of the reflecting prism of Known Point C accurately,

and press



The measurement is started. When the measurement has been finished, the measured values are displayed. "Busy" will appear on the display while the instrument station coordinates are being calculated.





The instrument station coordinates are calculated and displayed.

This value is input as the instrument station coordinate. (Basic mode)

If, for some reason, the instrument station cannot be calculated, the display is as at left. After that the instrument returns to Program mode.

Nullification may be caused by poor layout of the known points, an error in the known station data input, or an inability to measure the distance or angle, etc.

Check the observation conditions and try the procedure again from Step 1).

Note : If "Signal off" is displayed, the return signal strength has become inadequate for measurement. Verify the target sighting. If within 2 minutes the return signal becomes sufficient, the measurement is restarted. After 2 minutes, the measurement is stopped automatically and the display appears as at left.

After that the display asks whether to observe the first station or not.





- The traverse-style coordinate measurement is used to measure the second survey station (No.2) coordinate after moving the instrument to the first survey station (No.1) and setting it up.
- The measured coordinate data is stored in the memory for up to about 1 week after power-off. Even after power-off it is possible to set new instrument station coordinates and the azimuth angle for the instrument by sighting back on the first instrument station and pressing a key on the SET B keyboard.











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Stn pt replace?

Yes / No (exit)





6) Press 🔡 .

Set the instrument station movement in SET B

The display appears as at left and asks whether the new station coordinates are to replace the previously stored ones.

7) Press ENT .

The display appears as at left after the coordinates of Instrument station P1 have been set as the new Backsight station 2, and the measured coordinates of Station No.1 have been set as the new instrument station P2.

The instrument then calculates. The measured coordinates are displayed and the azimuth angle is set.

- To interrupt the movement, press ট্রিয়
- 8) Measure and input the instrument height of instrument station P2 and the target height of Station No.2. (Refer to P.57 12.2)
- 9) Sight the centre of the reflecting prism of Station No.2 correctly.
- Press at to go to coordinate measurement mode and start 3-Dimensional coordinate measurement.



VIEWASSI ELEWIS

- SET B can determine the distance and angle of the target point by setting the reflecting prism at a point (offset point) at a distance from the point to be measured (target point) and measuring the distance and angle of the offset point.
- There are two methods to determine the distance and angle of the target point.
 - ① The target point is determined by inputting the distance between the target point and the offset point.



- When the offset point is positioned to the left or right of the target point, the offset point and target point should both be approximately 90°.
 - When the offset point is in front of or behind the target point, the offset point should be on a line connecting the instrument station point and the target point.

- Đ.
- The target point is determined by sighting the direction of the target point.



The offset point should be positioned to the right or left of the target point, as close to the target point as possible.





- The positions of the target point and the offset point are shown at the left. In this case, determine the slope distance to the target point when the horizontal distance is 1.5m.
 - Note: The offset point should be positioned so that the line connecting the target point and offset line is at a 90° angle to the line connecting the instrument station and offset point.

Sight the offset point and measure



: Starts the distance measurement



3 : Stop the measurement





1.

2.

Offset

angle

distance

3)

2)

 Set the reflecting prism at the offset point, sight the centre of it correctly, and in Theodolite mode or Basic mode,

press either , , , , or , . After about 4.7 seconds (Fine measurement mode), the distance value, the vertical angle and the horizontal angle are displayed and stored in the instrument memory.

For Repeat measurement mode, press



The display appears as at left. The display asks you to select one of the following options:

- Input the horizontal distance between the target point and the offset point.
- 2. Sight the direction of the target point.







e.g.



- The positions of the search point and the offset point are shown at the left. In this case, determine the slope distance to the centre point of a telephone pole.
 - Note: The offset point should be positioned to the right or left of the target point, as close to the target point as possible.

Sight the offset point and measure



: Starts the distance measurement





Stop the measurement

To Offset Measurement mode

3)



- Offset
- 1. distance
- 2. angle

 Set the reflecting prism at the offset point, sight the centre of it correctly, and in Theodolite mode or Basic mode press either 27,

🧯 , or 🎽 .

After about 4.7 seconds (Fine measurement mode), the distance value, the vertical angle and the horizontal angle are displayed and stored in the instrument memory.

2) For Repeat measurement mode, press

Press I and I. The display appears as at left. The display prompts to select one of the following options:

- Input the horizontal distance between the target point and the offset point.
- 2. Sight the direction of the target point.





When the direction of the centre of the telephone pole has been sighted, press 📓 The slope distance from the in-

strument station to the target point and the vertical and horizontal angles are calculated and the results are displayed.



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HAR

: Display the horizontal distance

3.210m

To display the horizontal distance, press 🚰 🖳



- When measuring the height of certain objects such as overhead power cables or bridge supports where the reflecting prism cannot usually be positioned, the Remote Elevation Measurement function can be used to calculate the height above the ground using a point directly above or below the object.
- The height of the target is calculated using the following formulas. Ht = h1 + h2 h2 = Ssin0z1 x cot0z2 - Scos0z1





• The measured values are first displayed after 0.7 seconds and then every 0.5 seconds for all measurement modes.





Measure the height to a suspended cable e.g.

Set up the prism below the object and input the target height









































Measure the distance

S	50.432m		
ZA	89"	45'	20"
HAR	123°	45'	50"



: Stop the measurement

Set up the reflecting prism di-1) rectly below the object to be surveved using an optical nadir or plummet for accurate setting.

- 2) Measure the target height (h1) with a measuring tape, and input the target height. æ P.57
- 3) Sight the centre of the reflecting prism with the SET B correctly.
- In Theodolite mode or Basic 4) mode.

press either 🚰 , 🔮 , or 🚆 .

This accesses the Distance Measurement mode, and the measurement is started. The display appears as at left and flashes.

(The illustration at the left shows an example of slope distance measurement.)

After about 4.7 seconds (Fine measurement mode), the distance value, the vertical angle and the horizontal angle are displayed and stored in the instrument memory.

For Repeat the measurement CE-CA to stop the mode, press measurement.





- The Missing line measurement is used to measure the slope distance, the horizontal distance, and the height difference between the starting position (P1) and any other points without moving the instrument itself.
- The SET B can measure the distances to many points continuously. It is also possible to change the starting position to that of the lastmeasured point. P.98





- 17.1 Measurement mode selection
- Select the measurement mode from the following according to your required measurement.

See P.42 "11.1 Measurement mode selection" for key operation.

Measurement mode		Measurement time	Units
Fine meas.	Single	5.6 secs	
	Repeat	First 5.6 secs & every 3.3 secs	1
Coarse meas.	Single	2.9 secs	Imm
	Repeat	First 2.9 secs & every 0.7 secs	_
Tracking meas.		First 2.8 secs & every 0.7 secs	10mm

17.2 Measuring the distance between two or more points





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Set up the prism on the starting position and start the distance measurement





: Starts the distance measurement







: Stop the measurement

 Set up the reflecting prisms on the required number of target points, sight the centre of the reflecting prism on the starting position. In Theodolite mode or Basic mode press either , .
 or .

> This accesses the Distance Measurement mode, and the distance measurement is started. The display appears as at left and flashes. (The illustration at the left shows an example of slope distance measurement.)

> After 4.7 seconds (Fine measurement mode), the distance value, the vertical angle and the horizontal angle are displayed and stored in the instrument memory.

 For Repeat the measurement mode, press

Sight the prism on the target station and start the missing line measurement



 Sight the centre of the reflecting prism on the target station No.1. If the prism constant and ppm correction for Target Station No.1 are different from those of the starting position, reset these values now.

Start the missing lin measurement Missing line	e 4)	Press 🛃 This accesses the Distance Mea- surement mode and the Missing line measurement is started. The display appears as at left and flashes.
S 20.757m Slo H 27.345m Hor V 1.012m Hei	ope distance rizontal distance ight differ.	After about 5.6 seconds (Fine measurement mode), the slope distance, the Horizontal distance and the height difference are displayed.
জেঝ : Stop the measureme	ent 5)	For Repeat the measurement mode, press Est to stop the measurement.
Start the missing line measurement	e •	After this measurement, to mea- sure the distance between the starting position and Target sta- tion No.2 (or between the starting position and Target station No.3), sight the required reflecting prism and press to start the missing line measurement.

