# SURVEYING INSTRUMENTS

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# SET2CII SET3CII SET4CII Intelligent Total Station

# OPERATOR'S MANUAL

### SURVEYING INSTRUMENTS

# SET2C证 SET3C证 SET4C证 Intelligent Total Station

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## OPERATOR'S MANUAL

Congratulations on your purchase of the SET CII Series! Before using the instrument, please read this operator's manual and verify that all equipment is included, refer to P. 232 "STANDARD EQUIPMENT".

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- <Important>



Tribrach clamp locking screw

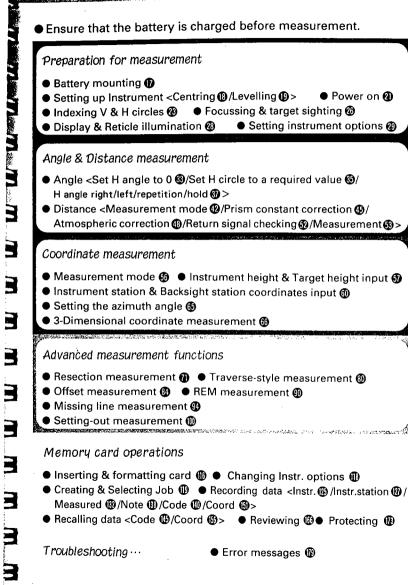
When the new SET C is shipped, the tribrach clamp is fixed with a screw.

Loosen it and leave it loose.

And if the SET C is again shipped, fix the tribrach clamp with the screw to stop the tribrach becoming detached from the instrument.

The specifications and general appearance of the instrument may be altered at any time and may differ from those appearing in catalogues and this operator's manual.

# QUICK GUIDE TO THIS MANUAL



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• Power on **(a)** 

# 1. FEATURES

### < SET CII ADVANCED MEASUREMENT FUNCTIONS >

- Resection measurement
- Traverse-style coordinate measurement
- Offset measurement
- REM measurement
- Missing line measurement
- Setting-out measurement

### < MEMORY CARD OPERATION >

- Set the job name
- Record and review the data
   Instrument data/Instrument station data/Measured data/Note/Co ordinate data/Feature code
   One 64Kb card cap stars approximate to data

One 64Kb card can store approximately 1000 measured target points in angle and distance (S, V, H) format.

 Recall the data stored on Card to Instrument Feature code/Coordinate data

### < TILT ANGLE COMPENSATION >

- Dual axis tilt sensor
- The index error of the tilt angle can be eliminated

### < COLLIMATION PROGRAM >

 The collimation error between the centre of the telescope reticle and the sighting line can be calculated, and the correction value specified is set. (for angle measurement of high accuracy.)

### < DATA OUTPUT >

- The SET CIIRS232C-compatible data output connector allows 2way communication with an external device.
- Key operations allow the SET C to output the data stored on the card via the data output connector to an external device using an interface cable.

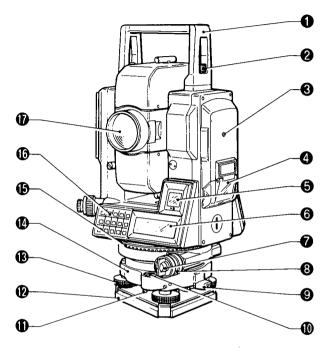
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7	DISPLAY SYMBOLS	<sub>€\$</sub> 7 P.13



# 2. PRECAUTIONS

- Never place the SET C directly on the ground. Avoid damaging the tripod head and centring screw with sand or dust.
- Do not aim the telescope at the sun. Avoid damaging the LED of the EDM.
- Protect the SET C with an umbrella. against direct sunlight, rain and humidity.
- Never carry the SET C on the tripod to another site.
- Handle the SET C with care. Avoid heavy shocks or vibration.
- When the operator leaves the SET C, the vinyl cover should be placed on the instrument.
- Always switch the power off before removing the standard battery.
- Remove the standard battery from the SET C before putting it in the case.
- When the SET C is placed in the carrying case, follow the layout plan.
- Make sure that the SET C and the protective lining of the carrying case are dry before closing the case. The case is hermetically sealed and if moisture is trapped inside, damage to the instrument could occur.

# 3. PARTS OF THE INSTRUMENT



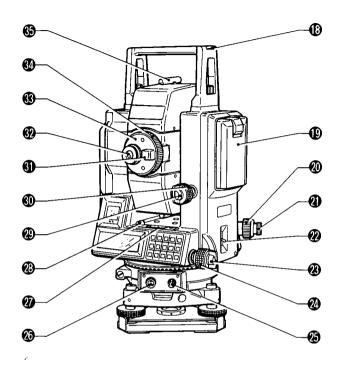
- Handle
- **2** Handle securing screw
- **③** Instrument height mark
- Gard cover
- Sub display
- 6 Main display
- O Lower clamp
- O Lower clamp cover
- O Tribrach clamp
- O Circular level

6

Circular level adjusting screws

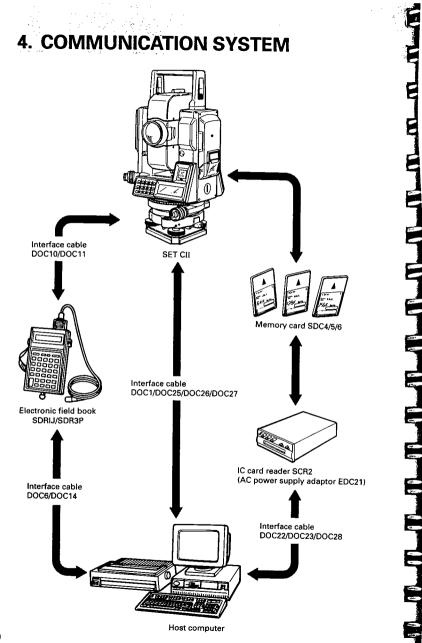
- Base plate
- B Levelling foot screw
- Tribrach
- Horizontal circle positioning ring
- Keyboard
- Objective lens



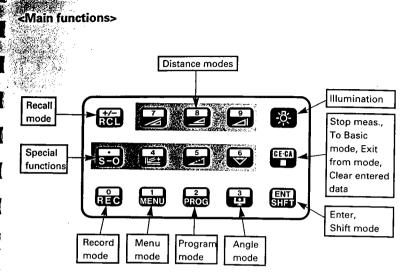


- Tubular compass slot
- Battery BDC25
- Optical plummet focussing ring
- Optical plummet eyepiece
- Power switch
- Horizontal clamp
- Horizontal fine motion screw
- Ø Data output connector
- External power source connector

- Plate level
- Plate level adjusting screw
- Ø Vertical clamp
- Ø Vertical fine motion screw
- Telescope transitting knob
- Telescope eyepiece
- Telescope reticle adjustment cover
- Telescope focussing ring
- Peep sight

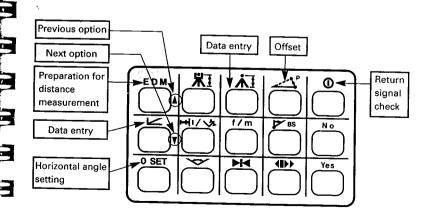


# 5 KEY JUNCTIONS

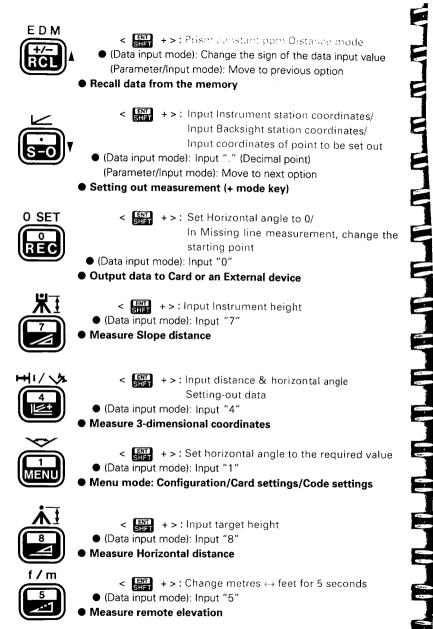


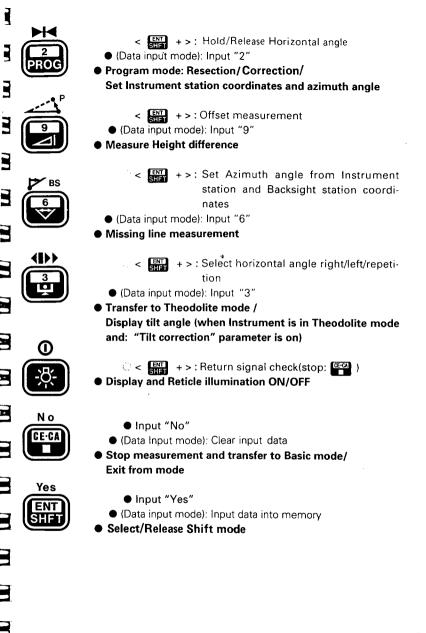
### <Shift functions>

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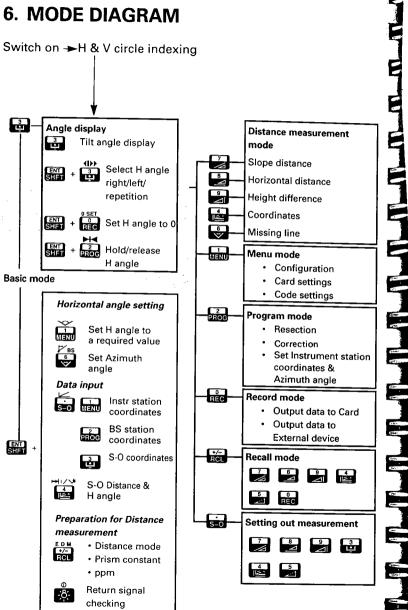


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# 6. MODE DIAGRAM



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# . DISPLAY SYMBOLS

### <Sub display>

### ppm/P.C/MODE

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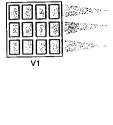
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			ospheric correction value) n constant correction value)
Г	· _+	:	Tilt angle compensation on
L	SHFT	:	Shift
	SO	:	Setting-out measurement mode
L	MENU	:	Menu mode
	PROG	:	Program mode
	REC	:	Record mode
	RCL	:	Recall mode
L	Stn	:	Instrument station coordinates
1	BS	:	Backsight station coordinates

Pt : Coordinate setting-out data

### <Main display>

- : Select options S н : Zenith angle (Z 0°) v ZA VA : Vertical angle (H 0°) Ht Vertical angle (H 0°±90°) D HAR : Horizontal angle right : Horizontal angle left HAL HARp: Horizontal angle repetition : Horizontal angle hold HAh dHA : Horizontal angle from setting-out data Х : Tilt angle in sighting direction Y : Tilt angle in horizontal axis direction
- : Slope distance
- : Horizontal distance
- : Height difference
- : REM value/Instrument height/Target height
- : Distance setting-out data/ Offset distance

PREPARATION FOR MEASUREMENT

8. MOUNTING THE BATTERY æ P.17 **ﷺ** P.18 9. SETTING UP THE INSTRUMENT Centring ( 9.1 Levelling **(** 9.2 ্ব ₽.21 **10. POWER ON 11. PREPARATION FOR MEASUREMENT** æ P.23 Indexing the vertical and horizontal circles @

- 11.1
- Focussing and target sighting @ 11.2

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- 11.3 Display and reticle illumination @
- Setting the Instrument options @ 11.4

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# 8. MOUNTING THE BATTERY

- Charge the battery fully before measurement. ap P.211
- Note: Turn off the power supply switch @ before replacing the battery.



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### < Mounting the battery >

- 1) Close the battery release button cover.
- Match the battery guide with the hole in the instrument battery recess.
- Press the top of the battery until a click is heard.

### < Removing the battery >

- 1) Open the battery release cover.
- 2) Press the release button downward.
- 3) Remove the battery.

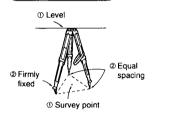
• If the power is to be turned on immediately after replacing the battery, please refer to P. 21.

# 9. SETTING UP THE INSTRUMENT

 Mount the battery in the instrument before performing this operation, because the instrument will tilt slightly if the battery is mounted after levelling.

# 9.1 Centring

### Set up the tripod

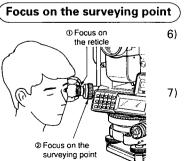


### Install the instrument

 Make sure the legs are spaced at equal intervals and the head is approximately level. Ę

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- Set the tripod so that the head is positioned over the surveying point.
- Make sure the tripod shoes are firmly fixed in the ground.
- Place the instrument on the tripod head.
- Supporting it with one hand, tighten the centring screw on the bottom of the unit to make sure it is secured to the tripod.



Centring screw

- Looking through the optical plummet eyepiece, turn the optical plummet eyepiece **(4)** to focus on the reticle.
- Turn the optical plummet focussing ring @ to focus on the surveying point.

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# 9.2 Levelling

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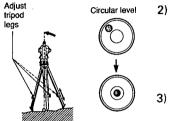
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### Centre the surveying point in the reticle

1)

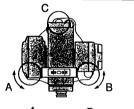
- De Optical plummet
- Adjust the levelling foot screws (B) to centre the surveying point in the optical plummet reticle.

### Centre the bubble in the circular level



- One more tripod leg must be adjusted to centre the bubble.

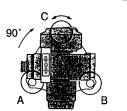
### Centre the bubble in the plate level





- Loosen the horizontal clamp 
   <sup>®</sup> to turn the upper part of the instrument until the plate level 
   <sup>®</sup> is parallel to a line between levelling screws A and B.
- 5) Centre the air bubble, using levelling screws A and B.
  - Note: The bubble moves towards a clockwise rotated foot screw.

### Turn 90° and centre the bubble

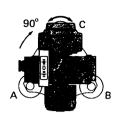


6) Turn the upper part of the instrument through 90°.

The plate level is now perpendicular to a line between levelling screws A and B.

7) Centre the air bubble, using levelling screw C.

### Turn another 90° and check bubble position



 Turn the upper part of the instrument a further 90° and check to see if the bubble is in the centre of the plate level Ø.

If the bubble is off-centre, perform the following: Ę

- ① Adjust levelling screws A and B in equal and opposite directions, to remove half of the bubble displacement.
- Turn the upper part a further 90°, and use levelling screw C to remove half of the displacement in this direction.

Or try the adjustment described on P.183, under "23.1 Plate level".

### Check to see if bubble is in same position in any direction

 Turn the instrument and check to see if the air bubble is in the same position for any position of the upper part.

If it is not, repeat the levelling procedure.

Focus on the centre of the reticle again



- 10) Loosen the centring screw slightly.
- Looking through the optical plummet eyepiece, slide the instrument over the tripod head until the surveying point is exactly centred in the reticle.
- 12) Re-tighten the centring screw securely.

### Check plate level bubble again

 Check again to make sure the bubble in the plate level is centred. (If not, repeat the procedures starting from step 4).)

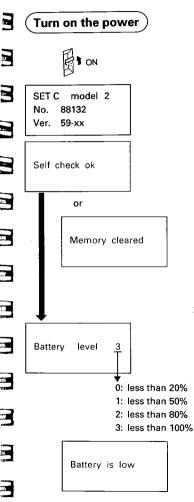


## **10. POWER ON**

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• When the power is turned on, a self-check is run to make sure the instrument is operating normally.



- Turn on the power switch @ after completing sections 8 and 9.
- The instrument name, instrument number, and software version are displayed for several seconds, an audio tone sounds, and the instrument performs self-diagnostic checks.

On successful completion of the checks, "Self check ok" is displayed for 2 secs.

- Note: After power-off for more than 1 week, the previously stored data have been cleared from the short-term memory and "Memory cleared" is displayed.
- 3) The remaining battery power is then displayed for 3 seconds as a numeric value.

(BDC25, Coarse meas. mode, Single meas., Temperature 25°C)

If the battery is at the "low" level, the message "Battery is low" will be displayed, and an audio tone sounds. Turn the power off and charge the battery.

If the battery power becomes low during surveying, the same message will be displayed. ì

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- This display indicates that the instrument is ready for vertical and horizontal circle indexing.
- If the parameter horizontal indexing is set to "Manual", a horizontal angle of 0° is displayed, when the power is turned on.

If this error message is displayed, the instrument tilt sensor is indicating that the instrument is offlevel. Relevel the instrument once again, using the plate level bubble.

 When "Face 1" is displayed for the vertical angle, please refer to P.217 (Appendix 1: Manually indexing the vertical circle).

Instrument parameter No.8 JP P.201 Parameter No.8 can change the indexing method. Options are indexing by transitting the telescope or indexing by face left, face right sightings.

### [Note: Changing the brightness of the display]

 If the display appears too dim or too bright, the keyboard can be used to adjust the brightness level (6 levels).

For a brighter display  $\rightarrow$  Press and  $\frac{1}{100}$  at the same time. For a dimmer display  $\rightarrow$  Press and  $\frac{1}{100}$  at the same time.

### [Note: Power-saving cut-off]

SET C switches off automatically 30 minutes after the last key operation.

• Parameter No. 12 can be changed so that the SET C will not switch off automatically after 30 minutes.

# **11. PREPARATION FOR MEASUREMENT**

# 11.1 Indexing the vertical and horizontal circles

(H and V circle indexing parameters - "Auto")

# Vertical circle indexing

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ZA 91' 04' 30" HAR 0 SET

### Horizontal circle indexing

- ZA 91° 04' 30" HAR 350° 39' 00"

- 2) An audio tone sounds, and the vertical angle (ZA) is displayed.

Vertical indexing has been completed.

Loosen the horizontal clamp 
 and rotate the upper part of the instrument completely.

(Indexing occurs when the plate level **@** passes the 0 mark of the horizontal positioning ring.)

 The audio tone sounds, and the horizontal angle (HAR) is displayed.

Horizontal indexing has been completed.

Note: Each time the instrument is switched on, the vertical and horizontal indexes must be redetermined.

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### [Note: Horizontal angle back-up]

- The parameter No.9 default setting allows for the memorization of the previous horizontal 0 position at power-off for about 1 week. ("Memory cleared" is displayed after more than 1 week of power off.) H and V circles are each provided with a 0 index. When next switching on the SET C and indexing the horizontal circle again, the horizontal angle is recovered at the previously-memorized 0 position. This feature is useful when the battery voltage becomes low during measurement or after automatic power-off has occurred.
  - —– Instrument parameter No. 9 ᡒ P.201 –
  - Parameter No.9 can be used to change the horizontal circle indexing method. Options are indexing by rotating the upper part or indexing and zero setting at power-on.

### [Note: Automatic tilt angle compensation]



 When the ⊥+ symbol is shown on the subdisplay, the vertical and horizontal angles are automatically compensated for small tilt errors using the 2-axis tilt sensor. 67236 5386

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- Read the compensated angle after the displayed angle value becomes steady.
- The formula used for calculation of the compensation value applied to the horizontal angle uses the tilt and vertical angles as shown below:

Compensated horizontal angle = Measured horizontal angle + <u>Tilt in angle Y</u> tan(Vertical angle)

Therefore, when the SET C is not perfectly levelled, changing the vertical angle by rotating the telescope will cause the displayed (compensated) horizontal angle value to change. (The displayed horizontal angle value will not change during telescope rotation when the instrument is correctly levelled.)