17.3 Change of the starting position

• The last measured target station can be changed to become the next starting position.



 • Changing the last measured target station No.4, to be-come the next starting position

After missing line measurement of the last target station is finished, set the next starting position







 After the missing line measurement of target station No.4 has been finished, the measured values are displayed.

Press and dathis point.

The display appears as at left and asks whether the starting position is to be moved.

2) Press ENT .

The data for Target station No.4 is set as the data for the new starting position, and the display appears as at left. The instrument returns to Basic mode.

To continue missing line measurement from the new starting position to the next target stations, sight each target station and press .

- AB: SETTING:OUT MEASUREMENT
 - The Setting-out measurement is used to set out the required point.
 - In the SET B, the difference between the previously input data to the instrument (the setting-out data) and the measured value can be displayed by measuring the horizontal angle, distance or coordinates of the sighted point.









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18.1 Horizontal angle and distance settingout measurement

- This measurement is used to set out the point from a certain direction (horizontal angle) and a certain distance away from a reference point (the instrument station).
- It is possible to set out a slope distance, horizontal distance, height difference or remote elevation value after inputting the required value.



• Setting-out a horizontal angle right 90°55'40" from the e.g. reference object and setting-out a horizontal distance of 12.345 m. Sight the reference direction from the reference point, and set Horizontal angle to 0° Sight the reference direction from Reference 1) direction the reference point (the instrument station). In Theodolite mode, 2) Station press ENT ENT RÉC The horizontal angle display has been set to 0°. 92" 36' 40" 7A HAR 0° 00' 00" To Setting-out Data Input mode Press 🔜 and 🛃 . 3) ÉNT . 4 The previously input values are S-O data displayed. "D" flashes to prompt 0.000m .D.for the input of the distance set-HAR 0° 00' 00" ting-out data. Input distance setting-out data Input "12.345" and press 4) ENT SHFT The distance setting-out data is S-O data input. "HAR" flashes to prompt 12.345 for the input of the horizontal 0° 00' 00" angle setting-out data.

(Input horizontal angle setting-out data)

90.554

ENT SHFT

D.

HAR

S-O data 12.345

Press function keys to select operation Input "90.554" and press . The horizontal angle setting-out data is input, and the display returns to Basic mode.



5)



6) Set the reflecting prism at a position about 90°55′40" from the reference direction and about 12.345 metres from the reference point (the instrument point), and sight the reflecting prism.



6

Setting out

12.345m

90° 55' 40"

-3° 45' 50"

94° 41' 30"

-40

so ⊥+

D.

HAR

dHA

HAR

: Start H angle S-O measurement

7) Press 📻 and 📑

The setting-out measurement is started, and the horizontal angle "dHA" from the setting-out data is displayed.



64. 54 EK.

5. . .

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9 E

Start H distance S-O measurement





– data : from the instrument + data : towards the instrument

Move the reflecting prism right or 8) left in the correct direction until the "dHA" becomes 0°00'00". Sighting the moving reflecting prism again changes the "dHA" without key operation.

9) When "AHA" has become 0°00'00". press 📻 and then 🖳 .

> The setting-out measurement is started, and then the horizontal distance measurement is started.

> After about 4.7 seconds (Fine measurement mode), the distance from the setting-out data to the reflecting prism is displayed.

10) Move the reflecting prism towards or away from the instrument until the horizontal distance becomes 0.000 m to determine the point.

If minus data is displayed, move the prism away from the instrument, and if plus data is displayed, move the prism towards the instrument.

When the Repeat measurement is selected, sighting the moving reflecting prism again changes the distance without key operation.

At Step 9), the following settingout measurements are possible: Slope distance, by pressing and 🕎

Height difference, by pressing and 🖳

REM, by pressing 📻 and 📑 (after slope distance measurement).

18.2 Coordinates setting-out measurement

- This measurement is used to set out the point of a certain coordinate away from the reference point (the instrument station).
- After input of the coordinates for the point to be set out, the SET B calculates the setting out horizontal angle and horizontal distance and stores the values in the memory. By selecting the horizontal angle and then the horizontal distance setting out functions, the required coordinate location can be set out. The Z-coordinate can also be set out using the setting out coordinate function.
- To recall the setting-out coordinate data from coordinate data stored in the memory, please refer to P.118.



 In this case, the values are as follows: Instrument station coordinates: N = 20, E = 20, Z = 3 Backsight station coordinates : N = 10, E = 10, Z = 3 Setting out a point : N = 40, E = 30, Z = 4

> • The following preparations must be completed before beginning measurement:

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- 12.1 Measurement mode selection
- 12.2 Instrument height and target height input
- 12.3 Inputting instrument station and backsight station coordinates
- 12.4 Setting the azimuth angle
- To set out the Z coordinate, set the reflecting prism on a fixed height object, such as a pole.

From Theodolite mode or Basic mode to Coordinate Setting-out Data Input mode

a e	SHFT	s-o :	For Coord data inpu	linate t mode
·····································	1. 2.	Station Backsigl	ht	
	3.	S-O poir	nt	
	3	: For S- 6 -40 Pt	O data	1
	-)Ń-		0.000	
	Ė		0.000	
	Z		0.000	

 In Theodolite mode or Basic mode,

press and control of the display appears as at left, showing Coordinate data input mode.

2) Press 🔂 for S-O data input mode.

The previously stored values are displayed.

"N" flashes, to prompt for the input of the N coordinate settingout data.

(Input the setting-out data

- Rec
 Imp

 N
 40.000

 E
 0.000

 Z
 0.000
- Image: N
 40.000

 E
 30.000

 Z 0.000



: To Basic mode

The N coordinate is input. "E" flashes to prompt for the input of the E coordinate setting-out data.

Input "30" and press III .

The E coordinate is input. "Z" flashes to prompt for the input of the Z coordinate setting-out data.

5) Input "4" and press IT. .

The Z coordinate is input, and the instrument returns to Coordinate data input mode.

The setting-out horizontal distance and horizontal angle from the instrument station coordinates are calculated and the values are stored in the memory.

- Note: Input the instrument station coordinates before inputting the setting-out data. Calculations may not be carried out correctly if the data is input in the reverse order.
- 6) Press to return to Basic mode.

Set the prism and start H angle S-O measurement.			
Sight the reflecting prism.		Set the reflecting prism in the appropriate position, and sight its centre.	
Setting out D. 22.361m HAR 26' 33' 54"	8)	Press sign and sign . The setting-out measurement is started, and the horizontal angle "dHA" from setting-out data to the sighted direction is displayed.	
	9)	Move the reflecting prism right or left until the "dHA" value be-	

Start H distance S-O measurement

-3° 00' 00"

94° 41' 30"

0.000m

0' 00' 00"



dHA

HAR

H ZA

HAR

10) When "dHA" has become 0°00'00", 8

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press 📻 and then 🛃 .

comes 0°00'00".

The setting-out measurement is started, and then the horizontal distance measurement is started.

After about 4.7 seconds (Fine measurement mode), the distance from the setting-out data to the reflecting prism is displayed.





- 11) Move the reflecting prism towards or away from the instrument on the sighting line to determine the point until the horizontal distance becomes 0.000 m.
- If the Repeat measurement mode has been selected, press to stop the measurement.

Start coordinates S-O measurement, and determine the height `





12) When "H" has become 0.000 m, press 💼 and then 🔂 .

The setting-out measurement is started, and then the coordinate measurement is started.

After about 5.1 seconds (Fine measurement mode), the coordinates from the setting-out data to the reflecting prism are displayed.

Since the horizontal angle and horizontal distance have already been determined, the N and E coordinates are "0".

 Move the reflecting prism up or down until the Z coordinate becomes 0.000, and determine the height.

The tip of the pole is the point to be set out.

 If the Repeat measurement mode has been selected, press to stop the measurement.



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USING THE COORDINATE DATA MEMORY FUNCTION

19. COORDINATE DATA MEMORY FUNCTION 😙 P.113

- 19.1 Coordinate data input/deleting
- 19.2 Coordinate data stored in the memory input to Instrument **(**
- 19.3 Reviewing the coordinate data stored in the memory **(B**)





- ●、g、● To input the coordinate data, Point number : 201
 - N coordinate : 35
 - E coordinate : 67
 - Z coordinate : 48



ø



4) Input coordinate data.

N = 35	CANTE SHFT
E = 67	SHFT
Z = 48	I ANTI SHFT

"No." flashes to prompt for the input of the point number. (The previously input number +1 is dislayed.)

- 5) Input the point number "201" and press
 - Note: Different coordinate data can share the same point number.

The display asks whether the coordinate data is input into the memory.

- Press Friendlaw A constraints of the second second
- To input the next coordinate data, go back to step 4) and input the data.

(Up to 100 points of coordinate data can be input into the memory.)

7) Press and the second second

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• All the coordinate data stored in the memory can be cleared.











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19.2 Coordinate data stored in the memory input to Instrument

- The coordinate data stored in the memory can be used as follows:
 - Instrument station coordinates
 - Backsight station coordinates
 - Known point coordinates for Resection measurement
 - Setting-out coordinates
- Before using the data from the instrument, the following parameter should be set to "Memory".

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To change the paramenter, please refer to P.167 "23. CHANGING INSTRUMENT PARAMETERS".

No.	Parameter	Options	
1	Coordinate data from	Keyboard/Memory	



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È ≜ N	 98.765
E	43.210
ΞZ	1.456 -
L'anna anna an Anna an Anna an Anna an Anna an Anna	 <u></u>

No data Keyboard input Yes / No (exit)



CE-CA : To Basic mode

Note: If more than one stored coordinate data record has the same point number, the display flashes to prompt for the selection of the required coordinate data.

Press , or to display the coordinates to be recalled. And then press [III] to recall the displayed coordinates.

Note: When the coordinate data is not found, the display appears as at left and asks whether you will input the coordinate data from keyboard or input the point number again.

> Press 📖 to input the Instrument station coordinates from kevboard.

Press CE-CA to input the point number again.

• Press ceret to return to Basic mode.





Input Known station coordinates for Resection measurement by using the coordinate data in the memory>

 To input the following coordinate data stored in the memory as the known station coordinates for Resection measurement:

Known station A: Point No.=501, Measure angle & distance, Target height = 1.5m Known station B: Point No.=503, Measure angle Known station C: Point No.=507, Measure angle & distance, Target height = 1.5m

From Theodolite mode or Basic mode to Program mode

2 PROG

- 1. Resection
- 2. Correction
- 3. Pt. replace

- In Theodolite mode or Basic mode,
 - press 🔁 .

The display appears as at left, showing Program mode.

Select Resection measurement

Targe	t / Coord.
-) No. (-	400

2) Press 🛄 .

"No." flashes to prompt for the input of the point number.

Input the data of Known station A

501 ENT.

Measure dist ?	
Yes / No	

 Input the point number "501" and press []].

The display asks whether to measure the distance or not.







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503

No.

Measure dist ? Yes / No

ENT.

ENT : Measure distance

1.500m

ENT: : Retain displayed value

502

Target / Coord.

Target

Ht.



Distance not measured (Measure only angle)

Target / Coord. No. 504

6) Input the point number "503" and press .
 The display asks whether to measure the distance or not.

The previously stored target

"Ht." flashes to prompt for the

When the data for the first station has been input, "No." flashes to

prompt for the input of the point

number of the next known sta-

tion. (The previously stored value

input of the target height. If measuring angle only,

7) Press

Press N.

press

Press Ent

+1 is displayed.)

height is displayed.

4)

5)

When the data for the second station has been input, "No." flashes to prompt for the input of the point number of the next known station. (The previously stored value +1 is displayed.) If measuring distance,



Input the data of Known station C



 Input the point number "507" and press ().

The display asks whether to measure the distance or not.

- 9) Press F
 The previously stored target height is displayed.
 "Ht." flashes to prompt for the input of the target height.
 If measuring angle only,
 press F
- 10) Press ENT .

When the data for the third station has been input, "No." flashes to prompt for the input of the point number of the next known station. (The previously stored value +1 is displayed.)

11) Press

The display asks whether you want to observe the first station (Known station A) or not.

• See P.77 from 15) to continue the resection measurement.



19.3 Reviewing the coordinate data stored in the memory

• The SET B can display the coordinate data stored in the memory.



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🖲 , 🕘 , 🔹 • To review the coordinate data for point number 1008

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OUTPUT THE DATA TO AN EXTERNAL DEVICE

20. DATA OUTPUT AN EXTERNAL DEVICE 3 P.129

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- 20.1 Changing the Instrument options @
- 20.2 Instrument data output (
- 20.3 Instrument station data output 🕲
- 20.4 Measured data output (
- 20.5 Note output @





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Key operations allow the SET B to output measured data via the data output connector to an external device using an interface cable. (For more information, see the Series B 2-way communication manual.)

• The contents of data which can be output are as follows. When measurement data is output, the target number, target code, target height, distance unit, angle unit, vertical indexing, horizontal indexing, and atmospheric correction value can be output, along with the following data.



- → Slope distance, vertical angle, horizontal angle
- → Prism direction and distance from target (only if input through offset measurement) Slope distance, vertical angle, horizontal angle
- → Vertical angle, horizontal angle, X direction tilt angle, Y direction tilt angle
- → N coordinate (E coordinate), E coordinate (N coordinate), Z coordinate
- → N coordinate (E coordinate), E coordinate (N coordinate), Z coordinate Slope distance, vertical angle, horizontal angle
- → Date, instrument station number, code, instrument height, temperature, atmospheric pressure, curvature and refraction correction ON/OFF, prism constant correction, automatic tilt angle correction ON/OFF, instrument station N coordinate (E coordinate), E coordinate (N coordinate), Z coordinate

 Instrument name, instrument number, software version number



20.1 Changing the Instrument options

- Confirm that following parameters are set according to your required measurement and the data output to an external device condition.
- To confirm or change the parameter options, see P.167 "23.
 CHANGING INSTRUMENT PARAMETERS".

No.	Parameter		Options	
2	Recording	1. Set code	*1. Input	2. Non-input & skip
~		2. Set target height	*1. Input	2. Non-input & skip
3	Tilt correction		*1. Applied	2. Not applied
5	V angle format		*1. Zenith	
-			2. Horizontal 0°360° (0400gon)	
			3. Horizontal ±90° (±100gon)	
6	Anale	SET2B / 3B	*1.1" (0.2mgon)	2. 5" (1mgon)
	resolution	SET4B	*1.5" (1mgon)	2. 10" (2mgon)
7	BS-232C	1. Baud rate	*1.1200 baud	2. 2400 baud
	format	2. Checksum	*1. No	2, Yes
		3. Parity bit	*1. No	2. Yes (even)
8	Vindexing		*1. Auto	2. Manual
9	Hindexing		*1. Auto	2. Manual
10	0 C+R correction		*1. No	
			2. Yes K=0.142	3. Yes K=0.20
11	Units	1. Distance	*1. metres	2. feet
		2. Angle	*1. Degrees	2. Gon
	1	3. Temperature	*1. °C & hPa	2. °C & mmHg
		& pressure	3. Next	1. °F & hPa
				2. °F & mmHg
	1			3. °F & inchHg

* Factory settings

20.2 Instrument data output

- With the SET B, the following items can be output to an external device as instrument data:
 - Instrument name
 - Instrument number
 - Software version number



20.3 Instrument station data output

 The SET B can output the following items as instrument station data;

Date, instrument station number, instrument station code, instrument height, temperature, atmospheric pressure, instrument station coordinates, curvature and refraction correction, prism constant, and automatic tilt angle correction.



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- €.g. Date: Ou Instrum Code: "
 - To output the following instrument station data: Date: October 4, 1992 Instrument station number: No.100 Code: "HOME" Instrument height: 1.45m Temperature: 25°C Atmospheric pressure: 980 hPa Instrument station coordinates: N = 30, E = 30, Z = 10

In Record mode, display "Station data"

- S=0 or H
- Select Station data Yes / No (exit)

- 1) In Record mode,
 - press **Fo**, or **F**o. to display "Station data".

Select the "Station data"

Press I .
 The previously input date is displayed.

Date yy. mm. dd 92. 8. 10

Yes ENT SHIFT

- Input the date

 92.10.4
 - Stn point
- Input "92.10.4" and press []]

The date "92.10.4" is input, and "No." flashes to prompt for the input of the station number.