- When the measured vertical angles are within ±1° of the zenith or nadir, tilt compensation is not applied to the horizontal angle. In this situation, the displayed horizontal angle value flashes to show that the tilt compensation is not being applied.
  - Instrument parameter No.3 ᡒ P.201
  - Parameter No.3 can be used to switch off and on the automatic tilt angle compensation; for example, the automatic compensation should be switched off if the display is unsteady due to vibration or strong wind.

### [Note: Levelling using the tilt angle display]

• For levelling, the tilt angle X and Y values can be displayed for use as a 2-axis (X,Y) tilt sensor. The tilt angle values are used to automatically correct the vertical and horizontal angles for error due to the non-verticality of the vertical axis. The measurement range is ±3'. The "Tilt correction (Dual axis)" parameter must be set to "Yes".



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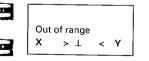
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Tilt a	gle
Х	0°01'20"
Y	0° 00' 40"

- X: Levelling foot screws AB Y: Levelling foot screw C (in above illustration)
- Tilt angle minimum display unit SET2C:1" SET3C:1" SET4C:5"





To Theodolite mode To Basic mode

- In Theodolite mode, turn the upper part of the instrument until the telescope is parallel to a line between levelling foot screws A and B and tighten the horizontal fine motion screw @.
- 2) Press 🛃 .
- The X and Y tilt angles are displayed.
  - X : Tilt angle in sighting axis direction
  - Y : Tilt angle in horizontal axis direction
- Set both tilt angles to 0° by turning the levelling screws A and B for the X direction and C for the Y direction.
- "Out of range" indicates that the tilt angle exceeds the ±3' measurement range.
- To exit from the tilt angle display, press to return to Theodolite mode or press to go to Basic mode.

To record the horizontal, vertical and tilt angles on the card, please refer to P.113.

# 11.2 Focussing and target sighting

### Focus on the reticle



Sight the target

Line the target with the white arrow in the peep sight

(0

- Look through the telescope eyepiece 
   Ø at a bright and featureless background.
- Turn the eyepiece clockwise, then counterclockwise little by little until just before the reticle image goes out of focus.

Using this procedure, frequent reticle refocussing is not necessary, since your eye is focussed at infinity.

- 4) Tighten both clamps.
- Turn the focussing ring @ to focus on the target.
- 6) Turn the vertical @ and horizontal
   @ fine motion screws to align the target object with the reticle.

The last adjustment of each fine motion screw should be in the clockwise direction.



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< Target centre>



<Prism centre>

- The relation between the target and the reticle is shown in the illustration at the left.
- First, align the measuring point precisely with the centre of the target.

Then align the reticle precisely with the centre of the target.

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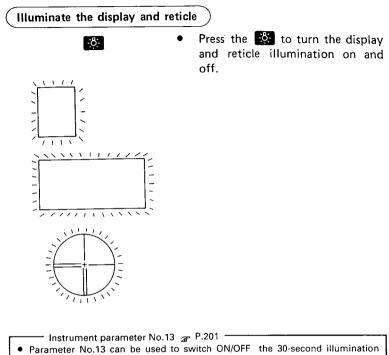
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- Note: Observe to the same point of the reticle when the telescope face is changed.

### [Note:Parallax]

- This is the relative displacement of the target image with respect to the reticle when the observer's head is moved slightly before the eyepiece.
  - Parallax will introduce reading errors and must be removed before observations are taken. Parallax can be removed by refocussing.

# 11.3 Display and reticle illumination



- automatic cut-off facility.
  - --- Instrument parameter No.15 🛷 P.201 --
- Parameter No.15 can be used to change the brightness of the reticle illumination.

# 11.4 Setting the Instrument options

- Confirm that these parameters, indispensable for measurement, are set according to your required measurement.
- Data storage period : Until next changing (Power-off possible)
  - To confirm or change the parameter options, please refer to P.201 "24. CHANGING INSTRUMENT PARAMETERS".



No.	Parameter			Options
3	Tilt correction			Correction YES* / Correction NO
4	Coordinate format			N, E, Z*/E, N, Z
5	Vertical angle format			Zenith angle (zenith 0°) * /
				Vertical angle (horizontal 0°) /
				Vertical angle (horizontal 0° ± 90°)
6	Angle resolution		SET2C	1" (0.2 mgon) * / 5" (1 mgon)
	SET3		SET3C	1" (0.2 mgon) * / 5" (1 mgon)
			SET4C	5" (1 mgon) * / 10" (2 mgon)
10	C + R correction			No correction * /
				Yes K = 0.142
				Yes K = 0.20 🚓 P. 225
11	1	1 Distance unit		metres*/feet
	2	Angle unit		360°* / 400gon
	3 Temperature/Pressure		e/Pressure	°C & mbar* / °C & mmHg / °F & mbar/
	ľ	units		°F & mmHg/ °F & inchHg

\* Factory setting

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• For other parameters, please refer to P.201 "24. CHANGING IN-STRUMENT PARAMETERS".

# CALIFICATION OF A CALIFIC AND A CALIFICATION OF A CALIFICATION OF

MEASUREMENT

### **12. ANGLE MEASUREMENT**

- Measure the horizontal angle between two points @ 12.1 <Horizontal angle 0>
- Set Horizontal circle to a required value @ 12.2
- 12.3 Horizontal angle display @ <Angle right/left/repetition/hold>

### **13. DISTANCE MEASUREMENT**

- 13.1 Measurement mode selection @
- 13.2 Prism constant input @
- Atmospheric correction @ 13.3
- 13.4 Returned signal checking @
- 13.5 Slope distance/Horizontal distance/ Height difference measurement @
- Review of measured data 60 13.6

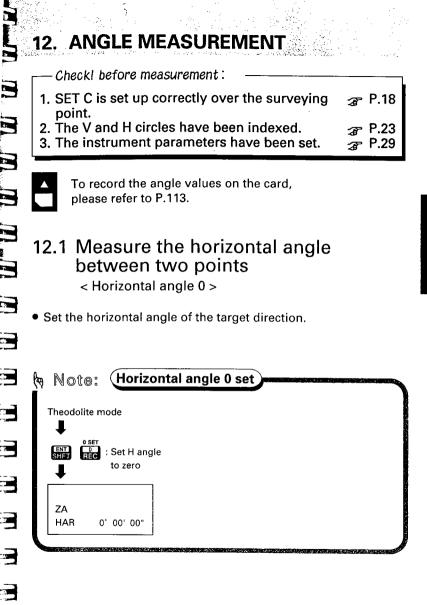
### **14. COORDINATE MEASUREMENT**

- 14.1 Measurement mode selection @
- Instrument height and target height input @ 14.2
- 14.3 Instrument station coordinates and backsight station coordinates input @
- 14.4 Setting the azimuth angle from Instrument and backsight station coordinates @
- 3-Dimensional coordinate measurement @ 14.5

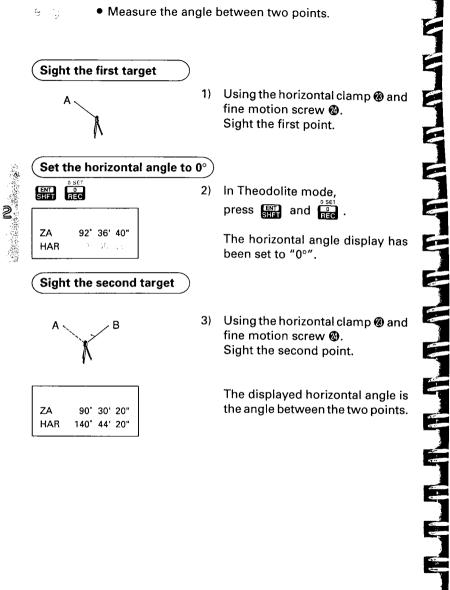
2 P.33

æ P.42

æ P.56



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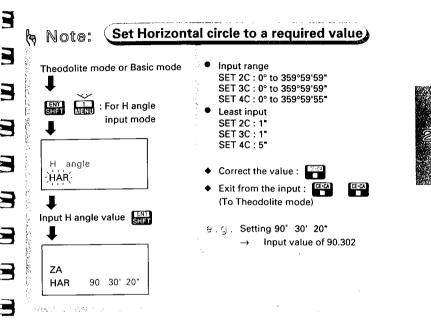


# 12.2 Set Horizontal circle to a required value

2

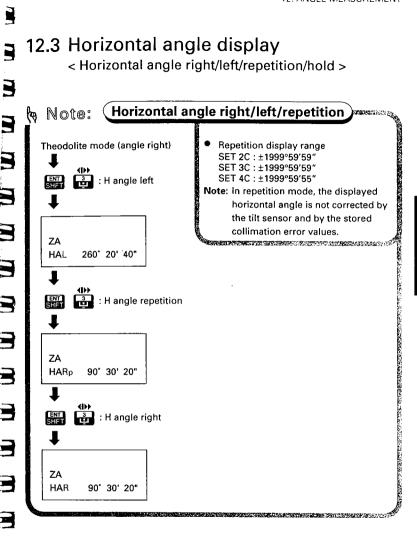
R

Set the horizontal circle of the target direction to a required value.



6)

AL REAL REAL R Set the horizontal angle of reference target R to ຣ.ຊຸ. 60° 00'20". Sight target R 1) Using the horizontal clamp 🕲 and fine motion screw @. Sight target R. From Theodolite mode or Basic mode to H Angle Input mode 2) In Theodolite mode or Basic ENT mode, press The display appears as at left, and angle "HAR" flashes to prompt for the HAR input of the horizontal angle value. Input the horizontal angle) Input "60.002". 3) € 0 ▼ REC S=0 REC REC PROG angle 60.002 ENT Press E to finish inputting. 4) The instrument returns to Theodolite mode. ΖA 90° 30' 00" Here, the horizontal angle for tar-2 60' 00' 20" HAR get R has been set to 60° 00'20".

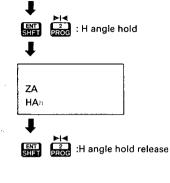




Theodolite mode (right/left/repetition)

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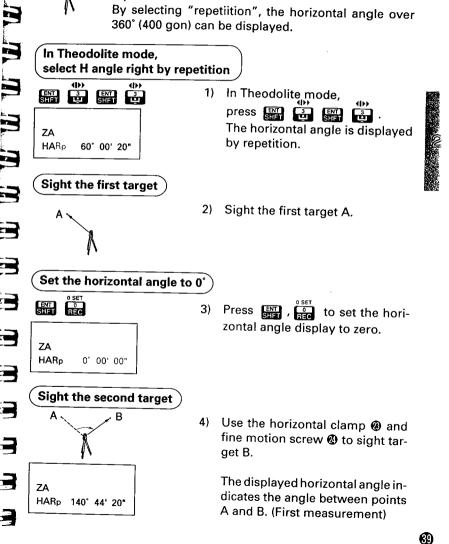


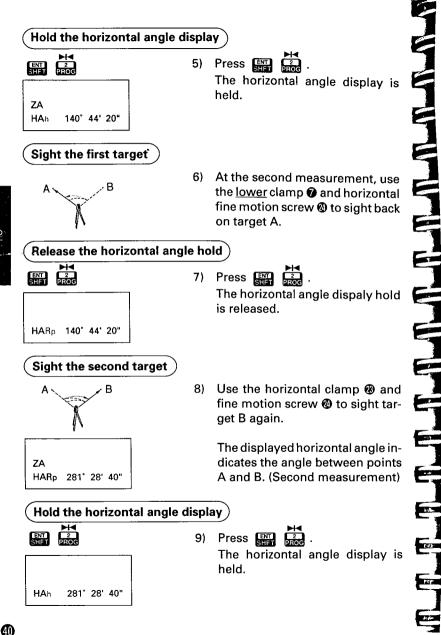
Horizontal angle repetition mode.

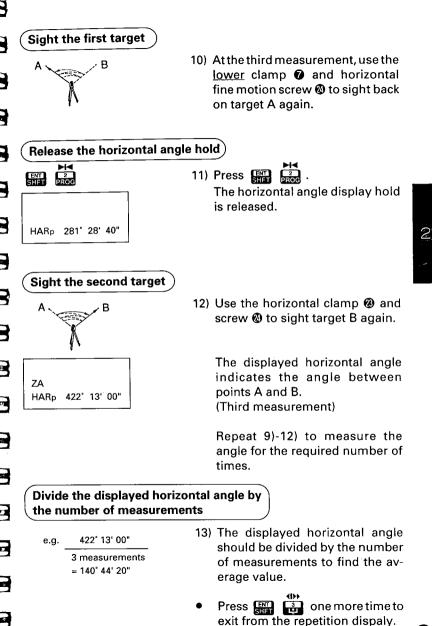


For higher accuracy horizontal angle measurement, the average horizontal angle should be measured by repetition.

By selecting "repetiition", the horizontal angle over 360° (400 gon) can be displayed.



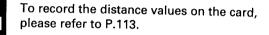




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# **13. DISTANCE MEASUREMENT**

- The following preparations are required for Distance measurement.
  - 13.1 Measurement mode selection
  - 13.2 Prism constant input
  - 13.3 Atmospheric correction
  - 13.4 Return signal checking

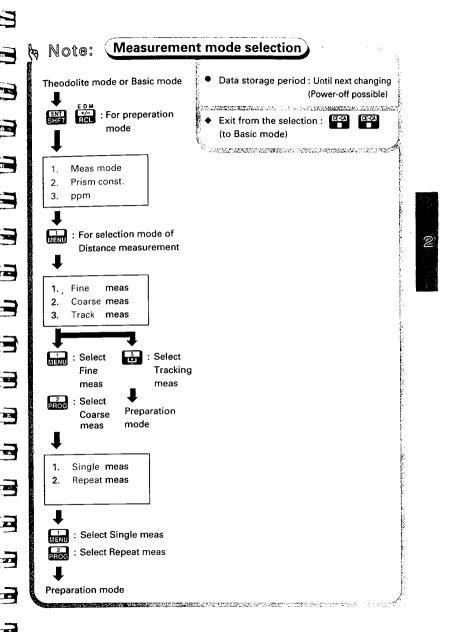




# 13.1 Measurement mode selection

 Select the measurement mode from the following according to your required measurement.

Measurement mode		Measurement time (slope distance)	Units
Fine meas.	Single	4.7 secs	
	Repeat	First 4.7 secs & every 3.2 secs	
Coarse meas.	Single	1.7 secs	- 1mm
	Repeat	First 1.7 secs & every 0.7 secs	-1
Tracking meas.		First 1.6 secs & every 0.3 secs	10mm



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ອູຊູ, • Selecting the "Repeat" option under Fine measurement

### From Theodolite mode or Basic mode to Preparation mode



- 1. Meas mode
- 2. Prism const.
- 3. ppm

 In Theodolite mode or Basic mode, 

The display appears as at left, showing Preparation mode.

### To Selection mode of Distance measurement mode

### MENU

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### 1. Fine meas

- 2. Coarse meas
- 3. Track meas

### 2) Press .

The display appears as at left, and the previously selected measurement type flashes.

### Select Fine measurement

MENU

- 1. Single meas
- 2. Repeat meas

### Select Repeat measurement

### 2 PROG

- 1. Meas mode
- 2. Prism const.
- 3. ppm

### 3) Press .

The display appears as at left, and the previously selected measurement type flashes.

### Press Proc

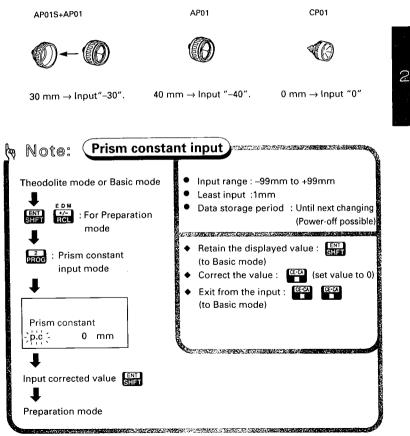
4)

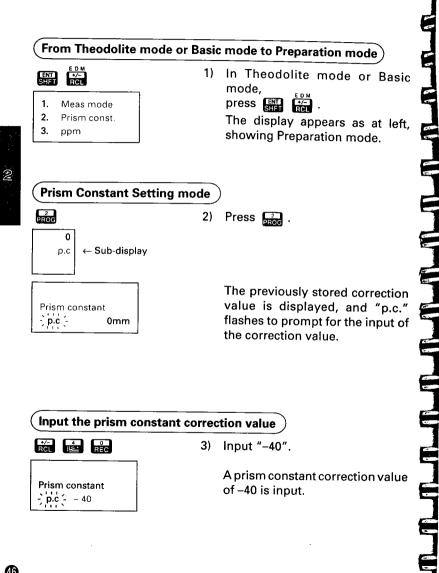
Fine and Repeat measurement modes are set, and the instrument returns to Preparation mode.

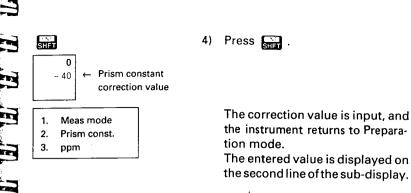
 To return to the Basic mode after this , press

# 13.2 Prism constant input

- Each reflecting prism type has a different prism constant value. Here, we will input the constant correction value for the reflecting prism being used.
- The prism constant correction values for reflecting prisms made by Sokkia are as follows:







ter this,



 To return to Basic mode after this, press ଜ୍ୟୁଥ .

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CE-CA : To Basic mode

- 3
- E E

# 13.3 Atmospheric correction

- **Note**: To obtain the average refractive index of the air throughout the measured light path, you should use the average atmospheric pressure and temperature. Take care when calculating the correction factor in mountainous terrain.

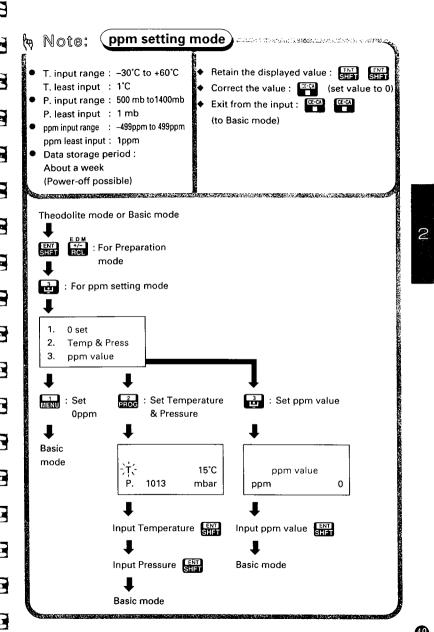
P.223, Appendix 3

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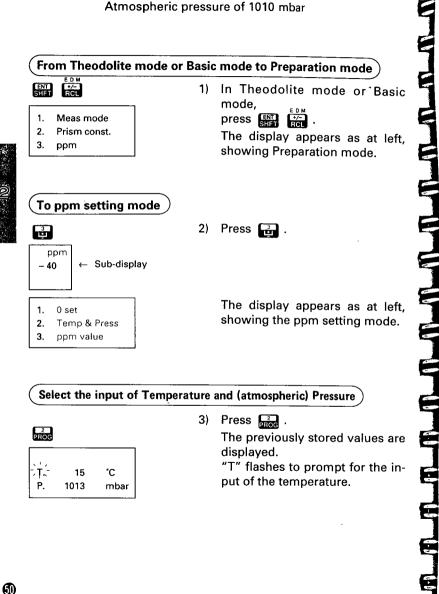
- The SET C is designed so that the correction factor is 0 ppm for a temperature of +15°C (+59°F) and an atmospheric pressure of 1013 mbar (29.9 inch Hg).
- By inputting the temperature and pressure values, the correction value is calculated and set into the memory. The formula used is as follows:

ppm =  $278.96 - \frac{0.2904 \text{ x P (mb)}}{1+0.003661 \text{ x T (°C)}}$ 

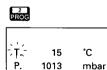
- To input ppm value, read the correction factor from the table on P.238.
- For precise distance measurement, relative humidity should be taken into account together with atmospheric pressure and ambient temperature. See P.223.