	1) Input "100" and
100 ABCDEFGHIJ press 0123456789 Cd ← ABC	 4) Input 100° and press
Input the code	
	5) Input the code.
CE-CA : Single-character dele	ete Press read to delete one charac- ter to the left.
7 : Input "H"	Press ⋥ to input "H".
sion: Display K to T	Press 🚮 to display "K ~ T".
: Input "O"	Press 📷 to input "0".
PROG : Input "M"	Press 🗾 to input "M".
RCL : Display A to J	Press 👘 to display "A ~ J".
:Input "E"	Press 💼 to input "E".
ENT : Input finished	Press SHFT .
Instr H.:- 0.000m	The code "HOME" is input, and "Ht" flashes to prompt for the input of the instrument height.
Input the instrument	height
1.45 MINU	6) Input "1.45" and press []]

- 1. 0 set
- 2. Temp & Press
- 3. ppm value

Input "1.45" and press . An instrument height value of "1.45" is input, and the display turns to the ppm setting mode. 12 **1**

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20.4 Measured data output

• The SET B can output the following items as measured data: Target number, target code, target height, distance unit, angle unit, vertical indexing, horizontal indexing, atmospheric correction measured data.

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• The distance is measured in accordance with the selected distance measurement mode, but the measurement is done only once (single measurement).


20. DATA OUTPUT TO AN EXTERNAL DEVICE



e.g.

 To output the following offset measurement data Target number : No. 2001 Code : "TREE1". Target height : 1.23 m Horizontal distance from target point to offset point : 1.8 m Direction of prism from target : Front



Select "S, V, H (offset)"



Ht.:

Target

		- Yi
2)	Press	Ę

The previously stored values are displayed. "Ht" flashes to prompt for the input of the target height.

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Note: If the target height setting parameter is set to "Non-input", this procedure is omitted. Instead, go directly to step 4).

Sight r	eflection prisr	n for offset	point and input target height
S ZA HAR 1. dista 2. angle	dist'-	3)	 Sight the reflection prism for the offset point. Input "1.23" and press . A target height value of 1.23 m is input, and the Distance mode is accessed. Distance measurement is started. The display appears as at left and flashes. After about 4.7 seconds (Fine measurement mode), the distance value, the vertical angle and horizontal angle are displayed. The display prompts you to select one of the following options: Input of the horizontal distance from the target point to the offset point. Sight the direction of the target point.
Select	"distance"		
Direct prism : Yes / N	ction → lo(exit)	4)	Press . The display appears as at left and prompts for the selection of the direction from the target point to the reflecting prism.
Select	offset point di	rection	
triangle for the second secon	tion ↓ Jo(exit)	5)	Press $fight or fight$ to display " \downarrow ". Note: \rightarrow Prism is right of target \leftarrow Prism is left of target \uparrow Prism is behind target \downarrow Prism is in front of target

Offset distance $_{,}_{,}_{,}$ 0.000m	ce fro	When "↓" appears, press "D" flashes to prompt for the in- put of the horizontal distance be- tween the target point and offset point. bm the target point to the offset
1.8 ENT Target point	6)	Input horizontal distance of "1.8" and press III .
Input the target point num	ber	i
2001 ABCDEFGHIJ press 0123456789 Cd ←	7) No	 Input a target number of "2001" and press . A target number value of "2001" is input. "Cd" flashes to prompt for the input of the target point code. te: If the parameter of the code setting is set to "Non-input", this procedure is omitted.
(Input the target point code		· · · · · · · · · ·
0123456789 ABCDEFGHIJ KLMNOPQRST UVWXYZ& 0123456789	8)	If the displayed code is the re- quired one, press and go to step 9). Press to delete one charac- ter to the left.



Press Find display "K to T". Press 🖳 to input "T". Press 🔛 to input "R". Press 🚰 to display "A to J". Press 🛃 🙀 to input "EE". Press 🚮 to display "0 to 9". Press 🔜 to input "1". And press [] .

When the code has been input, the output is started.

 When the target number is displayed, the output is finished.

The display then returns to Record mode.

Note: If the display returns to Record mode following a display like that at the left, there is an error in the output. Please check to see if there are any abnormalities in cables or external device, or if there is a problem with the program. If the display returns to Record

not the display returns to Record mode following a display like that at the left, there is an error in the measurement. Try levelling the instrument again, or sight the reflecting prism once again and start over from step 1).

20.5 Note output

The SET B can output notes.



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TROUBLESHOOTING

21. ERROR MESSAGES

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22. CHECKS AND ADJUSTMENTS

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- 22.1 Plate level 🕲
- 22.2 Circular level 🕲
- 22.3 Reticle 🕲
- 22.4 Coincidence of distance measuring axis with reticle 🕲

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- 22.5 Optical plummet 🕲
- 22.6 Distance measurement check flow chart (
- 22.7 Additive distance constant 🕲





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- If the following error messages are shown during measurement, see the table below.
- If the same error message is repeated or if other messages are shown, please contact your Sokkia agent.

Display	Meaning	Action
Bad cond.	Prism sight is bad.	Sight the target again. Measure again after confirming the re- turned signal using the signal checking mode.
Battery is low	Battery voltage is too low.	Charge the battery or replace it with a charged one.
Confirm 0 set	Reset is not performed.	Index the V and H circles again.
Data error	An error has occurred during outputting.	, Level the SET Bagain or sight the reflecting prism.
	Error when measuring the initial slope dis- tance during either REM or horizontal dis- tance between two points measurement.	Sight the reflecting prism to perform slope distance measurement again.
Memory cleared	After 1 week, data stored in the short term memory has been cleared.	
Memory is full	There is no area to input coordinate data in the memory.	
No data	There is no data for the specified point num- ber.	

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Display	Meaning	Action	
Out of range	During REM, the verti- cal angle is more than $\pm 89^{\circ}$ or the measured distance is more than 9999.999m.	Press 🖾 to stop measuring.	
Out of range X > ⊥ <y< td=""><td>Tilt sensor range error. Tilt angle exceeds ±3'.</td><td>Level the SET B again.</td></y<>	Tilt sensor range error. Tilt angle exceeds ±3'.	Level the SET B again.	
Record error	External device does not reply with ACK/ NAK. (when "recording" pa- rameter is set to "out".)	Check to see if there are any abnormalities in cables or external equipment, or if there is a problem with the pro- gram.	
Signal off	At start of measure- ment, the returned sig- nal was totally absent or disturbed.	Sight the target again. Measure again after confirming the re- turned signal using the signal checking mode.	
Tilt error	While setting the azi- muth angle, tilt angle exceeds ±3'.	Level the SET B again.	
Tilt Out of range	During distance mea- surement, tilt angle ex- ceeds ±3'.	Level the SET B again.	
Time out	No measured distance data is received within 2 minutes of starting the measurements, or the measured distance data cannot be ob- tained for a total of one minute.	Sight the target again. Measure again after confirming the re- turned signal using the signal checking mode.	
E 100	Error when measuring a horizontal angle*.	Index the horizontal circle again.	
E 101	Error when measuring a vertical angle*.	Index the vertical circle again.	

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* If the SET B telescope or upper part is rotated faster than four revolutions per second, the error indication "E 100" or "E 101 is displayed.

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 Periodically, checks and adjustments should be performed before and after measurement. In addition, the instrument should be checked after long storage, transportation or when damage to the instrument is suspected to have occurred due to a strong shock.

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• The checks should be performed in the following order.

22.1 Plate level

 The glass tube of the plate level is sensitive to temperature changes or shock.







- Turn the upper part of the instrument until the plate level is parallel to a line between levelling foot screws A and B.
 Centre the plate level bubble using levelling screws A and B.
- Note: The bubble moves towards a clockwise rotated foot screw.
- Loosen the horizontal clamp and turn the upper part 90°. The plate level is perpendicular to a line between levelling screws A and B.

Centre the plate level bubble using levelling screw C.





4) Use levelling screws







- 3) Turn the upper part through 180° and check the bubble position.
 If the bubble is still centred, no adjustment is necessary.
 If the bubble is off-centre, adjust as follows:
- Correct half of the bubble displacement using levelling screw C.
- **Note :** The bubble moves away from a clockwise rotation of the adjusting screw.
- Repeat the procedures from 1) to 5) until the bubble remains centred for any position of the upper part.
 - If the bubble can not be centred, please contact your Sokkia agent.





- 1) Perform the plate level adjustment or level the instrument carefully using the plate level.
- Check the position of the circular level bubble.

If the bubble is off-centre, adjust as follows:

- Verify the off-centre direction of the bubble.
- Loosen the adjusting screw farthest from that direction to centre the bubble.
- 5) Adjust all 3 adjusting screws until the tightening tension of each screw is the same, and the bubble is centred.
- Note: Over-tightening the adjusting screws may damage the circular level. Unequal tightening of the screws may mean that the bubble will go out of adjustment.

If the bubble can not be centred, please contact your Sokkia agent.

22.3 Reticle

• This adjustment is very delicate. If you have any difficulties, please contact your Sokkia agent.

Perpendicularity of the reticle to the horizontal axis





Adjustment







- Level the SET B carefully. Select and sight a clear target on the upper part A of the reticle line.
- Turn the telescope vertical fine motion screw @ until the target is on the lower part of the reticle B. If the target is still positioned centrally within the reticle lines, no adjustment is necessary.

If the target is off-centre, adjust as follows:

- 3) Remove the telescope reticle cover @ .
- Slightly loosen one vertical and one horizontal adjusting screw by a certain amount using the adjusting pin.
- Place a small piece of plastic or wood against one side of the top adjusting screw mount as a buffer.
- 6) Look through the eyepiece and gently tap the piece of plastic or wood to rotate the reticle slightly.
- Retighten the two adjusting screws loosened in step 4) by the same amount.
- Note: Over-tightening the adjusting screws may damage the reticle. Unequal tightening of the adjusting screws may mean that the reticle will go out of adjustment.

- Check the reticle perpendicularity again using procedures 1) and 2) above and repeat the adjustment if necessary. Replace the reticle cover.
- Note: After this adjustment, perform the check and adjustment of the reticle position as follows:

Vertical and horizontal reticle line positions

(Check)





ZA	269°	30'	00"
HAR	198"	34'	10"

- Set up a clear target 50 100m from the SET B. Level the instrument carefully, switch on, and index the vertical and horizontal circles.
- 2) Sight the target on face left. Read the vertical and horizontal angles.

e.g. HAR 18°34′00".....a1 ZA 90°30′10".....b1

- Now sight the target on face right. Read the vertical and horizontal angles.
 - e.g. HAR 198°34′10"....a2 ZA 269°30′00"....b2
- 4) Calculate a2 a1 = $180^{\circ}00'10"$. The difference should be within $180^{\circ} \pm 20"$
- 5) Calculate b1+ b2 = $360^{\circ}00'10"$. The sum should be within $360^{\circ} \pm 20"$

If a difference of more than \pm 20" still remains after repeating these procedures several times, adjust as follows:

Note: Moving the reticle line effects the distance measurement. Do not move the reticle more than 20".



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Adjustment

e.g. a1 = 18° 34′ 00" b1 = 90° 30′ 10" a2 = 198° 34′ 20" b2 = 269° 30′ 10"

ZA	296°	30'	00"
HAR	198°	34'	10"







 Calculate Horizontal angle A and Vertical angle B,

A = (a2+a1)/2+90°=198°34'10"

B = (b2-b1)/2+180° = 269°30'00"

- 7) While still sighting the target on face right, use the horizontal and vertical fine motion screws to adjust the displayed horizontal and vertical angles to the above values.
- 8) Look through the telescope. The reticle is now slightly shifted from the target.
- 10) To move the vertical reticle line towards the target centre, use the adjusting pin to adjust the left and right adjusting screws as follows: Slightly loosen the top and bottom adjusting screws by the same amount.

To move the reticle to the **right** (left), first very slightly loosen the **left** (right) adjusting screw, then tighten the **right** (left) adjusting screw by this same amount. [() for opposite direction] Finally tighten the top and bottom adjusting screws as before.

Check the reticle position and repeat the procedure until the reticle comes close to the target centre.

 To move the horizontal reticle line towards the target centre, adjust the top and bottom adjusting screws as follows:

Slightly loosen the right and left adjusting screws by the same amount.

To move the reticle **down** (up), first slightly loosen the **top** (bottom) adjusting screw, then tighten the **bottom** (top) adjusting screw by this same amount.

Finally tighten the right and left adjusting screws as before.

Check the reticle position and repeat the procedure until the reticle comes close to the target centre.

- 12) Replace the reticle cover.
- Note: Over-tightening the adjusting screws may damage the reticle. Unequal tightening of the adjusting screws may mean that the reticle will go out of adjustment.

After this adjustment, please adjust the collimation error referring to P.186 "Appendix 2:<Adjusting the collimation error by collimation program>".



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22.4 Coincidence of distance measuring axis with reticle

 After the reticle check, verify that the distance measuring axis is matched with the reticle.

Note: Do not adjust the reticle in this step.





6) Press at this position ("*" not displayed) to return to Basic mode, then press to go to Theodolite mode and read the vertical angle.

a = 89°47′00"

7) Press again to return to Basic mode, then press is a constraint of the return signal checking mode.

 Lower the telescope slowly with the vertical fine motion screw until the "*" symbol disappears.



9) Press at this position ("*" not displayed) to return to Basic mode, then press to go to Theodolite mode and read the vertical angle.

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b = 89°54'20"

10) There is no problem if the difference of a and b against c is more than 2'30" (SET4B: 3'). The right and left directions require the same check. If any of the differences are less than 2'30" (SET4B: 3'), please contact your Sokkia agent.

22.5 Optical plummet



- Level the SET B and exactly centre a surveying point in the reticle of the optical plummet.
- 2) Turn the upper part 180°.
 If the surveying point is still centred, no adjustment is necessary.
 If the surveying point is off-centre, adjust as follows:
- 3) Correct half the deviation with the levelling foot screws (2).
- 4) Unscrew the optical plummet focussing ring (1).
- 5) Adjust the remaining half of the displacement with the 4 adjusting screws to centre the reticle exactly on the surveying point. When surveying point is seen as a green (gray) area:
 - Loosen the upper (lower) screw slightly.
 - ② Tighten the lower (upper) screw by the same amount.



Next, if the surveying point is seen to be on the green line (gray line):

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- Loosen the right (left) screw slightly.
- Tighten the left (right) screw by the same amount.
- Note: Over-tightening the adjusting screws may mean that the reticle will go out of adjustment.
- 6) Check the adjustment by rotating the upper part of the instrument. The survey point should remain centred in the reticle. If necessary, repeat the adjustment.
- Reattach the optical plummet focussing ring.



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22.6 Distance measurement check flow chart

 If error codes EXXX are displayed, please contact your Sokkia agent.







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22.7 Additive distance constant

• The additive distance constant K of the SET B is adjusted to 0 before delivery. However, it may change over time and so should be determined periodically and then used to correct distances measured.

Check

- 1) Select points A and B on flat ground about 100 m (328ft) apart, and C in the middle.
- **Note:** Ensure that the target height is the same as the instrument height of the SET B objective lens centre. If the ground is not flat, use an automatic level to set the correct instrument heights of all points.



- 2) Set up the SET B at A, the target at B and measure (fine measurement) the distance A-B 10 times.
- 3) Shift the SET B to C, and measure (fine measurement) the distance C-A and C- B 10 times each.



- 4) Calculate the averages of $\overline{A-B}$, $\overline{C-A}$ and $\overline{C-B}$.
- 5) Compute the additive distance K using the formula:

 $K = \overline{A} - \overline{B} - (\overline{C} - \overline{A} + \overline{C} - \overline{B})$

Obtain the K value several times. If all K values are greater than ±3mm (SET4B:±5mm), please contact your Sokkia agent.

Note: Errors in setting up the instrument and sighting the target will affect the determination of the additive distance constant, therefore perform these procedures as carefully as possible.



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MEASUREMENT OPTIONS SELECTION

23. CHANGING INSTRUMENT PARAMETERS 3 P.167

24. POWER SUPPLIES

🕋 P.177

3

25. REFLECTING PRISMS AND ACCESSORIES 3 P.179





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• The instrument parameter settings can be changed by key operations to match the required measurement.