 Temperature of 20°C and э.<u>с</u>, Atmospheric pressure of 1010 mbar



Select the input of Temperature and (atmospheric) Pressure

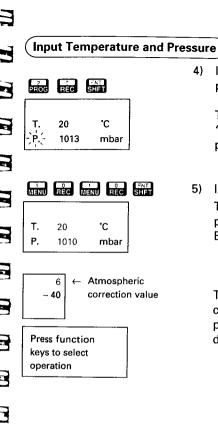


3) Press 2.

> The previously stored values are displayed.

> "T" flashes to prompt for the input of the temperature.

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4) Input "20" and press

The temperature "20°C" is input. "P" flashes to prompt for the input of the pressure.

5) Input "1010" and press The pressure "1010 mbar" is input, and the instrument returns to Basic mode.



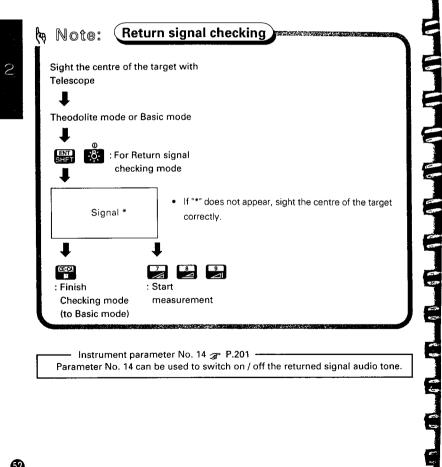
The atmospheric value coefficient is calculated, and is displayed on the first line of the subdisplay.

# 13.4 Return signal checking

• Especially for long distances, it is useful to check that the returned signal is adequate for measurement.

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Note : When the light intensity coming back from the reflecting prism is very high (short distance) an asterisk "\*" may be displayed, even for a slight mis-sighting. Therefore make sure that the target centre is sighted correctly.



Instrument parameter No. 14 🔐 P.201 -Parameter No. 14 can be used to switch on / off the returned signal audio tone.

# 13.5 Slope distance / Horizontal distance / Height difference measurement

The slope distance, the horizontal distance, and the height difference are measured simultaneously with the angle.

- Checkl before measurement:

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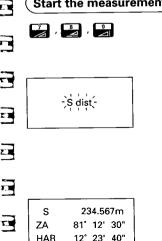
,

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Ω,

- 2 P.18 1. SET C is set up correctly over the surveying point. 2. The V and H circles have been indexed. ም P.23
- 3. The instrument parameters and the units 🔊 P.29
- have been set. 4. The distance measurement mode is selected. ☞ P.42
- 5. The prism constant correction value is set. \_\_\_\_\_\_ ⊋ P.45 æ P.48
- 6. The atmospheric correction is set.
- 7. The centre of the target is correctly sighted æ P.52 and the return signal is adequate for measurement.

Start the measurement from Theodolite mode or Basic mode



In Theodolite mode or Basic 1) mode.

press 🏹 , 🛃 or 🚔 .

This accesses the Distance measurement mode, and the distance measurement is started. The display appears as at left and flashes. (The illustration at the left shows an example of slope distance measurement.)

After about 4.7 seconds (Fine measurement mode), the distance value, the vertical angle and the horizontal angle are displayed.



# Stop the measurement





### After 2 minutes

s	Timeout		
ZA	81°12'30"		
HAR	12°23'40"		



ſ/m	
5	: Change
	metre $\leftrightarrow$ feet

s	769.57 ft		
ZA	81°12'30"		
HAR	12°23'40"		

2) Press 2 . (The display does not change.)

- If the single measurement mode has been selected, measurement stops automatically.
- Note: If "Signal off" is displayed, the return signal strength has become inadequate for measurement. Verify the target sighting. If within 2 minutes the return signal becomes sufficient, the measurement is restarted.

After 2 minutes, the measurement is stopped automatically and the display appears as at left:

In this case, sight the target again and restart the measurement. (The same display appears during measurement if the return signal is too weak. Press to stop measurement and sight the target again.)

Press Entry



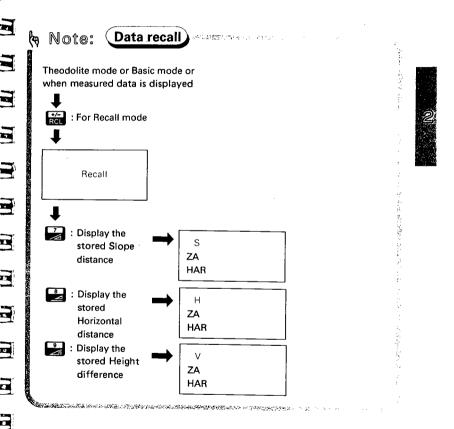
to change the distance unit for 5 seconds.

# 13.6 Review of measured data

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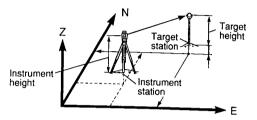
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• The distance and angle measured most recently are stored in the memory until the power is turned off. The stored slope distance, horizontal distance and height difference can be displayed in Recall mode as follows.



# 14. COORDINATE MEASUREMENT

 The SET C calculates the 3-Dimensional coordinates of the prism position. To calculate the Z (Height) coordinate, first enter the instrument and target heights, then the Instrument station coordinates.



- By inputting the Backsight station coordinates, sighting the backsight station and pressing a key on the SET C keyboard, the horizontal angle can be set to the azimuth value.
- The following preparations are required for Coordinate measurement.
  - 14.1 Measurement mode selection
  - 14.2 Instrument height and target height input
  - 14.3 Instrument station coordinates and Backsight station coordinates input
  - 14.4 Setting of azimuth angle from the instrument and backsight station coordinates.

# 14.1 Measurement mode selection

• Select the measurement mode from the following according to your required measurement.

See P.42 "13.1 Measurement mode selection " for key operation.

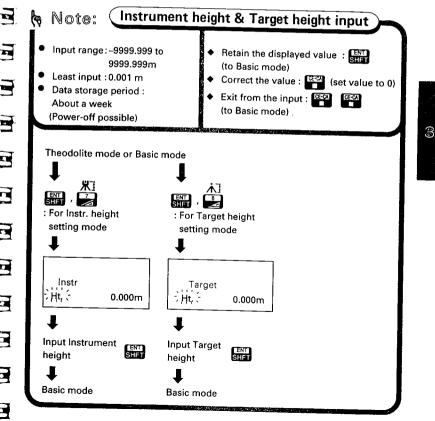
Measurement mode		Measurement time (slope distance)	Units
Fine meas.	Single	5.1secs	1mm
	Repeat	First 5.1 secs & every 3.3 secs	
Coarse meas.	Single	2.4 secs	
	Repeat	First 2.4 secs & every 0.7 secs	
Tracking meas.		First 2.2 secs & every 0.7 secs	10mm



# 14.2 Instrument height and target height input

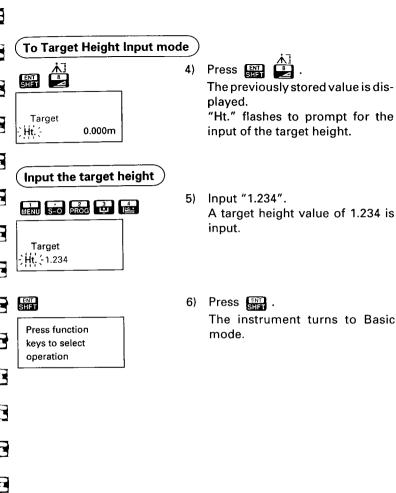
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- As preparation for coordinate measurement, the instrument height (the height difference between the surveying point and the instrument station height mark (2) and target height (the height difference between the surveying point and the centre of the target) should be input to the SET C before the measurement.
  - The heights of the instrument and the target are measured manually beforehand, using a measuring tape, etc.



- Input Instrument height of 1.567 m and ອ.ຝຸ. Target height of 1.234 m From Theodolite mode or Basic mode to Instrument Height Input mode 1) In Theodolite mode or Basic mode, press 🔛 🗂 The previously stored value is dis-Instr played. Ht. (-0.000m "Ht" flashes to prompt for the input of the instrument height. Input the instrument height 2) Input "1.567". An instrument height value of 1.567 is input. Instr Ht. 1.567
  - Press function keys to select operation

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Press function keys to select operation  Press . The instrument turns to Basic mode. 



# 14.3 Instrument station coordinates and Backsight station coordinates input

- The coordinates of the instrument setting surveying point (instrument station) and those of a point whose coordinates are already known (backsight station) can be input to the SET C.
- The coordinates of the backsight station are input in order to set the horizontal angle in the X-axis direction to 0°.
   If the azimuth angle is already known, the following steps are carried out:
  - 1) Input only the coordinates of the instrument station.
  - 2) Sight the backsight station.
  - Press is to turn Theodolite mode, and set the horizontal angle to the azimuth value.

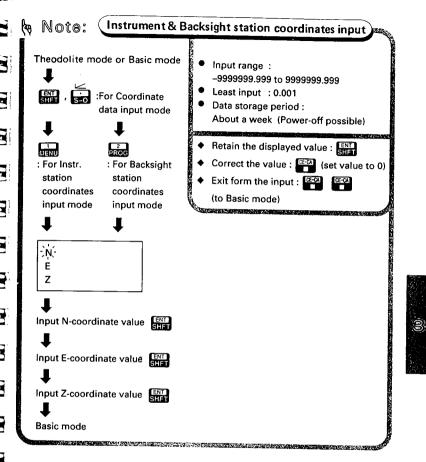
Then skip the instructions in Section 14.4 and go directly to Section 14.5.



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To recall the instrument station coordinates and backsight station coordinates from coordinate data stored on the card, please refer to P.113.

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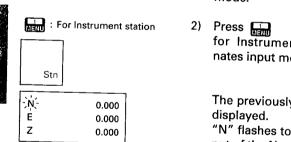
Ξ

 Instrument station coordinates are e.d. N = 31.1, E = 21.2, and Z = 1.3, and Backsight station coordinates are N = 10.1, E = 20.2, and Z = 3.3

### From Theodolite mode or Basic mode to Instrument station coordinate input mode

- : For Coordinates data input mode
- 1. Station
- 2. Backsight
- 3. S-O point





In Theodolite mode or Basic 1)

> mode. press 🔛 and 🗔 .

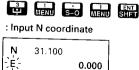
The display appears as at left, showing Coordinates Input mode.

for Instrument station coordinates input mode.

The previously stored values are

"N" flashes to prompt for the input of the N coordinate.

### Input Instrument station coordinates



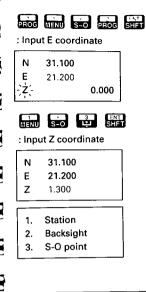
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- 0.000
- Input "31.1" and 3) press ENT .

The N coordinate is input. "E" flashes to prompt for the input of the E coordinate.



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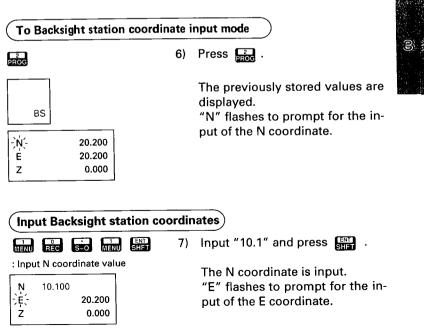
3

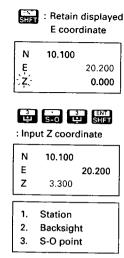
 Input "21.2" and press .

> The E coordinate is input. "Z" flashes to prompt for the input of the Z coordinate.

5) Input "1.3" and press .

The Z coordinate is input, and the instrument returns to Coordinate input mode.





<u>(</u>

 The displayed value is retained, so simply press

"Z" flashes to prompt for the input of the Z coordinate.

8) Input "3.3" and press SHET .

The Z coordinate is input, and the instrument returns to Coordinate input mode.

- Press and to return to Basic mode.

# 14.4 Setting the azimuth angle from Instrument and Backsight station coordinates

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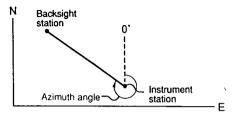
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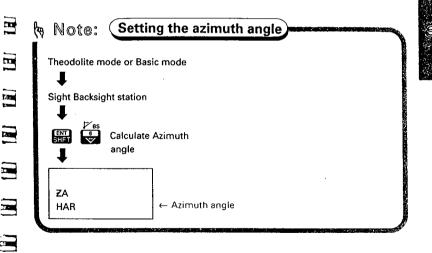
B

E

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With the SETC, the azimuth angle of the backsight can be automatically calculated from the input instrument station and backsight station coordinates. This means the horizontal angle is set to zero in the N direction.



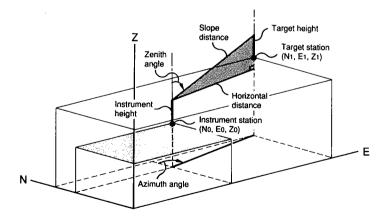
# 14.5 3- Dimensional coordinate measurement

 The coordinates of the target are calculated using the following formulas and the results are then displayed. It is first necessary to input the Instrument and prism heights, Instrument and Backsight station coordinates and calculate or input the azimuth angle (see previous pages).

> $N1 = N0 + S \times \sin\theta z \times \cos\theta h$ E1 = E0 + S \times \sin\theta \times \sin\theta h Z1 = Z0 + Mh + S \times \cos\theta z -Ph

Instrument station coordinates: (No, Eo, Zo)

Slope distance	: S
Zenith angle	: 0z
Azimuth angle	: 0h
Instrument height	: Mh
Target height	: Ph



To record the coordinate data on the card, please refer to P.113.



		· · · · ·		
;	Checkl before measuremen	t:		
Ξ	1. SET C is set up correctly point.	over the surveying	ar P.18	
	2. The V and H circles have 3. The Instrument parameter have been set.		ය P.23 ය P.29	:
	<ul> <li>4. The distance measureme</li> <li>5. The prism constant correction</li> <li>6. The atmospheric correction</li> </ul>	ction value is set.	ය P.42 ය P.45 ය P.48	
	7. The centre of the target i and the return signal is ac	s correctly sighted Jequate for measurem	ar P.52 nent.	
	<ul> <li>8. The instrument height and been input.</li> <li>9. The instrument station as</li> </ul>		சு P.57 சு P.60	
	station coordinates have 10. The azimuth angle is set.	been input	ar P.65	
	(Sight the target )			
	1)	Sight the centre of th prism correctly. (It is a mended to check the	also recom- returned	
		signal by pressing 🖁 P.52.)	H 🔅 7	
E E				
				~

### In Theodolite mode or Basic mode. start the coordinate measurement



N	123.456
E	345.678
Z	3.456



### Stop the measurement

- CE-CAT : Stop the measurement
- : Start next measurement
- : To Basic mode



3 : To Theodolite mode

In Theodolite mode or Basic 2) mode, press 🔛 .

This accesses Coordinate Measurement mode, and measurement of the 3-Dimensional coordinates is started. The display appears as at left and flashes.

After about 5.1 seconds (Fine measurement mode), the 3-Dimensional coordinates are displayed.

- Press (display does not 3) change).
- If the single measurement mode has been selected, the measurement stops automatically.
- Press 🛃 , 🛃 , 🛃 or 🛃 to start the next measurement. Pressing CE-CA returns to Basic to go to mode, or press Theodolite mode.
- To measure the next target point, check the prism constant correction, ppm values, and target height.
- If and are pressed, the last measured coordinate data can be displayed. 🔊 P.55



Review the measured data

# ADVANCED MEASUREMENT FUNCTIONS **15. RESECTION MEASUREMENT** æ P.71 **16. TRAVERSE-STYLE COORDINATE** æ P.80 MEASUREMENT **17. OFFSET MEASUREMENT** æ P.84 **18. REM MEASUREMENT** æ P.90 **19. MISSING LINE MEASUREMENT** æ P.94 19.1 Measurement mode selection @

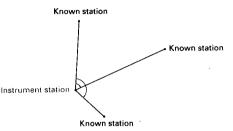
- 19.2 Measuring the distance between two or more points ()
- 19.3 Change of the starting position

### 20. SETTING-OUT MEASUREMENT

- æ P.100
- 20.1 Horizontal angle and distance setting-out measurement (1)
- 20.2 Coordinates setting-out measurement (

# 15. RESECTION MEASUREMENT

• The "Resection measurement" is used to determine the instrument station coordinates by observing 2 or more known stations.



- SET C can calculate the instrument station coordinates by method of least squares by observing 2 to 5 known stations.
  - To calculate the instrument station coordinates;

- when measuring distances, observe at least 2 known stations. or
- when unable to measure distances, observe at least 3 known stations.
- However, the greater the number of known stations and the greater the number of measured distances, the more precise the results will be.
- The Z coordinate can be calculated by inputting the Z coordinate of at least 1 known station and measuring the distances of 2 or more points. (The Z coordinate cannot be determined using only angle measurement.) Before the resection measurement, input the instrument height.
  - **Note:** For the Resection measurement of highest accuracy, please adjust the collimation error beforehand.
    - See P.218 "Appendix 2: For Angle measurement of the highest accuracy, <Adjusting the collimation error by collimation program>".
    - To recall the known station's coordinates from coordinate data stored on the card, please refer to P.113.

• It is best to avoid a situation where the unknown station (instrument station) lies on the same circle as the known stations (in the case of 3 or more known stations).

Nullification of calculation will result. The figure below describes the better arrangement.



 Unknown station (Instrument station)
 Known station

6 E.A

Note: When calculating the instrument station coordinates by only measuring the angles of 3 known stations, if a station is on the same circle as the known stations, the calculated station coordinate will not be correct.