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 The selected options are stored in the memory until they are changed.

The factory set options are reset when the "Configuration default set" is initialized.

No.	Parameter			Op	tions	
1	Coordinate data from		*1.	Keyboard		
				2.	Memory	
2	Recording	1. Set coc	le	*1.	Input	
				2.	Non-input	
		2. Set targ	get height	*1.	Input	
				2.	Non-input	
3	Tilt correctio	n		*1.	Tilt correction applied	
				2.	Correction not applied	
4	Coordinate f	ormat		*1.	N, E, Z	
				2.	E, N, Z	
5	V angle form	at		*1.	Zenith	
			2.	Horizontal 0° -360° (0 - 400gon)		
				3.	Horizontal ±90° (±100gon)	
6	Angle resolu	ution SET2B, SET3B		*1.	1" (0.2mgon)	
				2.	5" (1mgon)	
			SETAR	*1.	5" (1mgon)	
			00140	2.	10" (2mgon)	
7	RS-232C	1. Baud ra	ite	*1.	1200 baud	
	format			2.	2400 baud	
		2. Checks	um	*1.	No	
				2.	Yes	
		3. Parity bit		*1.	No	
				2.	Yes (even)	
8	V indexing			*1.	Auto	
				2.	Manual	
9	H indexing			*1.	Auto	
		<u> </u>		2.	Manual	

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No.	Parameter		Opt	ion		
10	C + R correction		*1.	No		
			2.	Yes K₌	=0.142	
			3.	Yes K=	=0.20	
11	Units 1. Distance		*1.	metre		
			2.	Feet		
		2. Angle	*1.	Degre	e	
			2.	Gon		
		3. Temperature	*1.	°C & h	Ра	
		&	2.	°C&n	mHg	
		pressure	3.	Next	1. °F&hPa	
			•		2. °F & mmHg	
					3. °F&inchHg	
12	Auto power	off	*1.	30 minutes timeout		
			2.	Power On/Off with switch		
13	Backlight co	ntrol	*1.	On/Off by key operation		
			2.	30 seconds timeout		
14	Audio for ret	turn signal	*1.	Audio tone		
			2.	No audio tone		
15	15 Reticle illumination		*1.	Strong reticle illumination		
			2.	Weak reticle illumination		
16	16 Configuration default set		Ini	Initialize : Yes / No		

*Parameter options set at the time the instrument left the factory.



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See next page

23. CHANGING INSTRUMENT PARAMETERS




23. CHANGING INSTRUMENT PARAMETERS



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No.1 "Coordinate data from" parameter

POWER SUPPLIES





te: When using any external power supply, it is recommended that the BDC25/25A battery be left in place to balance the weight on the axes.

Use the SET B only with the combinations shown here.

1) Battery BDC25/BDC25A

- Battery operating life is shortened at extreme temperatures because of its property of Ni-Cd battery.
- The battery can be recharged about 300 times under the ordinary use (Temperature = 20°C, Humidity = 65%).

Note: • The storage temperature is between 0°C and 40°C.

- Do not use the battery for any other equipment or purpose.
- Remove the battery from SET B to avoid damaging the battery when not in use.

Specifications:

Output voltage: DC6V Size: 58 x 23 x 92mm

Capacity: 1200mAh Weight: 0.2kg 6

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2) Battery charger CDC27/CDC31/CDC31A/CDC47

- The battery charger normally becomes warm while charging.
- How to charge: Connect the charger to the power supply, connect the adaptor to the battery charger and mount the battery in the adaptor. Then;
 - the charging light flashes during charging and it becomes lighting on when the charging is finished. (CDC27/CDC31/CDC47)
 - the charging lamp lights on during charging and it flashes when the charging is finished. (CDC31A)

Note: • The charging temperature is between 10°C and 40°C.

Specifications:

Input: CDC27: AC90V ~ AC125V, 50/60Hz, 20VA CDC31/CDC31A/CDC47: AC180V ~ AC264V, 50/60Hz, 20VA Output: DC7.5V, 1.2A Charging time at 25°C: about 80minutes (BDC25/25A) Size: 66 x 124 x 45mm Weight: CDC27: 0.35kg CDC31/CDC31A/CDC47: 0.38kg

3) Precautions for the use of external power supplies

- Ensure that the car cigarette lighter has DC12V output and that the negative terminal is grounded. Leave the engine running during the car cigarette lighter using.
- Before using EDC2/2A, set the voltage selector to the correct voltage.
- EDC14 has a breaker switch. When you short circuit the battery or the polarity is not correct, the breaker will switch off the power. When the breaker switches off the power, remove the rubber cover and set the breaker switch to see the rad mark in place.
- breaker switch to see the red mark in place.

 All Sokkia reflecting prisms and accessories have standardized screws (5/8" x 11 thread) for ease of use.

REFLECTING PRISMS AND



- *1: To change the stored prism constant value, see page 45.
- *2: Fluorescent target paint finishing allows clearer sighting in adverse observing conditions.

1) Precautions for use of reflecting prisms

- Carefully face the reflecting prism towards the instrument; sight the prism target centre accurately.
- To use the triple prism assembly AP31 or AP32 as a single prism (e.g. for short distances), mount the single prism AP01 in the centre hole of the prism holder.

2) Precautions for use of the instrument height adapter AP41

- Check the Plate level of the AP41 as described in Section 22.1. Check that the optical plummet of the AP41 sights the same point as that of the SET B.
- Check that **236** (the height of the SET B in mm) is displayed in the window of the instrument height adapter AP41. The height of the AP41 can be adjusted as follows:



- Loosen the 2 fixing screws.
- ② Turn the centre part counterclockwise to unlock it.

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- ③ Move it up or down until "236" appears in the window.
- ④ Turn the centre part clockwise to lock it.
- ⑤ Tighten the fixing screws.

3) Precautions for use of tribrach

• Use the plate level on the AP41 to adjust the tribrach circular level as described in Section 22.2.

APPENDICES

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Appendix 1:	MANUALLY INDEXING THE VERTICAL CIRCLE BY FACE LEFT, FACE RIGHT MEASUREMENTS	4	P.183
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ATMOSPHE	RIC CORRECTION CHART	Ŧ	P.202



VOIDERREIDA 29 REORTAINICLE MEASUREMENTROFTHE **CHECTEVADDEPAC**

<Adjusting the tilt zero point error>

- The tilt zero point error can be adjusted by the following procedures. (The "Tilt correction" parameter should be set to "Yes".)
- The range of the tilt sensor is ±3'.
- Tilt offset data storage period: Until the next adjustment is made (Power-off possible)
 - Level the SET B with the plate 1) level 🔊 . Tighten the vertical clamp @ with the telescope approximately horizontal.
 - Use the horizontal clamp @ to 2) turn the upper part of the SET B until the telescope is parallel to a line between levelling screws A and B.
 - In Theodolite mode, 3) press ENT , 0 The horizontal angle is set to 0°.
 - 4) Press 2 for Program mode.





: Set H angle to zero

ZA	89° 12' 30"
HAR	0°00'00"



2 : For Program mode

- 1. Resection
- Correction 2.
- 3. Pt. replace



- 5) Press **From** for Correction mode.
- Press for Tilt offset mode.
 Minimum display unit SET2B : 1" SET3B : 1" SET4B : 5"
- Wait for a few seconds until the tilt angle reading is steady.

Then press ENT , REC

(X and Y tilt angles will be memorized.)

 Turn the upper part of the SET B through 180°.³

9) Wait for a few seconds until the tilt angle reading is steady, OSET

then press 🖼 , 💼 . The tilt zero point error has been adjusted and the display has returned to Program mode.

- Press for to go to Basic mode.
- If there is no response when the key is pressed, the range in which adjustment is possible has been exceeded. Please contact your Sokkia agent and request adjustment.

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• The displayed angles are corrected automatically by the stored collimation errors.

These collimation error values can be adjusted and stored by following the relevant procedures.

The observation can be carried out up to 5 times, so if an accurate sighting can be made, increasing the number of times the observation is carried out will result in a more precise determination of the collimation error values.