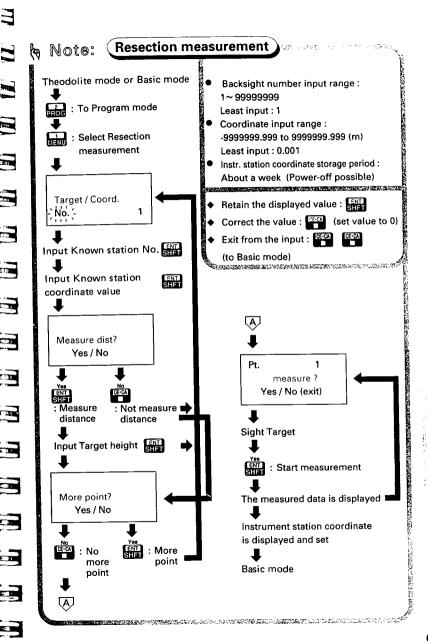
If this situation is expected, the following action is suggested.

- 1) If possible move the station to the near centre of the triangle or
- 2) Observe other known stations which are not on the circle or
- 3) Measure the distance of one of 3 stations along with the angles.



• If the angle between 2 known stations is narrow, the observing condition is not sufficient to calculate the instrument station coordinates. When the distances between the instrument station and the known stations are long, it is difficult to determine that the angles are narrow thereby avoiding the instrument station being on the same circle as the known stations.





 G. G. The instrument station coordinates will be determined from the following data:

Instrument height : 1.5m

Known Station A: Point number = 1 N = 2042.104, E = 1376.491, Z = 116.720. Measure angle and distance Target height is 1.5 m Known Station B: Point number = 2

- N = 1608.521, E = 2426.262, Z = 251.200.Measure angle
- Known Station C: Point number = 3 N = 862.988, E = 1554.186, Z = 101.240. Measure angle and distance Target height is 1.5 m





- 1. Resection
- 2. Correction
- 3. Pt. replace

 In Theodolite mode or Basic mode, press 2 and the second se

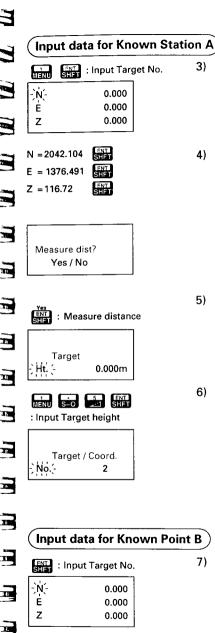
The display appears as at left, showing Program mode.

section")
oord.

2) Press .

The previously stored value +1 is displayed.

"No." flashes to prompt for the input of the point number.



 Input the coordinates for Known Station A.

N =	2042.104	ENT SHFT
Ε =	1376.491	<b>LENTI</b> Shft
Ζ=	116.72	ENY SHFT

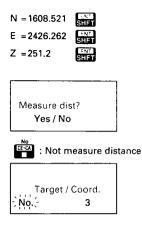
The display then asks whether to measure its distance or not.

5) Press

The display appears as at left. "Ht" flashes to prompt for the input of the target height. If measuring angle only, press

(The previously stored value +1 is displayed.)

7) The displayed value is retained, so simply press .
 The point number "2" is input, and "N" flashes to prompt for the input of the N coordinate.



8) Input the coordinates for Known Station B.

N =	1608.521	ENT SHFT
E =	2426.262	ENT SHFT
Ζ=	251.2	ENT

The display then asks whether to measure its distance or not.

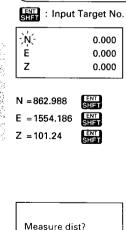
Press . 9)

> When the data for the second station has been input, "No." flashes to prompt for the input of the point number of the next known station.

> (The previously stored value +1 is displayed.)

If measuring distance, press

### Input data for Known Station C



Yes / No

10) The displayed value is retained, so simply press

> The point number "3" is input, and "N" flashes to prompt for the N coordinate.

11) Input the coordinates for Known Station C.

N =	862.988
-----	---------





E = 1554.186Z = 101.240



The display then asks whether to measure its distance or not.



12) Press [IT] .

The display appears as at left. "Ht" flashes to prompt for the input of the target height.

(The previously stored target height is displayed.)

If measuring angle only, press

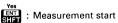
### 13) Press [1].

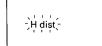
When the data for the third station has been input, if the conditions for calculating the instrument station coordinate have been satisfied, the display asks whether you want to observe any further stations. (Observation can be carried out up to 5 stations.)

14) Press 🖽 .

The display asks whether you want to observe the first station (Known Station A).

### **Observe Known Stations A to C**





1

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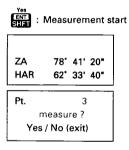
ΪĐ

15) Sight the centre of the reflecting prism of Known Point A correctly. Press ENT .

> The horizontal distance measurement is started.

H ZA HAR	820.570m 81° 59' 20" 0° 00' 00"
Pt.	2
m	easure ?
Yes	/ No (exit)

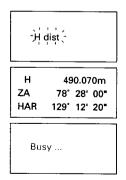
Sight Known Station B



Sight Known Station C



: Measurement start



When the measurement has been finished, the measured values are displayed, and the display asks whether you want to observe the second station (Known Station B).

16) Sight the centre of the reflecting prism of Known Station B correctly,

and press 🔝 .

The measurement is started. When the measurement has been finished, the measured values are displayed, and the display asks whether you want to observe the third station (Known Station C).

17) Sight the centre of the reflecting prism of Known Point C accurately,

and press SHFT .

The measurement is started. When the measurement has been finished, the measured values are displayed. "Busy" will appear on the display while the instrument station coordinates are being calculated.



77	N E		1234.000	1
	z		1.234	
784			<b>.</b>	-
	*N *E *Z	-	0.000 0.000 0.000	
	1.		ection	]
10	2. 3.		replace	
22				
			Signal off	
H				
		H ZA HAR	Time	out
31		Pt.	1 measure ?	
		Ye	es / No (exit)	

The instrument station coordinates are calculated and displayed.

This value is input as the instrument station coordinate. (Basic mode)

If, for some reason, the instrument station cannot be calculated, the display is as at left. After that the instrument returns to Program mode.

Nullification may be caused by poor layout of the known points, an error in the known station data input, or an inability to measure the distance or angle, etc.

Check the observation conditions and try the procedure again from Step 1).

Note: If "Signal off" is displayed, the return signal strength has become inadequate for measurement. Verify the target sighting. If within 2 minutes the return signal becomes sufficient, the measurement is restarted. After 2 minutes, the measurement is stopped automatically and the display appears as at left.

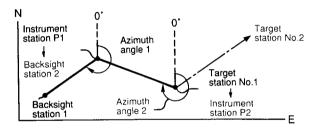
After that the display asks whether to observe the first station or not.

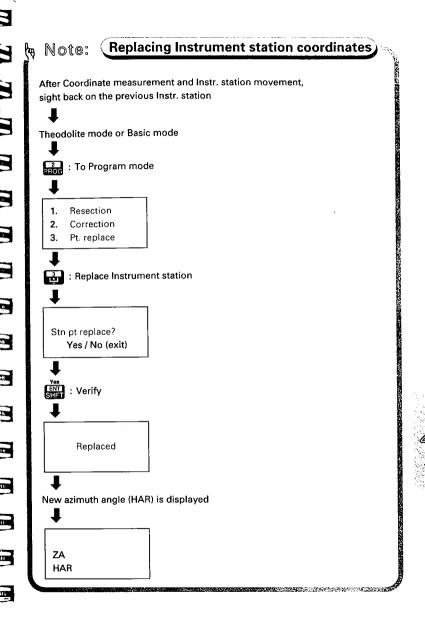
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### 16. TRAVERSE-STYLE COORDINATE MEASUREMENT

- The traverse-style coordinate measurement is used to measure the second survey station (No.2) coordinate after moving the instrument to the first survey station (No.1) and setting it up.
- The measured coordinate data is stored in the memory for up to about 1 week after power-off. Even after power-off it is possible to set new instrument station coordinates and the azimuth angle for the instrument by sighting back on the first instrument station and pressing a key on the SET C keyboard.





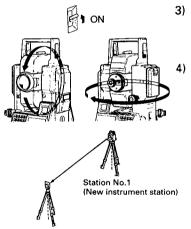
### After measuring Station 1, switch off and move the SET C





- Station No.1
- 1) After measuring the coordinates of Station No.1 (14.1 ~ 14.5), switch the SET C off.
- Move the instrument to Station No.1 and set it up over the survey point.

### Switch on and index V and H circles



- Switch the SET C on, and index the vertical and horizontal circles after the self-check.
- From Station No.1, sight back on the original instrument station P1.

### Previous instrument station P1

### From Theodolite mode or Basic mode to Program mode

### 2 PROG

- 1. Resection
- 2. Correction
- Pt. replace

### 5) Press 2.

The display appears as at left, showing Program mode.

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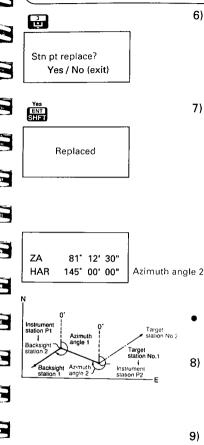
7

### Set the instrument station movement in SET C

Target

F

slation No 2



Press 🔜 . 6)

> The display appears as at left and asks whether the new station coordinates are to replace the previously stored ones.

7) Press [IT].

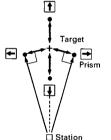
The display appears as at left after the coordinates of Instrument station P1 have been set as the new Backsight station 2, and the measured coordinates of Station No.1 have been set as the new instrument station P2

The instrument then calculates. The measured coordinates are displayed and the azimuth angle is set

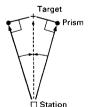
- To interrupt the movement, press 🕮 .
- Measure and input the instru-8) ment height of instrument station P2 and the target height of Station No.2. (Refer to P.57, 14.2)
- Sight the centre of the reflecting 9) prism of Station No.2 correctly.
- 10) Press 🔛 to go to coordinate measurement mode and start 3-Dimensional coordinate measurement.

# **17. OFFSET MEASUREMENT**

- The Offset measurement is used to measure the distance to point where it is not possible to set a reflecting prism directly, or where the reflecting prism cannot be sighted directly, in order to determine the angle.
- SET C can determine the distance and angle of the target point by setting the reflecting prism at a point (offset point) at a distance from the point to be measured (target point) and measuring the distance and angle of the offset point.
- There are two methods to determine the distance and angle of the target point.
  - The target point is determined by inputting the distance between the target point and the offset point.

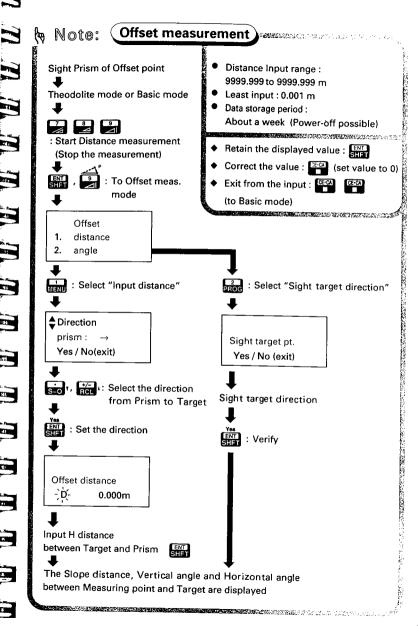


- When the offset point is positioned to the left or right of the target point, the offset point and target point should both be approximately 90°.
- When the offset point is in front of or behind the target point, the offset point should be on a line connecting the instrument station point and the target point.
- The target point is determined by sighting the direction of the target point.



The offset point should be positioned to the right or left of the target point.

To record the data on the card, please refer to P.113.



**4.0** 

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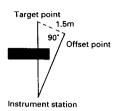
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- The positions of the target point and the offset point are shown at the left. In this case, determine the slope distance to the target point when the horizontal distance is 1.5m.
  - Note: The offset point should be positioned so that the line connecting the target point and offset line is at a 90° angle to the line connecting the instrument station and offset point.

### Sight the offset point and measure



: Starts the distance measurement



s	3.210m
ZA	
HAR	



ENT.

1.

2.

Offset

angle

distance

4

: Stop the measurement

To Offset Measurement mode

3)

 Set the reflecting prism at the offset point, sight the centre of it correctly, and in Theodolite mode or Basic mode,

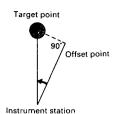
press either [7], [2], or [3]. After about 4.7 seconds (Fine measurement mode), the distance value, the vertical angle and the horizontal angle are displayed and stored in the instrument memory.

- For Repeat measurement mode, press 2 .
  - Press 🖭 and 🚔

The display appears as at left. The display asks you to select one of the following options:

- Input the horizontal distance between the target point and the offset point.
- 2. Sight the direction of the target point.

		17. OFFSET MEASUREMENT
Select "Input h	orizontal distan	ce")
Direction     prism : ↑     Yes / No(exit)	4)	Press . The display appears as at left and prompts to select the direction from target point to reflecting prism.
Select the offse	et point direction	
rccl₄ or s=o : "→"is displayed	5)	Press ∰, or , to display "→".
♦ Direction prism : → Yes / No(exit)		Note: → : Prism is right of target ← : Prism is left of target ↑ : Prism is behind target ↓ : Prism is in front of target
Offset distance		When $\rightarrow$ is displayed, press $\underbrace{\text{Withen}}_{\text{Withen}}$ . "D." flashes to prompt for the input of the horizontal distance between the target point and the offset point.
Input horizonta	I distance betwo	een target point and offset point )
		Input a horizontal distance of 1.5 metres and press
S 4.321n ZA HAR		The slope distance from the in- strument station to the target point and the vertical and hori- zontal angles are calculated and the results are displayed.
RCI. 🛃 : Display horizon	the •	To display the horizontal dis- tance, press 📆 🛃 .



- The positions of the search point and the offset point are shown at the left. In this case, determine the slope distance to the centre point of a telephone pole.
  - Note: The offset point should be positioned so that the line connecting the target point and offset line is at a 90° angle to the line connecting the instrument station and offset point.

### Sight the offset point and measure



: Starts the distance measurement



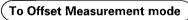
s	3.210m
ZA	
HAR	

 Set the reflecting prism at the offset point, sight the centre of it correctly, and in Theodolite mode or Basic mode press either 2,



After about 4.7 seconds (Fine measurement mode), the distance value, the vertical angle and the horizontal angle are displayed and stored in the instrument memory.

: Stop the measurement



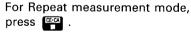


### Offset

- 1. distance
- 2. angle

2)

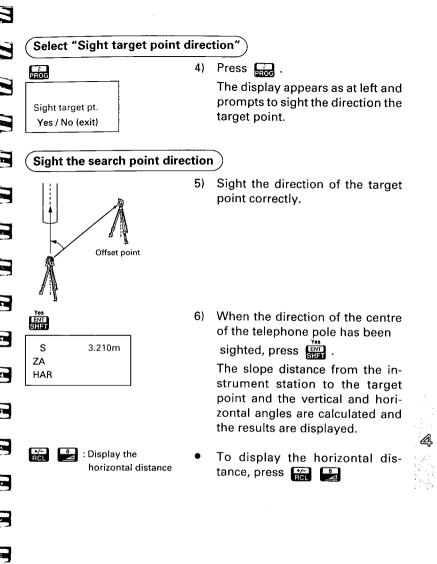
3)



Press 🔛 and 🖳

- The display appears as at left. The display prompts to select one of the following options:
- Input the horizontal distance between the target point and the offset point.
- Sight the direction of the target point.

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# **18. REM MEASUREMENT**

 When measuring the height of certain objects such as overhead power cables or bridge supports where the reflecting prism cannot usually be positioned, the Remote Elevation Measurement function can be used to calculate the height above the ground using a point directly above or below the object.

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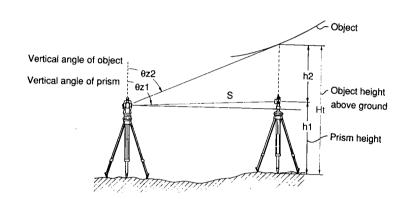
-

. 9 9

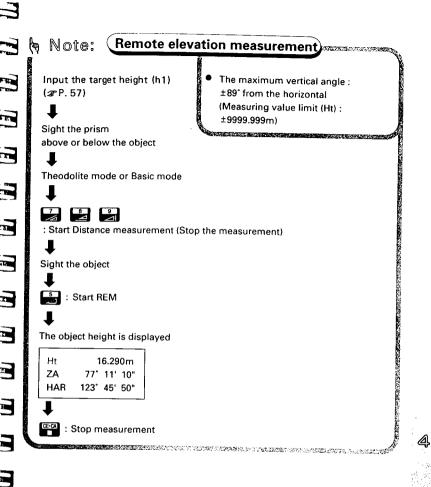
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 The height of the target is calculated using the following formulas. Ht = h1 + h2 h2 = Ssin0z1 x cot0z2 - Scos0z1

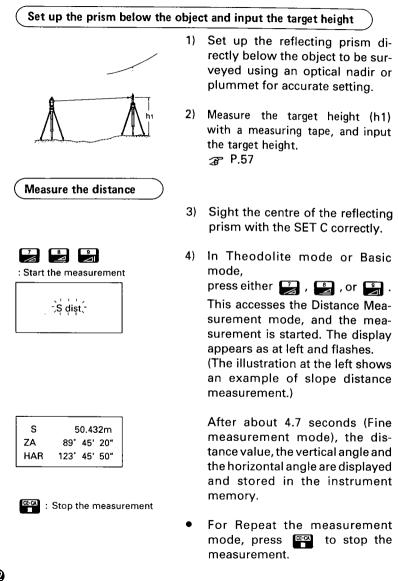


 The measured values are first displayed after 0.7 seconds and then every 0.5 seconds for all measurement modes.

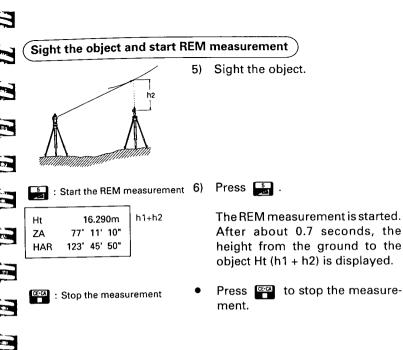


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### ອໍູ 🖉 🦲 🔹 Measure the height to a suspended cable



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- 1

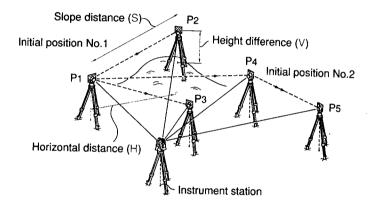
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# **19. MISSING LINE MEASUREMENT**

- The Missing line measurement is used to measure the slope distance, the horizontal distance, and the height difference between the starting position (P1) and any other points without moving the instrument itself.
- The SET C can measure the distances to many points continuously. It is also possible to change the starting position to that of the lastmeasured point. P.98



# 4 19.1 Measurement mode selection

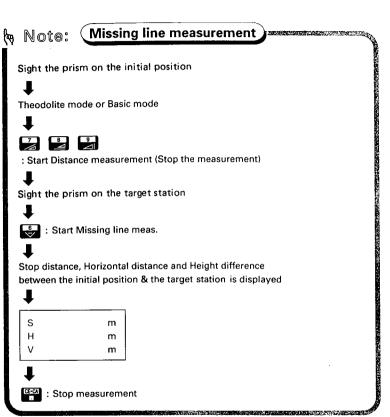
 Select the measurement mode from the following according to your required measurement.
 See P 42 #13.1 Measurement mode when the selection of the selec

See P.42 "13.1 Measurement mode selection" for key operation.

Measurement mode		Measurement time	Units
Fine meas.	Single	5.6 secs	
	Repeat	First 5.6 secs & every 3.3 secs	1mm
Coarse meas.	Single	2.9 secs	
	Repeat	First 2.9 secs & every 0.7 secs	
Tracking meas.		First 2.8 secs & every 0.7 secs	

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# 19.2 Measuring the distance between two or more points

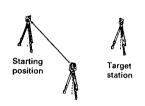




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- Measure the distances between the starting position and many points consecutively.

# Set up the prism on the starting position and start the distance measurement

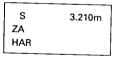
1)





: Starts the distance measurement





CE-CA : Stop the measurement

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the required number of target points, sight the centre of the reflecting prism on the starting position. In Theodolite mode or Basic mode press either 🙀 , 🛃 , or 🛃

Set up the reflecting prisms on

This accesses the Distance Measurement mode, and the distance measurement is started. The display appears as at left and flashes. (The illustration at the left shows an example of slope distance measurement.)

After 4.7 seconds (Fine measurement mode), the distance value, the vertical angle and the horizontal angle are displayed and stored in the instrument memory.

2) For Repeat the measurement mode, press and .

# Sight the prism on the target station and start the missing line measurement



Sight the centre of the reflecting prism on the target station No.1. If the prism constant and ppm correction for Target Station No.1 are different from those of the starting position, reset these values now.



7					
$\boldsymbol{n}$		Start the missin measurement	gline 4)		
	Mi	ssing line			
	S H V	20.757m 27.345m 1.012m	Slope distance Horizontal distan Height differ.		
	GE-CA : 5	Stop the measu	rement 5)		
21 21	Sight Tai	rget Station No.	.2		
	🗧 : Start the missing line 📍				

Press 🔩 .

4)

distance

This accesses the Distance Measurement mode and the Missing line measurement is started. The display appears as at left and flashes.

After about 5.6 seconds (Fine measurement mode), the slope distance, the Horizontal distance and the height difference are displayed.

- For Repeat the measurement 5) mode, press 🖾 to stop the measurement.
- After this measurement, to mea-٠ sure the distance between the starting position and Target station No.2 (or between the starting position and Target station No.3), sight the required reflecting prism and press 💭 to start the missing line measurement.

- × measurement





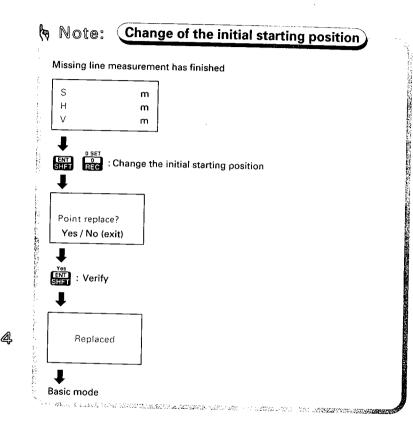




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# 19.3 Change of the starting position

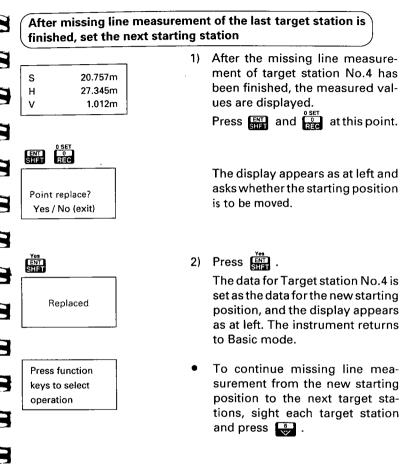
 The last measured target station can be changed to become the next starting position.



 G G Changing the last measured target station No.4, to become the next starting position

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# 20. SETTING-OUT MEASUREMENT

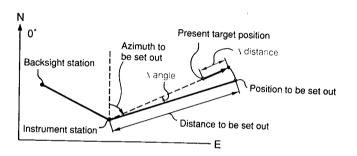
The Setting-out measurement is used to set out the required point.

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 In the SET C, the difference between the previously input data to the instrument (the setting-out data) and the measured value can be displayed by measuring the horizontal angle, distance or coordinates of the sighted point.

Displayed value = Difference between measured value and setting-out data

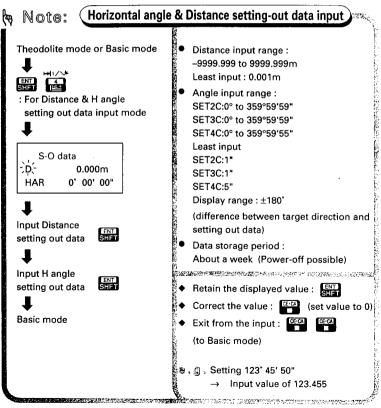


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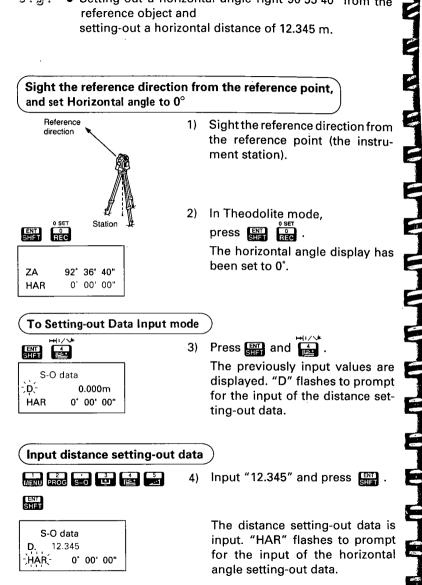
# 20.1 Horizontal angle and distance settingout measurement

- This measurement is used to set out the point from a certain direction (horizontal angle) and a certain distance away from a reference point (the instrument station).
- It is possible to set out a slope distance, horizontal distance, height difference or remote elevation value after inputting the required value.



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e.g. • Setting-out a horizontal angle right 90°55'40" from the reference object and setting-out a horizontal distance of 12.345 m.

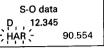


◬



### Input horizontal angle setting-out data

### ENT SHF T

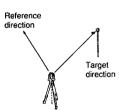


Input "90.554" and press . The horizontal angle setting-out data is input, and the display returns to Basic mode.

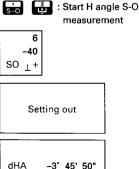
Press function keys to select operation

### Set the reflecting prism and start S-O measurement

5)



Set the reflecting prism at a position about 90°55′40" from the reference direction and about 12.345 metres from the reference point (the instrument point), and sight the reflecting prism.



94° 41' 30"

HAR

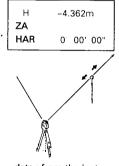
7) Press and and a.

The setting-out measurement is started, and the horizontal angle "dHA" from the setting-out data is displayed.



Start H angle S-O measurement





- data : from the instrument + data : towards the instrument

- Move the reflecting prism right or 8) left in the correct direction until the "dHA" becomes 0°00'00". Sighting the moving reflecting prism again changes the "dHA" without key operation.
- 9) When "dHA" has become 0°00'00",

press 🔚 and then 🖳 .

The setting-out measurement is started, and then the horizontal distance measurement is started.

-

After about 4.7 seconds (Fine measurement mode), the distance from the setting-out data to the reflecting prism is displayed.

10) Move the reflecting prism towards or away from the instrument until the horizontal distance becomes 0.000 m to determine the point.

If minus data is displayed, move the prism away from the instrument, and if plus data is displayed, move the prism towards the instrument.

When the Repeat measurement is selected, sighting the moving reflecting prism again changes the distance without key operation.

At Step 9), the following settingout measurements are possible: Slope distance, by pressing and 🔛

Height difference, by pressing sin and 🖳

REM, by pressing 🔚 and 📑 (after slope distance measurement).



# 20.2 Coordinates setting-out measurement



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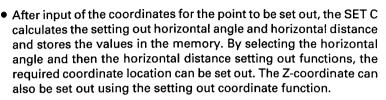
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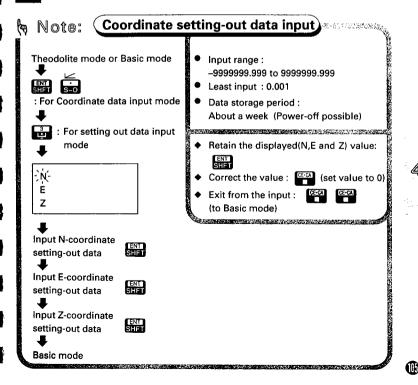
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This measurement is used to set out the point of a certain coordinate away from the reference point (the instrument station).





To recall the setting-out coordinate data from coordinate data stored on the card, please refer to P.113.

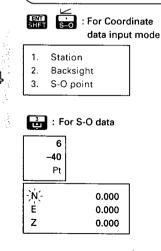


 In this case, the values are as follows: Instrument station coordinates: N = 20, E = 20, Z = 3 Backsight station coordinates : N = 10, E = 10, Z = 3 Setting out a point : N = 40, E = 30, Z = 4

- The following preparations must be completed before beginning measurement:
- 14.1 Measurement mode selection
- 14.2 Instrument height and target height input
- 14.3 Inputting instrument station and backsight station coordinates

- 14.4 Setting the azimuth angle
- To set out the Z coordinate, set the reflecting prism on a fixed height object, such as a pole.

# From Theodolite mode or Basic mode to Coordinate Setting-out Data Input mode



1) In Theodolite mode or Basic mode,

press and in . The display appears as at left, showing Coordinate data input mode.

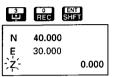
2) Press for S-O data input mode.

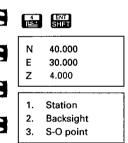
The previously stored values are displayed.

"N" flashes, to prompt for the input of the N coordinate settingout data.

### (Input the setting-out data

4	0 REC	ENT SHFT
N	40.000	0.000
가는지		
z		0.000





: To Basic mode

 Input "40" and press SHEET.

The N coordinate is input. "E" flashes to prompt for the input of the E coordinate setting-out data.

 Input "30" and press SHEP .

The E coordinate is input. "Z" flashes to prompt for the input of the Z coordinate setting-out data.

5) Input "4" and press

The Z coordinate is input, and the instrument returns to the Coordinate data input mode.

The setting-out horizontal distance and horizontal angle from the instrument station coordinates are calculated and the values are stored in the memory.

Note: Input the instrument station coordinates before inputting the setting-out data. Calculations may not be carried out correctly if the data is input in the reverse order.

.6) Press and to return to Basic mode.

### Set the prism and start H angle S-O measurement.

Sight the reflecting prism.



Setting out

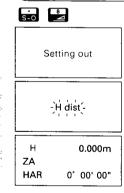
dHA	-3' 00' 00"
HAR	94°41'30"

- Set the reflecting prism in the appropriate position, and sight its centre.
- 8) Press 💼 and 급 .

The setting-out measurement is started, and the horizontal angle "dHA" from setting-out data to the sighted direction is displayed. R. M. M. M. M.

 Move the reflecting prism right or left until the "dHA" value becomes 0°00'00".

### ( Start H distance S-O measurement )



10) When "dHA" has become 0°00'00",

press 📻 and then 🔛 .

The setting-out measurement is started, and then the horizontal distance measurement is started.

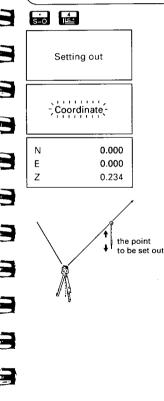
After about 4.7 seconds (Fine measurement mode), the distance from the setting-out data to the reflecting prism is displayed.



H 0.000m ZA HAR 0.00°.00"

- 11) Move the reflecting prism towards or away from the instrument on the sighting line to determine the point until the horizontal distance becomes 0.000 m.
- If the Repeat measurement mode has been selected, press to stop the measurement.

### Start coordinates S-O measurement, and determine the height



12) When "H" has become 0.000 m, press 🔜 and then 🔂 .

The setting-out measurement is started, and then the coordinate measurement is started.

After about 5.1 seconds (Fine measurement mode), the coordinates from the setting-out data to the reflecting prism are displayed.

Since the horizontal angle and horizontal distance have already been determined, the N and E coordinates are "0"

 Move the reflecting prism up or down until the Z coordinate becomes 0.000, and determine the height.

The tip of the pole is the point to be set out.

• If the Repeat measurement mode has been selected, press to stop the measurement. ∕∆

# LA MARANA MARANA MARANA

USING THE MEMORY CARD TO RECORD THE DATA

### **21.MEMORY CARD OPERATIONS**

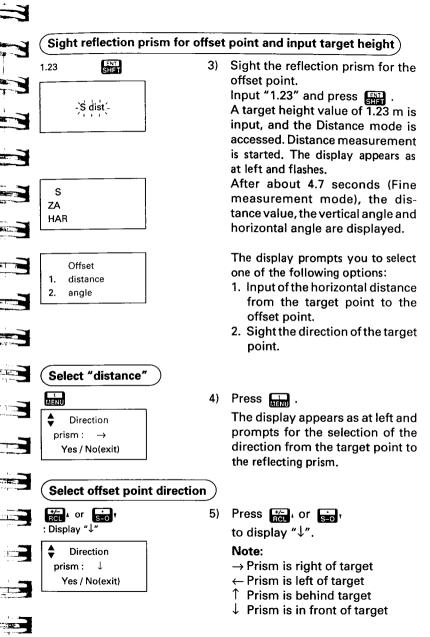
🔐 P.113

21.1 Card features

- 21.2 Inserting and formatting the card  $\oplus$
- 21.3 Changing the instrument options (
- 21.4 Job creating and selecting  $\oplus$
- 21.5 Instrument data recording @
- 21.6 Instrument station data recording @
- 21.7 Measured data recording @
- 21.8 Note recording
- 21.9 Feature code recording (
- 21.10 Feature code recalling to stack (
- 21.11 Feature code deleting (
- 21.12 Coordinate data recording (
- 21.13 Coordinate data recalling to Instrument @
- 21.14 Reviewing data stored on the card @
- 21.15 Protecting data stored on the card 🔀
- 21.16 Data stored on the card output to an external device (1)

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# The SET C can record data in the following formats on the cards.

### 1) Record Mode

 When measurement data is recorded, the target number, target code, target height, and atmospheric correction value can be stored, along with the following data.

< S, V, H >	$\rightarrow$	Slope distance, vertical angle, horizontal angle
< S, V, H (Offset) >	<b>→</b>	Prism direction and distance from target (only if input through offset measure- ment) Slope distance, vertical angle, horizontal angle
< V, H, Tilt >	$\rightarrow$	Vertical angle, horizontal angle, X direc- tion tilt angle, Y direction tilt angle
< N, E, Z >	$\rightarrow$	N coordinate (E coordinate), E coordinate (N coordinate), Z coordinate
< N, E, Z+S, V, H >	$\rightarrow$	N coordinate (E coordinate), E coordinate (N coordinate), Z coordinate, slope dis- tance, vertical angle, horizontal angle
< Note >	$\rightarrow$	Remark
< Station data >	$\rightarrow$	Date, instrument station number, code, instrument height, temperature, atmos- pheric pressure, curvature and refraction correction ON/OFF, prism constant cor- rection, automatic tilt angle correction ON/OFF, instrument station N coordinate (E coordinate), E coordinate (N coordi- nate) Z coordinate
< Instr ID >	$\rightarrow$	Instrument name Instrument number Software version number
Menu Mode		· · · · · · · · · · · · · · · · · · ·
< Code >	$\rightarrow$	Feature code, file name
< Card>→ <job file=""></job>	<b>→</b>	North coordinate (E coordinate), E coor- dinate (N coordinate), Z coordinate, point number, feature code

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# • Precautions when using the card

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The lifetime of the card battery is approximately 2 years, but if the card is used or stored at high temperatures, more battery power is used, thus shortening the life of the battery.

### • Replacing the card battery

If the battery becomes low, an error message like that shown below will be displayed. Replace the battery according to the following procedure.

Battery type: Sony CR2016 lithium battery or a battery of similar quality.

Note: When the battery has been replaced, all data on the card is cleared.

If the data on the card is necessary data, be sure to transfer it to a personal computer before replacing the card battery.





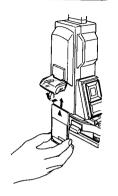
 Using a Phillips screwdriver, loosen the 4 screws on the back of the card, and remove the cover.

If the cover cannot be removed from the card itself, using a very thin flat-bladed screwdriver with a narrow tip, take off the cover where it is marked with  $\blacktriangle$ .

- Remove the used battery and fit a new one between the electrode springs, with the + side facing upwards. Use pliers made of a non-conductive material (plastic, etc.) when handling the battery.
- 3) Replace the cover and tighten that 4 screws as before.
- 4) Format the card referring to P.116, "21.2 Inserting and formatting the card". The message "Card error" will appear briefly before the message "Format end", however, the card will have been formatted and there is no problem.

# 21.2 Inserting and formatting the card





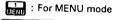
 Lift up the SET C card cover ④ and carefully insert the card. The card should be inserted with the arrow up and the printed side out.

Close the card cover.

### Formatting the card

 To use a new card, or to clear all of the data stored on a card, it must be formatted.

Note: If a card has been used and the stored data is to be retained, DO NOT REFORMAT THE CARD.



- 1. Config
- 2. Card
- 3. Code
- Р

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: Select "Card" setting

Card Job / file Yes / No (exit)  In Theodolite mode or Basic mode, press .

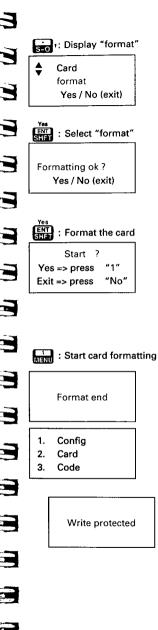
The display appears as at left, showing Menu mode.

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2) Press 2.

The display appears as at left, showing Card setting menu.

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- Press in .
   The display prompts for the selection of the card formatting.
- 4) Press <sup>Yes</sup> The display prompts for the formatting of the card.
- Press (FIT).
   The display asks whether you want to start formatting the card or not.
- Press .
   When the formatting has been completed, the display appears as at left, and the instrument returns to Menu mode.

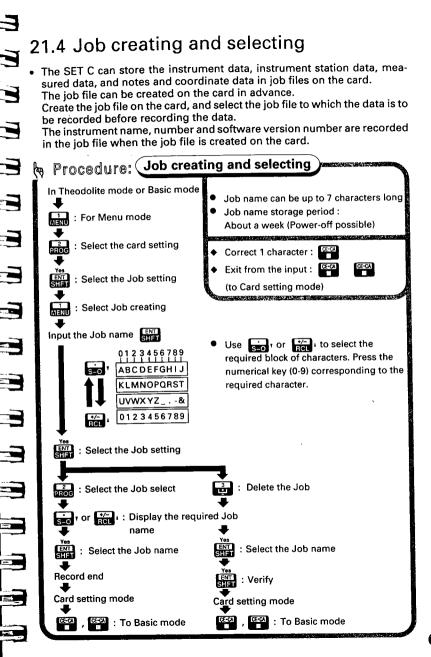
 If the display appears as at left, the data stored on the card is protected from erasure or overwrite by the write protect function.
 See P.125, "21.15 Protecting data stored on the card", and cancel the Write Protect function.