- **Note:** In Tracking measurement mode, the displayed horizontal angle is not corrected by the stored collimation error values.
- If angle measurements are to be made in only one position (e.g. Resection measurement), it is advisable to adjust the correction values accurately.
- Collimation error values storage period: Until next adjustment (Power-off possible)
- Note: Sight the target carefully to determine the collimation error accurately.

Ensure that the target height is the same as the instrument height. If the ground is not flat, use an automatic level to set the correct instrument height of all points.



- Select
- 1. Collimation
- 2. Tilt offset

- Set up a clear target at a horizontal distance of a bit longer than 100m from SET B.
- In Theodolite mode or Basic mode,

press 2 for Program mode.

3) Press Frog for Correction mode.



4) Press Menu

for Collimation mode.

A display prompts for the vertical angle and horizontal angle for the telescope face 1 to be stored in the memory.

A display prompts for the vertical angle and horizontal angle for the telescope face 2 to be stored in the memory.

 In face right (face 2), sight the same target correctly, and press
 Yes
 Image: A start of the sta

The display asks whether the observation is ended or not. (Observation can be carried out up to 5 times.)

 To end the observation process, press

The collimation error value is calculated and displayed.

Following that, the display asks whether a new collimation error value is to be set.





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- Press 🖾 to go to Basic mode.
- If the range in which adjustment is possible has been exceeded, an asterisk (*) is displayed, and a confirmation message is displayed, the display asks whether you begin observation once again, from the beginning.

To continue the observation,

Repeat the procedures from step

To set a new collimation error

The collimation error has been adjusted and the display has re-

turned to Program mode.

press Geo

value, press

5).

8)

To redo the observation, press To redo the procedure reverts to Step 5).

To end the observation process, press 쨜을 . The display returns to Program mode.

If an asterisk is still displayed after repeated attempts at observation, the allowable adjustment range has been exceeded. Please contact your Sokkia agent and request adjustment.





Appendix 3: FOR DISTANCE MEASUREMENT OF THE HIGHEST ACCURACY

1) Atmospheric correction

- The SET B uses a beam of infrared light to measure the distance. The velocity of this light in the atmosphere varies according to the temperature and pressure.
 - The distance will be changed by 1 ppm by:
 - a variation in temperature of 1°C
 - a variation in pressure of 3.6 hPa
 - (A 1 ppm change means a 1mm difference for every 1km of measured distance).
 - To obtain distance measurement, of the highest accuracy, the temperature and pressure must be carefully measured by accurate equipment.
- The ppm correction should be applied when the calculated ppm value is over ±5ppm or if the slope distance is more than 200m.
- 2) Average temperature and pressure between 2 points in different atmospheric conditions:
 - In flat terrain: measure the temperature and pressure at the midpoint of the line as there is little variation in the values.
- In mountainous terrain: midpoint values should be used. If those values cannot be measured, take the temperature and pressure at the instrument and target stations, then calculate the average values.





1+ 0.003661 x t (°C)

e: Partial water vapour

pressure t: Temperature 4

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60%

40%

20%

50°C

 If you take the influence of relative humidity into account, please set the Correction factor (ppm) by the following method.

40°C

- (f) Input the temperature and pressure values. The correction factor A is calculated and displayed on the sub display.
- (2) Measure the relative humidity and read the correction factor B from above table.

For pressure between 500hPa and 1400hPa, if instead of the formula, the graph above is used to look up the correction factor, a difference of less than 0.1ppm will be present.

③ Calculate A plus B. (C)

20°C

(1013hPa)

30°C

(ppm) 5

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-10°C

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10°C

- ④ Input C in ppm mode. (Refer to P.48"13.3 Atmospheric correction")
- (5) Measure the distance. The displayed distance is corrected by the correction factor C.
- Temperature: 30°C, Pressure: 1020hPa e.g. Relative humidity: 80% Measured distance corrected by only the correction factor A: 3000m

A=12 (sub display), B=1.4 (above table)

$$D = \frac{1+(12 \text{ ppm} + 1.4 \text{ ppm}) \times 10^{-6}}{1+12 \text{ ppm} \times 10^{-6}} \times 3,000 \text{ m}$$

= 3,000.0042 m



When measuring the Horizontal distance and Height difference. the earth-curvature and refraction correction can be selected by the parameter "C & R correction". The Atmospheric refraction constant K can be set to either 0.142 or 0.20.

<No correction>

Horizontal distance: H = S x sin Z Height difference: $V = S \times \cos Z$

<Applied correction>

Horizontal distance: H' = S x sin Z - $\frac{1 - \frac{K}{2}}{2}$ x S² x sin Z x cos Z

Height difference: $V' = S \times \cos Z + \frac{1 - K}{2R} \stackrel{!}{\times} S^2 \times \sin^2 Z$



- S: Slope distance (atmospheric corrected value)
- Z: Vertical angle (0° at zenith)
- K: Atmospheric refraction constant
- R: Radius of the earth (6.372 x 10⁶ m)
- e.g. Correction value at Z=70° (K=0.142)

S (m)	500	1000	1500
H'–H (m)	- 0.012	- 0.047	- 0.105
V'–V (m)	0.015	0.059	0.134



Note: The horizontal distance is the distance measured at the height of the surveying point above sea level. If required, reduce this distance to the average sea level and apply the local projection correction.





1) Plumb bob

If the weather is calm, or for initial tripod centring, the plumb bob can be used for centring. To use, unwind the plumb bob and attach it to the hook inside the centring screw. Use the cord grip piece to adjust the cord length.

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2) Tubular compass CP7

To mount the CP7,slide it into the tubular compass slot **①**. To use,loosen the clamping screw to free the compass needle. Turn the instrument in the face left position until the compass needle bisects the index lines. The telescope will be nearly aligned with magnetic north. After use,tighten the clamp and remove the compass from the slot. Replace it in the specified position in the carrying case.

Note: Magnetism and metal will influence the tubular compass,making it incapable of projecting true magnetic north. Do not use the magnetic north indicated by this compass for base line surveying.



1) Diagonal eyepiece DE18

The diagonal eyepiece is convenient for near-vertical observations and in places where space around the instrument is limited. Remove the handle and the telescope eyepiece by unscrewing the mounting ring, and screw in the diagonal eyepiece.

2) Solar filter OF2/OF2A, OF1/OF1A

For observations made facing the sun, and where glare is present. The OF2/OF1 and OF2A/OF1A (flip-up) filters are mounted on the objective lens.

OF2, OF2A:for SET2B, SET3B OF1, OF1A:for SET4B









Host computer

3) Electronic field book SDR series

The SDR series collects and stores slope distance, zenith and horizontal angle data from the SET B.

Calculations can be performed on the data so that the measurements can be verified in the field. The stored data can be transmitted to a data processing system.





4) Interface cables DOC1, DOC25/DOC26/DOC27

The interface cable DOC1 can be used for direct two-way communication between the SET B and a host computer.

This cable is not provided with a connector on the computer end of the cable.

Also available are:

DOC25: NEC connector DOC26: IBM connector DOC27: Toshiba J3100

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• Please verify that all equipment is included.

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① SET B main unit	. 1
② Internal battery,	
BDC25/25A	. 2
③ Battery charger,	
CDC27/31/31A/47	. 1
④ Battery charging adaptor,	
EDC19	. 1
(5) Tubular compass, CP7	. 1
6 Lens cap	. 1
⑦ Lens hood	. 1
(8) Vinyl cover	. 1
9 Plumb bob	. 1







- Wipe off moisture completely if the instrument gets wet during survey work.
- 2) Always clean the instrument before returning it to the case.



- The lens requires special care. Dust it off with the lens brush first, to remove minute particles. Then, after providing a little condensation by breathing on the lens, wipe it with a soft clean cloth or lens tissue.
- 3) Do not wipe the displays (), () and keyboard () or carrying case with an organic solvent.
 - 4) Store the SET B in a dry room where the temperature remains fairly constant.
 - 5) If the battery is discharged excessively, its life may be shortened. Store it in a charged state.
 - 6) Check the tripod for loose fit and loose screws.

 - 8) When the instrument is not used for a long time, check it at least once every 3 months.
 - 9) When removing the SET B from the carrying case, never pull it out by force. The empty carrying case should then be closed to protect it from moisture.
 - 10) Check the SET B for proper adjustment periodically to maintain the instrument accuracy.