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# 21.3 Changing the instrument options

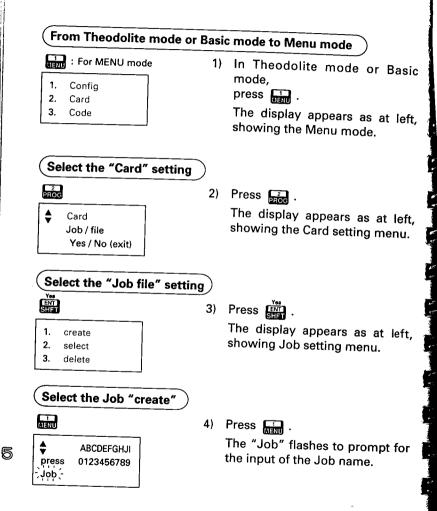
- Confirm that this parameter is set according to the data recording conditions.
- To confirm or change the parameter options, see P.201, "24. CHANGING INSTRUMENT PARAMETERS".

No.	Pa	Parameter		
2	Recording	1. Send data to	Card/Out	
		2. Set code	Set/Skip	
		3. Set target ht	Set/Skip	

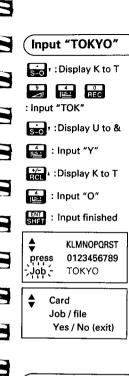


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 Create Job file "TOKYO" and record data in Job file ê.g. "OSAKA" (Select Job file).



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- 5) Press , to display "K ~ T".
- 6) Press 📴 , 💼 , 🚉 to input "TOK".
- 7) Press , to display "U ~ &".
- Press 🛃 to input "Y". 8)
- 9) Press **H** to display "K ~ T".
- 10) Press 🔜 to input "O".
- 11) Press ENT .

When the Job file has been created, the display returns to Card setting menu.

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Yea ENT SHIFT	12) Press Start .
<ol> <li>create</li> <li>select</li> <li>delete</li> </ol>	The display appears as at left, showing Job setting menu.

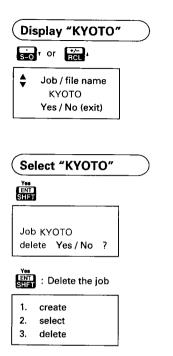
200	14) Press PROG
Job select TOKYO Yes / No (exit)	The display prompts for the sele tion of the Job files.
Display "OSAKA"	15) Press 💼 or 👬
; Job select OSAKA Yes / No (exit)	to display "OSAKA"
Card Job / file Yes / No (exit)	16) Press 🔛 . The Job file "OSAKA" is select and the display returns to the ca setting menu.
	• Press 🖼 ன to return to Bas
: To Basic mode	mode.

## $\circledast, \complement, \bullet$ To delete the Job file "KYOTO" from the card

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З

1. Config 2. Card 3. Code	1)	In Theodolite mode or Bas mode, press . The display appears as at le showing Menu mode.
Select the "Card" setting acce Card Job / file Yes / No (exit)	2)	Press The display appears as at le showing Card setting menu.
Select the "Job/file" sett Yes State 1. create 2. select 3. delete	ting 3)	Press 🔛 . The display appears as at le showing Job setting menu.
Select the file "delete" ↓ Job / file name OSAKA Yes / No (exit)	) 4)	Press 📑 . The display prompts for the sele tion of the file name to be delete



Press son or for to display "KYOTO".



The job "KYOTO" is selected and the display asks whether this Job is deleted or not. 2 F - 2 F

7) Press

"KYOTO" is deleted from the card, and the display returns to Job setting menu.

# 21.5 Instrument data recording

- With the SET C, the following items can be recorded on the card as instrument data:
  - Instrument name
  - Instrument number
  - Software version number

	<ol> <li>In Theodolite mode or Basic mode,</li> </ol>
Card ready Job KYOTO 64384byte free ♦ Select S,V,H Yes / No (exit)	press press . The selected job file name and the available space for data recording are displayed. A new card has 64,384 available bytes (approximately 1000 mea- sured data points in S, V, H for- mat). After that, the display shows Record mode. And the display prompts for selection of the data format.
<ol> <li>Job create</li> <li>select</li> <li>delete</li> </ol>	<ul> <li>When there is no Job file on the card, the display returns to Job setting menu. Create a Job file (seeing P.120 "21.4 from 4)"). Af- ter that, the display changes to Record mode.</li> </ul>
No card	<ul> <li>"No card " means that the card is not correctly mounted in the SET</li> </ul>

10 seconds. After 10 seconds, the message "Card error" appears and the display returns to Basic mode.

C. Insert the card correctly within

Card error

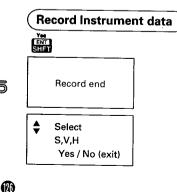
Card is full





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Select Instr ID Yes / No (exit)



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If "Card error" is displayed after pressing **F**, there is some problem with the card. Insert the card correctly.

If "Card error" is displayed after inserting the card correctly, please contact your Sokkia agent.

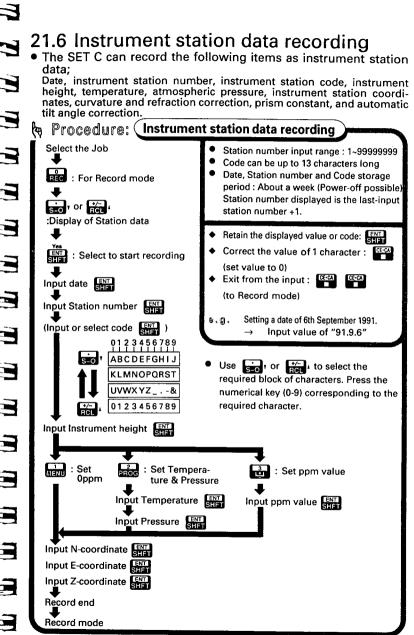
- When the card becomes full of data, "Card is full" is displayed.
- When the card battery is running low, "Card bat low" is displayed. Please change the battery. a P.115

Or replace with a new card.

2) Press , or to display "Instr ID".

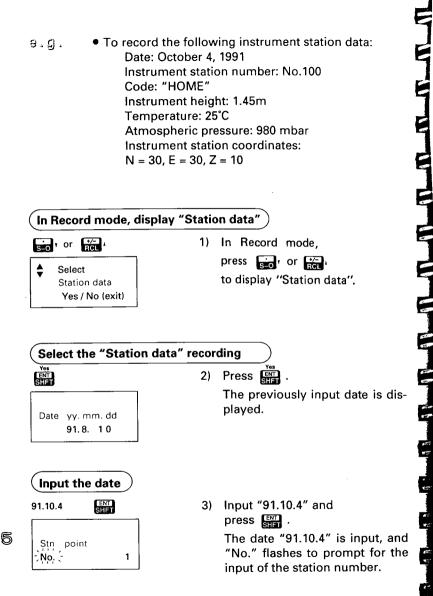
3) Press .

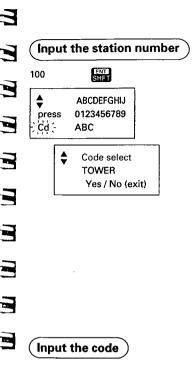
> When recording of the instrument data has been finished, the message "Record end" is displayed, and the display returns to the Record mode.



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 To record the following instrument station data: 9.0. Date: October 4, 1991 Instrument station number: No.100 Code: "HOME" Instrument height: 1.45m Temperature: 25°C Atmospheric pressure: 980 mbar Instrument station coordinates: N = 30, E = 30, Z = 10





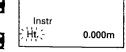
CE-CA : Single-character delete

: input "H"

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- sor: Display K to T
- 📩 : input "O"
- 2 : Input "M"
- Hele I: Display A to J
- 🛓 :Input "E"
- ENT : Input finished



4) Input "100" and press SHET .

"100" is input for the station number. "Cd" flashes to prompt for the input of the instrument station code.

If the codes are stored in a stack, the display prompts for the selection of the code. After a code is selected, the code can be edited.

- To input the code directly, press 
   <sup>№</sup>
   .
- Note: If the parameter of the code setting is set to Non-input, this procedure is omitted. Instead, go directly to step 6).
- 5) Input the code.

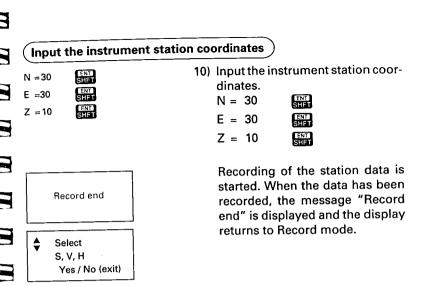
Press and to delete one character to the left.

- Press 🛃 to input "H".
- Press **stor** to display "K ~ T".
- Press 🛃 to input "0".
- Press Prog to input "M".
- Press Handle to display "A ~ J".
- Press 🛃 to input "E".
- Press ENT .

The code "HOME" is input, and "Ht" flashes to prompt for the input of the instrument height.

### Input the instrument height 1.45 ENT Input "1.45" and press 6) An instrument height value of 1. 0 set "1.45" is input, and the display 2 Temp & Press turns to the ppm setting mode. 3. ppm value Select the temperature and pressure input) Press 2. 2 PROG 7) The previously stored values are displayed. ÷.;-°C 15 "T" flashes to prompt for the in-Ρ. 1013 mbar put of the temperature. Input the temperature and pressure Input "25" and press STA . PROG 8) A temperature 25°C is input. "P" flashes to prompt for the in-25 °C Т. put of the pressure. Р. 1013 mbar Input "980" and press 9) A pressure "980 mbar" is input. -`N'-"N" flashes to prompt for the in-E put of instrument station coordi-Z nates.

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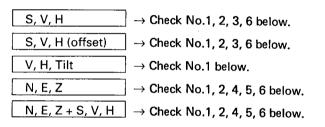
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# 21.7 Measured data recording

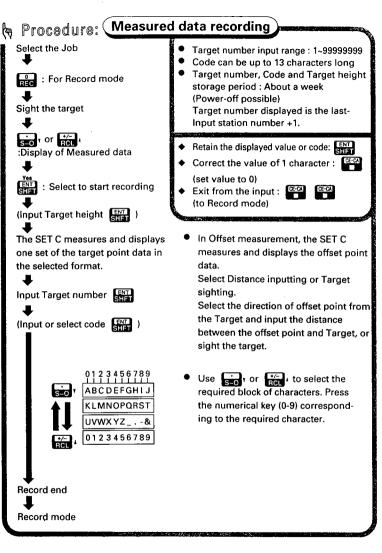
- The SET C can record the following items as measured data: Target number, target code, target height, atmospheric correction measured data.
- The distance is measured in accordance with the selected distance measurement mode, but the measurement is done only once (single measurement).

### – Checkl before recording the data: —



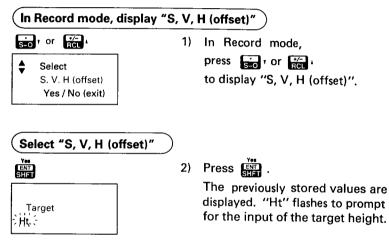
1	The instrument parameters have been set.	_	
		æ	P.29
2.	The correct prism constant has been set.	æ	P.45
3	I be instrument station date has been newfares al		
		<i>ቼ</i> የ	P.127
	or else atmospheric correction has been set.	P	P.48
	The instrument station data has been performed		
т.	the instrument station data has been performed	ℬ F	P.127
	or else the instrument height, atmospheric correction	~~	D E7
	and instrument station coordinates have been set.		
		- 4	8,60
5.	The azimuth angle has been set.		P.65
	The centre of the reflecting prism is being		
		Æ	P.52
	sighted and the return signal is adequate for	_	
	measurement.		





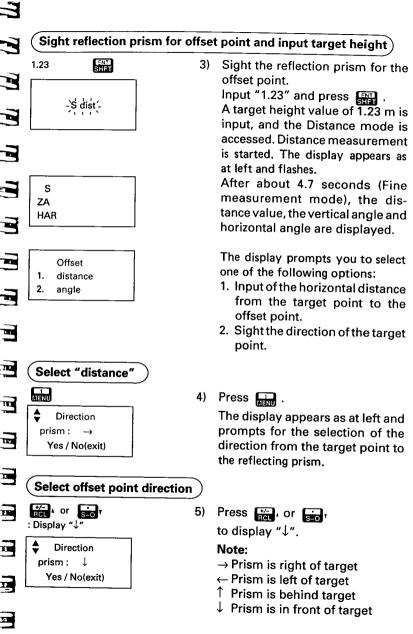
 To record the following offset measurement data Target number : No. 2001 Code : "TREE1". Target height : 1.23 m Horizontal distance from target point to offset point : 1.8 m

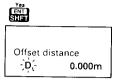
Direction of prism from target : Front



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Note: If the target height setting parameter is set to "Non-input", this procedure is omitted. Instead, go directly to step 4). 



When "\" appears, press

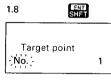
"D" flashes to prompt for the input of the horizontal distance between the target point and offset point.

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- <u>6</u>

Input the horizontal distance from the target point to the offset point



Input horizontal distance of "1.8" 6) and press [].

### Input the target point number

2001

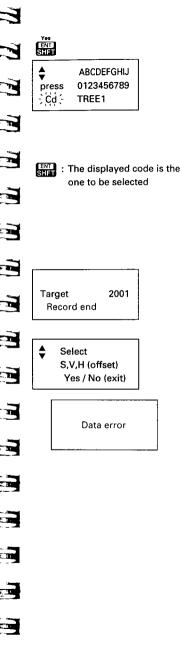


7) Input a target number of "2001" and press

A target number value of "2001" is input. If the codes have been stored in a stack, the first code input is displayed, and the display prompts the selection of the code.

- Note: If the parameter of the code setting is set to "Non-input", this procedure is omitted.
- Set the code : Display "TREE1" Code select TREE 1 Yes / No(exit)
- 8) Press Fin or Fin to display "TREE1"

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When "TREE1" is displayed, press [ENT].

- If the required code is not among the displayed codes, press
   "Cd" flashes to prompt for the input of the code.
- 9) If the displayed code is the required one, press .
   To change the displayed code, press to delete the characters one at a time. Input the code required. Then press .

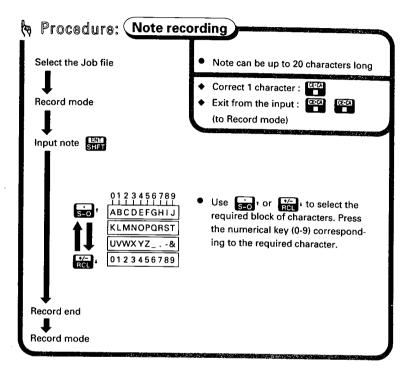
When the code has been input, the target number is displayed, and the recording is finished.

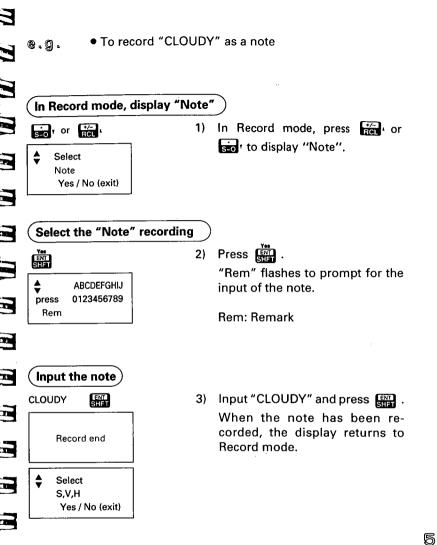
The display then returns to the Record mode.

Note: If the display returns to Record mode following a display like that at the left, there is an error in the measurement. Try levelling the instrument again, or sight the reflecting prism once again and start over from step1).

### 21.8 Note recording

• The SET C can record remarks as notes.







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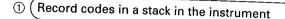
# -

# 21.9 Feature code recording

 The SET C can record the feature codes in the instrument and on a card in advance.

The feature code is input with recording instrument data and instrument station data.

 The procedure of code file recording to a card and recalling from the card is as follows:



₽ 21.9

If codes have been stored in a stack, the codes in that stack are automatically displayed whenever a new code is set, and the display prompts for the selection of the code. When creating a new file on the card, any codes currently recorded in the stack should be deleted, and then the new codes should be recorded in the stack.

(Record codes in the stack on a card)

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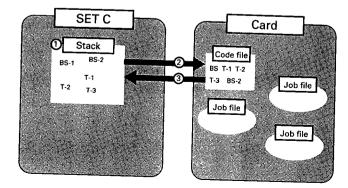
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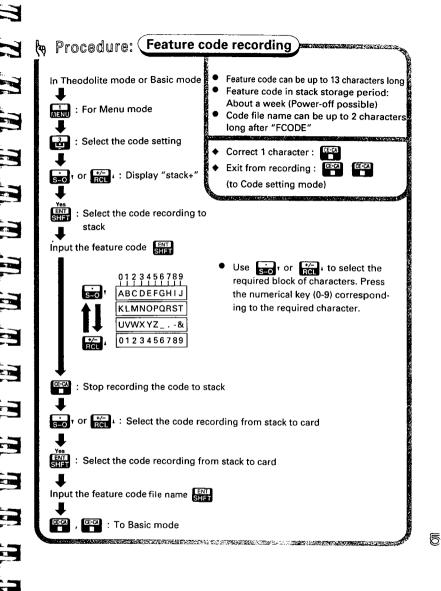
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 ${\textcircled{3}}\left( { ext{Recall the codes from the card to the stack in the instrument} 
ight.$ 

### ☞ 21.10

The newly recalled codes are displayed when a new code is set and the display prompts for the selection of the code.

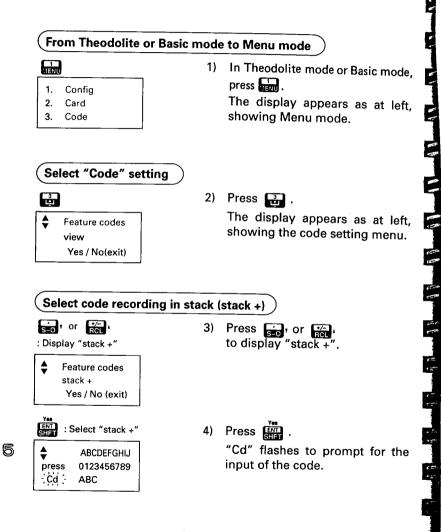




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S. S. • To record the codes "SCHOOL" and "FACTORY" in a stack, and then to record them on a card under the file name "FCODE-1".



Input the code ENT SCHOOL ABCDEFGHIJ 0123456789 press Cd ( Stack is full CE-CA : Input is finished \$ Feature codes view Ð. Yes / No (exit)

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- Input "SCHOOL" and press . The code has been recorded. "Cd" flashes again to prompt for the input of the next code.
- Note: If the message "Stack is full" is displayed, no more codes can be recorded in that stack. Press to stop inputting the codes and record the codes on the card.
- Note: 140 characters can be recorded in stack. For example, the number of

codes composed of 6 characters is 20.