Telescope

Length: SET2B:177mm SET3B:177mm SET4B:170mm Aperture: 45mm Magnification: 30X 3" Resolving power: Erect Image: Field of view: 1°30' (26m/1000m) Minimum focus: 1.3m (4.3 ft) Reticle illumination: Bright or dim settings (Selectable with parameter) E

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Angle measurement

Horizontal and Vertical	Incremental with 0 index	
circles type :		E
Display range:	SET2B:-1999° 59' 59" to 1999° 59' 59"	5
	(–1999.9998gon to 1999.9998gon)	
	SET3B:-1999° 59' 59" to 1999° 59' 59"	50 15
	(–1999.9998gon to 1999.9998gon)	Sec.
	SET4B:-1999° 59' 55" to 1999° 59' 55"	E
	(–1999.999gon to 1999.999gon)	Ç
Minimum display:	SET2B:1" (0.2mgon)/5" (1mgon)	_
	SET3B:1" (0.2mgon)/5" (1mgon)	E
	SET4B:5" (1mgon)/10" (2mgon)	-
	(Selectable with parameter)	E
Angle units:	Degree/Gon	
	(Selectable with parameter)	-
Accuracy:	Standard deviation of mean of measurement taken in positions I and II (DIN18723)	ŝ
	SET2B:2" (0.6mgon)	C
	SET3B:3" (1mgon)	е 1
	SET4B:5"(1.5mgon)	-
Measuring time:	Less than 0.5sec	5

Automatic compensator: Type: Minimum display:

Range of compensation: Measuring mode: Horizontal angle:

Vertical angle:

Selectable ON/OFF with parameter Liquid, 2-axis tilt sensor SET2B:1" (0.2mgon) SET3B:1" (0.2mgon) SET4B:5" (1mgon) ±3'

Right/Left/Repetition/Hold (Selectable with keyboard) Zenith 0° (0gon)/Horizontal 0° (0gon)/ Horizontal 0°±90° (0gon ±100gon) (Selectable with parameter)

Distance measurement

Measuring range:		(Slight haze, visibility about 20km, sunny peri ods, weak scintillation)
	SET2B:	Compact prism CP01:1.3m to 800m (2600ft)
ĺ		Standard prism APx1:1.3m to 2400m (7800ft)
		Standard prism APx3:1.3m to 3100m (10100ft)
		Standard prism APx9:1.3m to 3700m (12100ft)
	SET3B:	Compact prism CP01:1.3m to 700m (2200ft)
		Standard prism APx1:1.3m to 2200m (7200ft)
		Standard prism APx3:1.3m to 2900m (9500ft)
		Standard prism APx9:1.3m to 3500m(11400ft)
	SET4B:	Compact prism CP01:1.3m to 600m(1900ft)
_		Standard prism APx1:1.3m to 1200m(3900ft)
		Standard prism APx3:1.3m to 1700m(5500ft)
		Standard prism APx9:1.3m to 2200m(7200ft)
Accuracy:		
Fine measuremen	it:	SET2B: \pm (3 + 2ppm × D) mm (unit:mm)
		SET3B: \pm (3 + 3ppm × D) mm (unit:mm)
		SET4B: \pm (5 + 3ppm × D) mm (unit:mm)
Coarse measurem	nent:	$\pm (5 + 5ppm \times D)mm$ (unit:mm)
Minimum display:		
Fine measuremer	nt:	1mm (0.01 ft)
Coarse measurem	nent:	1mm (0.01 ft)
Tracking measure	ement:	10mm (0.1 ft)
Maximum slope distance:		9999.999m (32808.33 ft)
Distance unit:	•	metres/feet
		(Selectable with parameter)
-	•	(Changeable for 5 seconds with keyboard)

Measuring time:

-			
	Fine meas.	Coarse meas.	Tracking meas.
Slope distance	4.7 + every 3.2s	1.7 + every 0.7s	1.6 + every 0.3s
Horizontal distance	4.7 +	1.9 +	1.8 +
Height difference	every 3.3s	every 0.7s	every 0.3s
Coordinates	5.1+ every 3.3s	2.4 + every 0.7s	2.2 + every 0.7s
REM	0.7s + every 0.5s		
Horizontal distance between two points	5.6 + every 3.3s	2.9 + every 0.7s	2.8 + every 0.7s

Atmospheric correction:

Temperature input range:

Pressure input range:

ppm input range: Prism constant correction: Earth-curvature and refraction correction: Audio target acquisition: Signal source: Light intensity control:

Power supply

Power source: Working duration at 25°C (77°F): -30°C to 60°C (in 1°C steps)/ -22°F to 140°F (in 1°F steps) (Selectable with parameter) 500hPa to 1400hPa (in 1hPa steps) 375mmHg to 1050mmHg (in 1mmHg steps) 14.8inchHg to 41.3inchHg (in 0.1inchHg steps) (Selectable with parameter) -499 to 499ppm (in 1ppm steps) -99mm to 99mm (in 1mm steps) ON (K=0.142/K=0.20)/OFF (Selectable with parameter) ON/OFF (Selectable with parameter) Infrared LED Automatic

(When "C+R correction" is not being applied.)

Ni-Cd rechargeable battery, BDC25/25A'(6V) Distance & Angle measurement: 2.5 hours (2500 to 2600 points) (Coarse and Single measurement, Measurement interval=every 4 secs) Angle measurement only: 9.5 hours Using optional battery BDC12 Angle and distance: 15 hours



Charging time: CDC11/11D/11E: CDC27/31/31A/47:



General



Display:



Sensitivity of levels: Plate level:



Circular level: Optical plummet: Image:



Magnification: Minimum focus: Self-diagnostic function: Power saving cut off:



Operating temperature: Data recording:





Weight:







15 hours 80 minutes

2LCD dot matrix displays on each faceMain display:16 characters x 3 linesSub display:4 characters x 3 lines

SET2B:20" /2mm SET3B:30" /2mm SET4B:30" /2mm 10'/2mm

Frect 3x 0.1m (0.3ft) Provided 30minutes after operation/ ON/OFF with switch (Selectable with parameter) -20°C to 50°C (-4°F to 122°F) 100 coordinate data can be stored in an internal memory Asynchronous serial, RS-232C compatible 236mm (9.3inch) from tribrach bottom, 193mm (7.6inch) from tribrach dish SET2B:168(W)X177(D)X371(H)mm SET3B:168(W)X177(D)X371(H)mm SET4B:168(W)X170(D)X371(H)mm (Without handle: H:330mm) SET2B:7.0Ka SET3B:7.0Kg SET4B:7.0Kg (with internal battery)



spheric correction can be input to the SET B for every ppm.

To convert a pressure in mmHg to one in hPa, divide by 0.75 To convert a pressure in inchHg to one in hPa, multiply by 33.87. $hPa = mmHg + 0.75 = 33.87 \times inchHg$

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To convert a temperature in °F to one in °C, compute using the following formula:

°C = 0.56 x (°F – 32)

Radio Frequency Interference

Peter Norten

WARNING: Changes or modifications to this unit not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

NOTE: This equipment has been tested and found to comply with the limits for a Class A digital device pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

Notice for Canada

This Class A digital apparatus meets all requirements of Canadian Interference-Causing Equipment Regulations.

Cet apparareil numérique de la Class A respecte toutes les exigences du Réglement sur le matériel brouilleur du Canada.





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CE Conformity Declaration in accordance with EMC Directive 89/336/EEC of the European Community			
We herewith declare that the undermentioned instrument, in view of its design and type of construction, fully complies with the relevant basic radio interference requirements of the EMC Directive. Should the instrument be modified without agreement, this declaration becomes invalid.			
Instrument Description: Power Supply (Battery Charger)			
Model Name : CDC31			
Relevant EC Directive: EMC Directive (89/336/EEC) Version: 91/263/EEC, 92/31/EEC, 93/68/EEC			
Applied Harmonized Standard: EN50081-1 1992, and EN50082-2 1995			
Date: Dec. 95 Firm: SOKKIA B.V. Address: Industrieterrein De Vaart, Damsluisweg I, NL-1332 EA Almere			
Representative's Signature:			
Name of Representative : Stephen Blaikie Representative's position : European vice President			

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