140+ {6(characters)+1(space)}=20

6) Press to stop recording the data to the stack.

The display returns to the code setting menu.

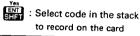
- After that, when instrument station data and measured data are to be recorded, the codes stored in the stack will be displayed to select the required one.
- Go back to step 5) and input "FACTORY".

Select code in the stack to be recorded on the card (card <= stack)

SEC ' OF RCL '

: Display "card <= stack"

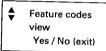
Feature codes card <= stack Yes / No (exit)



ABCDEFGHIJ press 0123456789 FCODE

### Input the file name

-1 ENT



7) Press , or to display "card <= stack".

8) Press ENT

"FCODE" is displayed to prompt for the input 2 characters as the file name for recording the codes to the card.

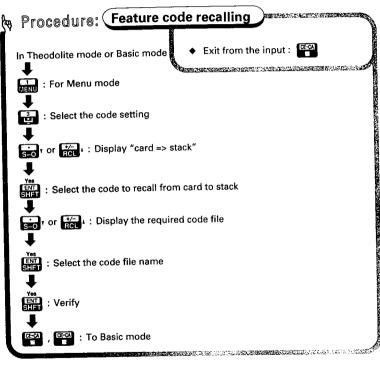
- The codes in the stack have been recorded on the card.
- Press and the Basic mode.

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# 21.10 Feature code recalling to stack

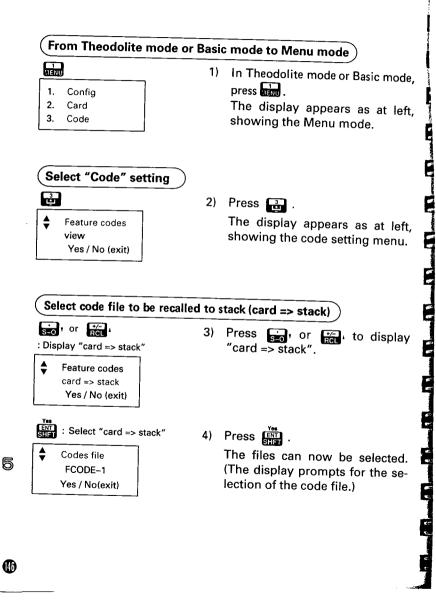
• The SET C can recall a code file stored on the card and input it to the stack in the instrument.

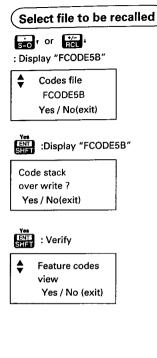
After that, you can select the required code from the recalled code file in the stack when the instrument station data and measured data are recorded.



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 To recall the code file named "FCODE5B", which is a. U. stored on a card, to a stack





CE-CA CE-CA : To Basic mode

5) Press , or to display "FCODE5B".

Press ENT . 6)

The display asks whether the codes currently stored in the stack are cleared and whether to recall the codes in the "FCODE5B" file.

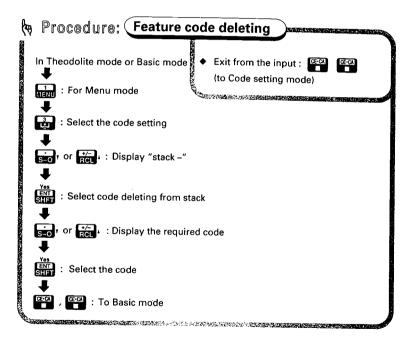
7) Press [N]

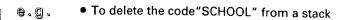
The codes in "FCODE5B" are recalled to the stack, and the display returns to the card setting menu.

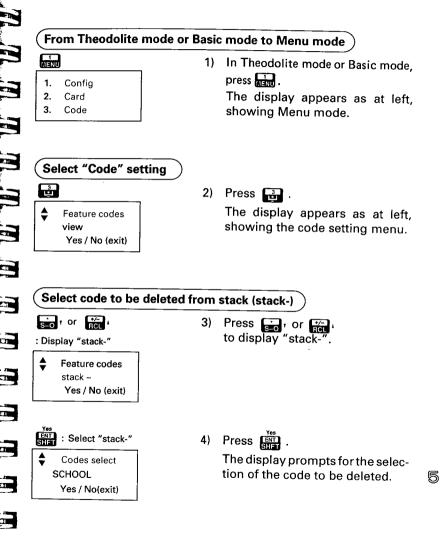
- After that, when instrument station data and measured data are to be recorded, the codes stored in the stack will be displayed to select the required code.
- Press CECA CECA to return to Basic mode.
- Note: If the message "File not exists" is displayed, no files storing codes are stored on the card.

# 21.11 Feature code deleting

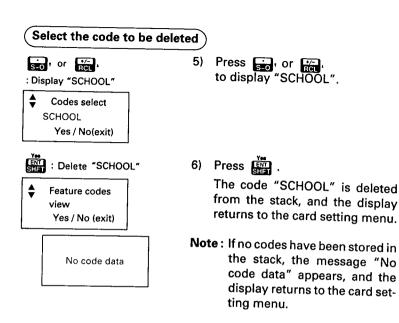
- The SET C can delete a code file stored on a card or a code stored in a stack. If there is no code in the stack, the code can be input directly when the instrument station data and measured data are recorded.
- To delete code files from a card, please refer to P.115, "21.4 Job creating and selecting", and specify the name of the file to be deleted.











Press and to return to the Basic mode.

# 21.12 Coordinate data recording

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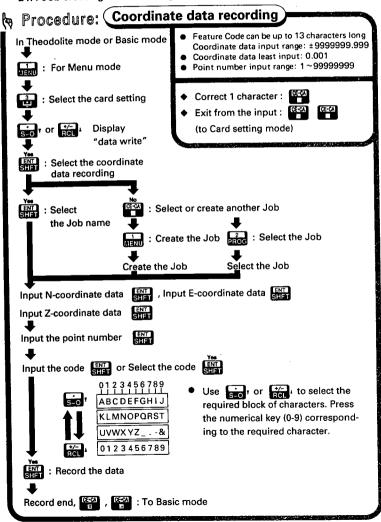
3

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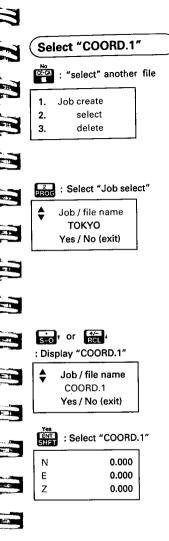
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- The SET C can record coordinate data on cards. The coordinate data is recorded in a Job file, and can be used as instrument station coordinates, backsight station coordinates, known point coordinates, and setting-out coordinates.
- To delete a file with coordinate data in it from a card, please refer to P.119, "21.4 Job creating and selecting".



- -E E -53 -54-4375-4221
- To record the coordinate data. ð.g. Point number: 201 N-coordinate: 35 E-coordinate: 67 Z-coordinate: 48 Code: BS-4 Job file: COORD.1 From Theodolite mode or Basic mode to Menu mode 1) In Theodolite mode or Basic mode, press have. 1. Config The display appears as at left, 2. Card showing the Menu mode. 3. Code Select "Card" setting 2 2800 Press 2) The display appears as at left, Card showing the card setting menu. Job / file Yes / No (exit) Select coordinate data recording (data write) 3) Press or in the second to display "data write". : Display "data write" Card data write Yes / No (exit) Select "data write" 4) Press ENT . The last selected file name is displayed. The display asks whether Job OSAKA the coordinate data is to be re-Yes / No (select) corded in the job file or in another iob file.

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 Press to select or create another job file.

The display returns to the job setting menu.

- To record the data in the displayed Job file, press in then proceed to step 8).
- 6) Press 2.

The display prompts for the selection of the file name.

 To create a new Job file, press .

> The display prompts for the input of the Job file name. Input the Job file name and press **ST** to advance to step 9).

 Press sor or RCL to display "COORD.1".

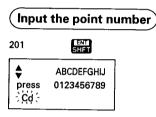
Press (\*\*\*) .
 "N" flashes to prompt for the input of the N coordinate data.





E

# Input the coordinate value N = 35 E = 67 SHET Z = 48 Point No. : 1000



Set the code			
BS-4	LEXU SHFT		
Data OK Yes / No	?		

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9) Input coordinate values.

N =	35	ENU SHFT
Ε =	67	SHFT
Ζ=	48	ENI SHFT

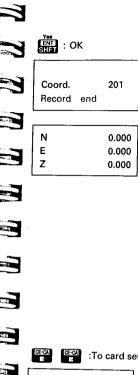
The previously stored values are displayed. "No." flashes to prompt for the input of the point number.

10) Input the point number "201" and press

"Cd" flashes to prompt for the input of the code.

- Note: If the code is stored in a stack, the display prompts for the selection of the code. After the code is selected, the display appears as at left.
- 11) Input the code "BS-4" and press ENT .

The display asks whether the coordinate data is recorded on the card or not.



Card Job/file Yes / No (exit)

### 12) Press

When the recording is confirmed, the point number is displayed, and the recording is finished.

The display then returns to step 8), so that the next coordinate data can be input.

- To record the next coordinate data, go back to step 9) and input the data.
- Note: Although it is possible to input up to about 1000 data to the 64Kbyte card, the SET C is only able to recall up to the first recorded 600 coordinate data. Therefore, when recording more than 600 coordinate data, input the additional point data into another job file.

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The display returns to the card setting menu.

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Press and to return to Basic mode.









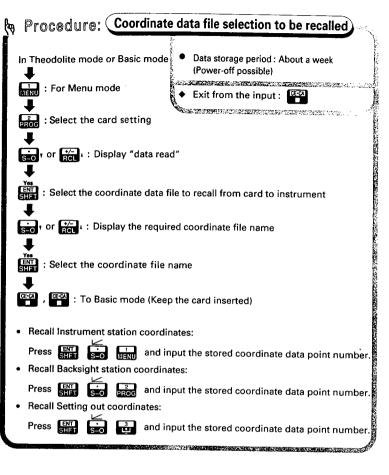
### 21.13 Coordinate data recalling to Instrument

- The SETC can recall and use the coordinate data stored on the card.
- Recalled coordinate data can be used as follows:
  - Instrument station coordinates
  - Backsight station coordinates
  - Known point coordinates for Resection measurement
  - Setting-out coordinates
  - **Note** : The SET C is only able to recall up to the first recorded 600 coordinate data from a job file. Therefore, when recording more than 600 coordinate data, input the additional point data into another job file.
- Before recalling the data into the instrument station, the following parameter should be set to "Card".

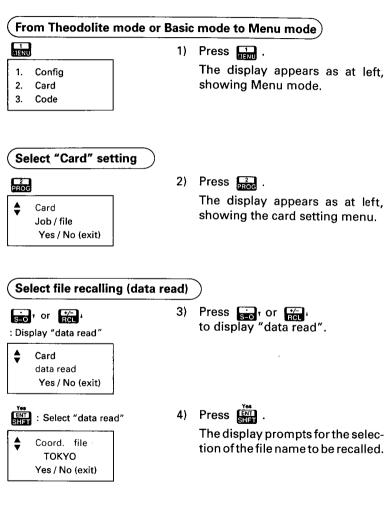
To change the parameter, please refer to P.197, "24. CHANGING INSTRUMENT PARAMETERS".

No. Parameter		Options	
1	Coordinate data from	Keyboard / Card	

ve.



S.
 To select or change the file name "COORD.5" to be recalled from the card into the instrument.

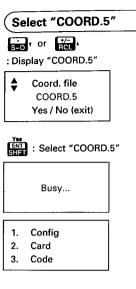


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Data table over write ? Yes / No (exit)

5) Press sor or the interview of the second second

Press in .
 While searching for the specified file name, the display appears as at left.

When the file has been selected, the display returns to Menu mode.

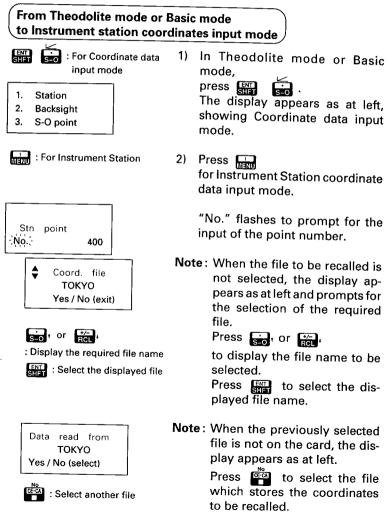
- Press and to return to Basic mode.
- Note: Keep the card inserted until recalling the instrument station coordinates, the backsight coordinates, or the setting out coordinates is completed.
- If this file is different from the previously selected file, the display asks whether the previous selection is cancelled and this file is to be selected or not.

Pressing , the file name searching is started.

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Note: If there is no data in the selected file, the message "No coord. data" is displayed, and the display returns to Menu mode.  To recall the coordinate data for Point No.401 from the selected file as the instrument station coordinates



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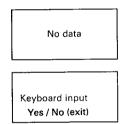




### Input the point number ENI SHFT 401 98.765 N Е 43.210 z 1.456 98.765 λN 43.210 Ε

Z

1.456



CE-CA : To Basic mode

3) Input the point number "401" and press ENT .

> The coordinate data for 401 is displayed and is input as the instrument station coordinates.

Note: If more than one stored coordinate data record has the same point number, the display flashes to prompt for the selection of the required coordinate data.

Press , or in to display the coordinates to be recalled. And then press End to recall the displayed coordinates.

Note: When the coordinate data is not found, the display appears as at left and asks whether you will input the coordinate data from keyboard or input the point number again.

> Press R to input the Instrument station coordinates from keyboard.

> Press CE-CA to input the point number again.

Press I to return to Basic mode.

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# e.g. Input Known station coordinates for Resection measurement by recalling the coordinate data from the cards

• To recall the coordinate data for the following point number from the selected file as the known station coordinates for Resection measurement:

Known station A: Point No.=501, Measure angle & distance, Target height is 1.5m

Known station B: Point No.=503, Measure angle

Known station C: Point No.=507, Measure angle & distance, Target height is 1.5m

### From Theodolite mode or Basic mode to Program mode

### 2 PROG

- 1. Resection
- 2. Correction
- 3. Pt. replace

 In Theodolite mode or Basic mode,

press 2

The display appears as at left, showing Program mode.

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### Select Resection measurement

MENU

Targe	t / Coord.
- No	400

2) Press .

"No." flashes to prompt for the input of the point number.

Input the data of Known station A

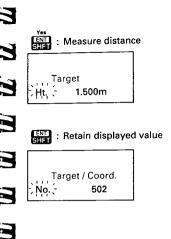
5

501 ENT SHIFT

> Measure dist ? **Yes / N**o

Input the point number "501" and press III .

The display asks whether to measure the distance or not.



4) Press Stat

The previously stored target height is displayed.

"Ht." flashes to prompt for the input of the target height.

5) Press SHET .

When the data for the first station has been input, "No." flashes to prompt for the input of the point number of the next known station. (The previously stored value +1 is displayed.)



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### Input the data of Known station B 03 ENT 6) Input the point number "503" and

- 503 ENT SHFT Measure dist ? Yes / No
- 2
- CE-CA : Distance not measured
- Target / Coord.

7) Press

press ENT .

When the data for the second station has been input, "No." flashes to prompt for the input of the point number of the next known station. (The previously stored value +1 is displayed.)

The display asks whether to mea-

sure the distance or not.

### Input the data of Known station C

507

Measure dist ? Yes / No

FNT



ENT SHET : Retain displayed value

More point ? Yes / No

: No more station Pt. 501 measure ? Yes / No (exit)

 Input the point number "507" and press ENT.

> The display asks whether to measure the distance or not.

9) Press

The previously stored target height is displayed.

"Ht." flashes to prompt for the input of the target height.

### 10) Press ENT .

When the data for the third station has been input, "No." flashes to prompt for the input of the point number of the next known station. (The previously stored value +1 is displayed.)

### 11) Press 🕮

The display asks whether you want to observe the first station (Known station A) or not.

See P.77 from 15) to continue the resection measurement.



### <Input Coordinate setting-out data by recalling the coordinate data from the card>

- To recall the coordinate data for Point No. 701 from the selected file as the setting-out coordinate data
- The following preparations must be completed before beginning measurement:
  - 14.1 Measurement mode selection 2 P.56
  - 14.2 Instrument height and Target height input ar P.57
  - 14.3 Instrument station coordinates and Backsight station coordinates input
  - 14.4 Setting the azimuth angle from the are P.65 instrument and backsight station coordinates

# From Theodolite mode or Basic mode to Coordinate setting-out data input



1.

2.

3.

Station

Backsight

S-O point

- For Coordinate data 1) input mode
- In Theodolite mode or Basic mode,



The display appears as at left, showing Coordinate data input mode.

 Press for Setting-out data input mode.

"No." flashes to prompt for the input of the point number.

### Input the point number

: For S-O data input mode

- 701
   Image: Constraint of the second sec
- Input the point number "701" and press (SHF).

The coordinate data for 701 is displayed and is input as the instrument station coordinates.

 See P.103 from 5) to continue the coordinate setting-out measurement.

# 21.14 Reviewing data stored on the card

- The SET C can display data recorded on the cards and codes stored in a stack.
- The data in a Job file can be displayed using the Recall mode. The feature codes in a stack can be displayed using Menu mode.
- Data in Job files is displayed in the format shown below.

### < Instr ID >

Instr ID	
SET C	Instr name
No. 88132	Instr No.

### < S, V, H > / < S, V, H (Offset) > (angle)

🗣 Pt.	1012
Code	TREE. 100
Ht	1.300 m
ppm	13
S	8.472 m
ZA	96' 48' 30"
HAR	244° 57' 55'

Target station number Code (If no code, "?" is displayed) Target height Atmospheric correction Slope distance Vertical angle Horizontal angle

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# < Station data >

Station data	
Date 92.1.1	Date
Stn 7000	Instrument station number
Code STATION. 1	Code (If no code, "?" is displayed)
Ht 1.500 m	Instrument height
Temp 25°C	Temperature (If 0 ppm or a ppm value has been input directly, "?" is displayed)
Press 1000 mbar	Pressure (If 0 ppm or a ppm value has been input directly, "?" is displayed)
C&R No	Curvature and refraction correction ON/OFF
PC –40mm	Prism constant correction
Tilt ON	Tilt correction ON/OFF
N 10.000	Instrument station N coordinate (E coordinate)
E 10.000	E coordinate (N coordinate)
Z0.000	Z coordinate

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# 2

< S,	V, I	H (Off	set) >	(distance)
------	------	--------	--------	------------

Pt. 1	012	Target station number
Code T	REE. 101	Code (If no code, "?" is displayed)
Ht ppm Off S ZA HAR	1.300 m 13 B 3.570 m 8.472 m 100° 48' 30° 244° 57' 55"	

### < V, H, Tilt >

### < N, E, Z + S, V, H >

	1012 HOUSE. SUZU	Target station number Code (If no code, "?" is displayed)	♣ Pt. Code	1014 TREE. 4	Target station number Code (If no code, "?" is displayed)
Ht ppm ZA HAR Tilt X Tilt Y	1.300 m 13 100° 48' 30" 244° 57' 55" 0° 01' 45" 0° 00' 05"	Target height Atmospheric correction Vertical angle Horizontal angle X direction tilt angle Y direction tilt angle	Ht ppm N E Z S	1.300 m 13 62.902 41.930 0.000 25.487 m	Target height Atmospheric correction N coordinate (E coordinate) E coordinate) (N coordinate) Z coordinate
-		•	ZA HAR	100° 48' 30" 244° 57' 55"	

-	-	
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2475 (22)

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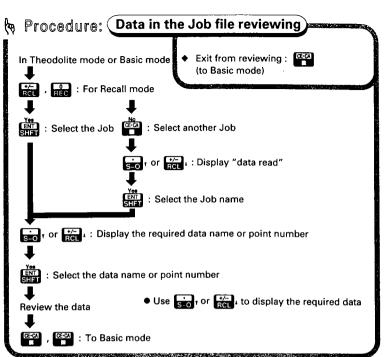
### < N, E, Z > / < Coordinate file >

Pt. 1013	Target station number/Point number
Code TREE.3	Code (If no code, "?" is displayed)
Ht 1.300 m	Target height/empty column if coordinate file
ppm 13	Atmospheric correction/empty column if coordinate file
N 62.902	N coordinate (E coordinate)
E 41.930	E coordinate (N coordinate)
Z 0.000	Z coordinate

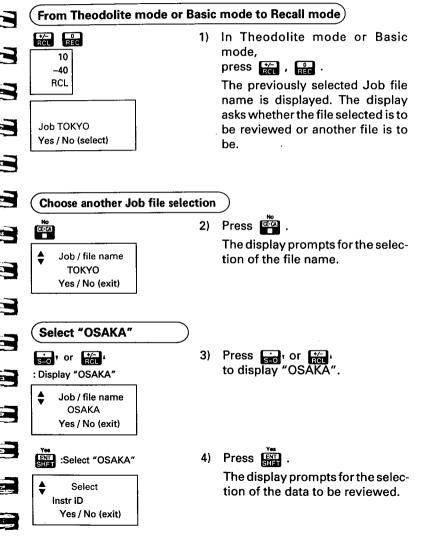
### <Note >

Note RAIN

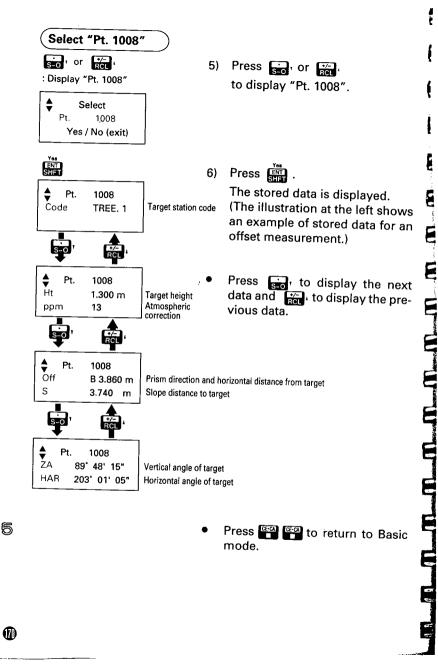
Remark

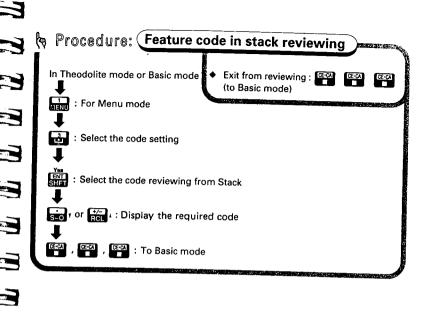


 To review the measured data for target station number 1008 in the Job file called "OSAKA"



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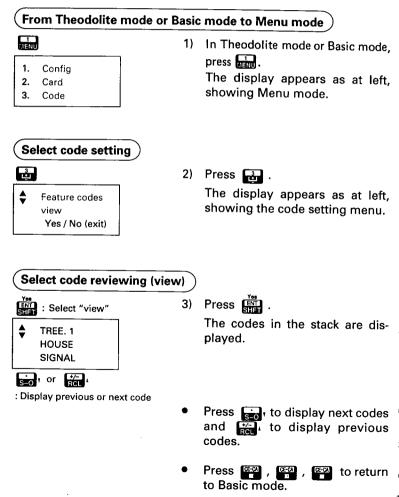




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Note: To review codes in a code file recorded on a card, please make sure the code file has been recalled into the stack referring to the instructions on P.145, "21.10 Feature code recalling to stack", in advance.





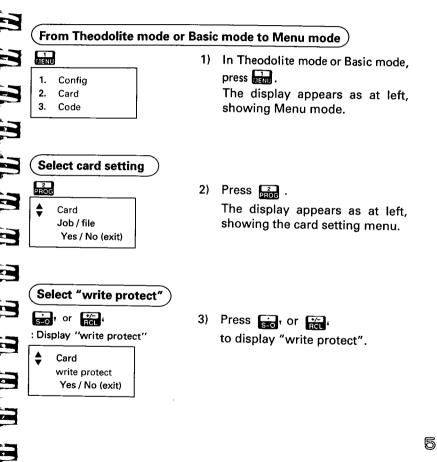
# 21.15 Protecting data stored on the card

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Once data has been recorded on the card, it can be protected from erasure or formatting by using the Write Protect function.



Select "write protect"

Write

- 1. protect on
- 2. enable

### 4) Press

The display asks whether the Write Protect function is to be turned on or canceled.

### Select the card protect function Press . 5) The message "Write protected" is displayed and the data is pro-Write protected tected. The display returns to Menu mode. Config 1. 2. Card 3. Code 2 : Cancel the protect Press 2. function The message "Write enabled" is displayed and the Write Protect Write enabled function is canceled. The display returns to Menu mode. 1. Config 2. Card 3. Code Press control to return to Basic mode.

### 21.16 Data stored on the card output to an external device

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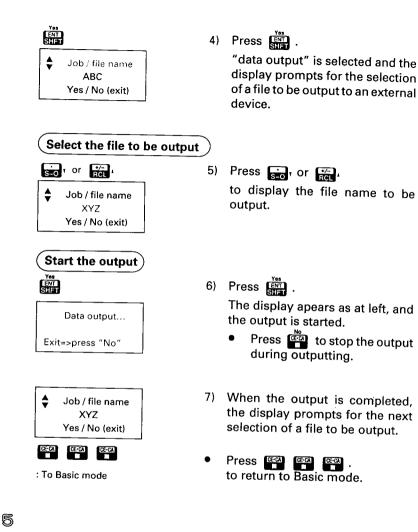
3

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• Key operations allow the SET C to output the data stored on the card via the data output connector to an external device using an interface cable. (For more information, see the Series C 2-way communication manual.)

1. Config 2. Card 3. Code	1)	In Theodolite mode or Bas mode, press . The display appears as at le showing Menu mode.
Select "Card" setting	0.1	
<pre>220G Card Job / file Yes / No (exit)</pre>	2)	Press and the press of the display appears as at le showing Card setting menu.
Select the "data output")		
Card data output Yes / No (exit)	3)	Press ون ، or المحمد ، to display "data output".



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### TROUBLESHOOTING

### 22. ERROR MESSAGES

### æ P.179

### 23. CHECKS AND ADJUSTMENTS

🖅 P.183

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- 23.1 Plate level
- 23.2 Circular level 🕲
- 23.3 Reticle 🕲
- 23.4 Coincidence of distance measuring axis with reticle 0
- 23.5 Optical plummet ®
- 23.6 Distance measurement check flow chart (1)
- 23.7 Additive distance constant @

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# 22. ERROR MESSAGES

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- If the following error messages are shown during measurement, see the table below.
- If the same error message is repeated or if other messages are shown, please contact your Sokkia agent.

Display	Meaning	Action
Bad cond.	Prism sight is bad.	Sight the target again. Measure again after confirming the re- turned signal using the signal checking mode.
Battery is low	Battery voltage is too low.	Charge the battery or replace it with a charged one.
Card bat low	Card battery level is too low.	Card should be re- placed with a new one. Or, replace the battery in the card.
Card is full	Less than 60 bytes of memory remaining.	Card should be re- placed with a new one.
Confirm 0 set	Reset is not performed.	Index the V and H circles again.
Data error	An error has occurred during recording.	Level the SET Cagain or sight the reflecting prism.
	Error when measuring the initial slope dis- tance during either REM or horizontal dis- tance between two points measurement.	Sight the reflecting prism to perform slope distance measurement again.

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Display	Meaning	Action	
File exists	Card has had the same code file name.		
File not exists	Card has no code file or Job file.		
Invalid file	The specified file has a different configuration and cannot be selected.	Select the correct file.	
Job area over	Card has no area for new Job file or code file.	MAX file 24 gsbs	
Memory cleared	After 1 week, data stored in the short term memory has been cleared.		
No card	Card is not correctly mounted in the instru- ment.	Make sure the card has been inserted properly	
Card error	No communication with card.		
	After changing the card battery.	No problem.	
No code data	Stack has no feature code data.		
No coord. data	There is no data in the selected file.		
No data	There is no data for the specified point number, or the specified point number does not con- sist of coordinate data.		
No Job	Card has no Job.		

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Display	Meaning	Action	
Not formatted	New card. Card has not been formatted.	Format the card.	
Out of range	During REM, the verti- cal angle is more than±89° or the mea- sured distance is more than 9999.999m	Press 🕬 to stop measuring.	
Out of range X > ⊥ <y< td=""><td>Tilt sensor range error. Tilt angle exceeds ±3'.</td><td>Level the SET C again.</td></y<>	Tilt sensor range error. Tilt angle exceeds ±3'.	Level the SET C again.	
Record error	External device does not reply with ACK/ NAK. (when "recording" pa- rameter is set to "out".)	Check to see if there are any abnormalities in cables or external equipment, or if there is a problem with the program.	
Signal off	At start of measure- ment, the returned sig- nal was totally absent or disturbed.	Sight the target again. Measure again after confirming the re- turned signal using the signal checking mode.	
Stack is full	There is no area to record codes in stack. (Up to 140 characters)		
Tilt error	While setting the azi- muth angle, tilt angle exceeds ±3'.	Level the SET C again.	
Tilt Out of range	During distance mea- surement, tilt angle ex- ceeds ±3'.	Level the SET C again.	
Time out	No measured distance data is received within 2 minutes of starting the measurements, or the measured distance data cannot be ob- tained for a total of one minute.	Sight the target again. Measure again after confirming the re- turned signal using the signal checking mode.	

Display	Meaning	Action	
Unit error	Instrument distance units do not match those on the card.	Set the distance unit in the data on the card to match that of the instru- ment.	
Write protected	The data on the card is protected and the card cannot be used.	Press for Menu mode, and change the setting for the card from "Write protected" to "Write enabled".	
E 100	Error when measuring a horizontal angle*.	Index the horizontal circle again.	
E 101	Error when measuring a vertical angle*.	Index the vertical circle again.	

\* If the SET C telescope or upper part is rotated faster than four revolutions per second, the error indication "E 100" or "E 101 is displayed.

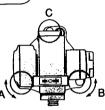
### 23. CHECKS AND ADJUSTMENTS

- Periodically, checks and adjustments should be performed before and after measurement. In addition, the instrument should be checked after long storage, transportation or when damage to the instrument is suspected to have occurred due to a strong shock.
- The checks should be performed in the following order.

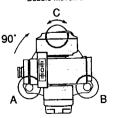
### 23.1 Plate level

 The glass tube of the plate level is sensitive to temperature changes or shock.

Check

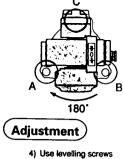






- Turn the upper part of the instrument until the plate level is parallel to a line between levelling foot screws A and B.
   Centre the plate level bubble using levelling screws A and B.
- Note: The bubble moves towards a clockwise rotated foot screw.
- Loosen the horizontal clamp @ and turn the upper part 90°. The plate level is perpendicular to a line between levelling screws A and B.

Centre the plate level bubble using levelling screw C.









- Turn the upper part through 180° and check the bubble position. If the bubble is still centred, no adjustment is necessary. If the bubble is off-centre, adjust as follows:
- Correct half of the bubble displacement using levelling screw C.
- Correct the remaining half of the displacement by adjusting the screw @ with the adjusting pin.
- Note: The bubble moves away from a clockwise rotation of the adjusting screw.
- Repeat the procedures from 1) to 5) until the bubble remains centred for any position of the upper part.

If the bubble can not be centred, please contact your Sokkia agent.

# 23.2 Circular level

- - Adjustment

Circular level adjusting screws



- 1) Perform the plate level adjustment or level the instrument carefully using the plate level.
- 2) Check the position of the circular level bubble.

If the bubble is off-centre, adjust as follows:

- 3) Verify the off-centre direction of the bubble.
- Loosen the adjusting screw farthest from that direction to centre the bubble.
- Adjust all 3 adjusting screws until the tightening tension of each screw is the same, and the bubble is centred.
- Note: Over-tightening the adjusting screws may damage the circular level. Unequal tightening of the screws may mean that the bubble will go out of adjustment.

If the bubble can not be centred, please contact your Sokkia agent.

### 23.3 Reticle

• This adjustment is very delicate. If you have any difficulties, please contact your Sokkia agent.

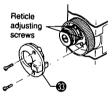
### Perpendicularity of the reticle to the horizontal axis

### Check













- Level the SET C carefully. Select and sight a clear target on the upper part A of the reticle line.
- Turn the telescope vertical fine motion screw 

   until the target is on the lower part of the reticle B. If the target is still positioned centrally within the reticle lines, no adjustment is necessary. If the target is off-centre, adjust as follows:

Remove the telescope reticle cover .

- Slightly loosen one vertical and one horizontal adjusting screw by a certain amount using the adjusting pin.
- Place a small piece of plastic or wood against one side of the top adjusting screw mount as a buffer.
- Look through the eyepiece and gently tap the piece of plastic or wood to rotate the reticle slightly.
- Retighten the two adjusting screws loosened in step 4) by the same amount.
- Note: Over-tightening the adjusting screws may damage the reticle. Unequal tightening of the adjusting screws may mean that the reticle will go out of adjustment.

- 8) Check the reticle perpendicularity again using procedures 1) and 2) above and repeat the adjustment if necessary. Replace the reticle cover.
- Note: After this adjustment, perform the check and adjustment of the reticle position as follows:

### Vertical and horizontal reticle line positions

- Check 50 ~ 100m
- 7A 90° 30' 10" HΔR 18° 34' 00" 10 ZΑ 269° 30' 00" HAR 198° 34' 10"

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- 1) Set up a clear target 50 - 100m from the SET C. Level the instrument carefully, switch on, and index the vertical and horizontal circles.
- 2) Sight the target on face left. Read the vertical and horizontal angles.

HAR 18°34'00" ..... a1 e.a. ZA 90°30'10".....b1

- 3) Now sight the target on face right. Read the vertical and horizontal angles.
  - e.g. HAR 198°34'10"....a2 ZA 269°30'00"....b2
- 4) Calculate a2 - a1 = 180°00'10". The difference should be within 180° + 20"
- 5) Calculate  $b1 + b2 = 360^{\circ}00'10''$ . The sum should be within 360° ± 20"

If a difference of more than  $\pm 20"$ still remains after repeating these procedures several times, adjust as follows:

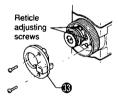
Note: Moving the reticle line effects the distance measurement. Do not move the reticle more than 20".

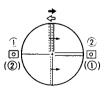
### Adjustment

e.g.  $a1 = 18^{\circ} 34' 00^{\circ}$  $b1 = 90^{\circ} 30' 10^{\circ}$  $a2 = 198^{\circ} 34' 20^{\circ}$  $b2 = 269^{\circ} 30' 10^{\circ}$ 

ZA	296° 30' 00"
HAR	198° 34' 10"
	_







6) Calculate Horizontal angle A and Vertical angle B,

 $A = (a2+a1)/2+90^{\circ}=198^{\circ}34'10"$ 

B = (b2-b1)/2+180° = 269°30'00"

- 7) While still sighting the target on face right, use the horizontal and vertical fine motion screws to adjust the displayed horizontal and vertical angles to the above values.
- 8) Look through the telescope. The reticle is now slightly shifted from the target.
- Unscrew the two fixing screws and remove the telescope reticle cover (9).
- 10) To move the vertical reticle line towards the target centre, use the adjusting pin to adjust the left and right adjusting screws as follows: Slightly loosen the top and bottom adjusting screws by the same amount.

To move the reticle to the right (left), first very slightly loosen the left (right) adjusting screw, then tighten the right (left) adjusting screw by this same amount.

- [( ) for opposite direction]

(1)(2)0 1..... 0 <u>ه</u>(۱)

Finally tighten the top and bottom adjusting screws as before.

Check the reticle position and repeat the procedure until the reticle comes close to the target centre.

11) To move the horizontal reticle line towards the target centre, adjust the top and bottom adjusting screws as follows:

> Slightly loosen the right and left adjusting screws by the same amount.

> To move the reticle down (up), first slightly loosen the top (bottom) adjusting screw, then tighten the bottom (top) adjusting screw by this same amount.

> Finally tighten the right and left adjusting screws as before.

> Check the reticle position and repeat the procedure until the reticle comes close to the target centre.

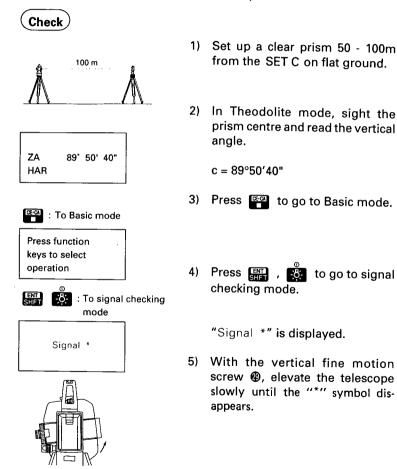
- 12) Replace the reticle cover.
- Note: Over-tightening the adjusting screws may damage the reticle. Unequal tightening of the adjusting screws may mean that the reticle will go out of adjustment.

After this adjustment, please adjust the collimation error referring to P.220 "Appendix 2:<Adjusting the collimation error by collimation program>".

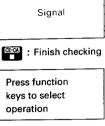
# 23.4 Coincidence of distance measuring axis with reticle

 After the reticle check, verify that the distance measuring axis is matched with the reticle.

Note: Do not adjust the reticle in this step.







: To Theodolite mode

ZA 89° 47' 00" HAR

CE-CAI : To Basic mode

Press function keys to select operation

	O (
ENT	- A
SHFT	<u> </u>

: To signal checking

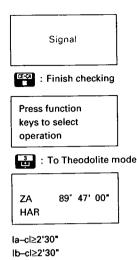




6) Press at this position ("\*" not displayed) to return to Basic mode, then press to go to Theodolite mode and read the vertical angle.

a = 89°47′00"

- 7) Press again to return to Basic mode, then press **FF**, **, FF** to go to the return signal checking mode.
- Lower the telescope slowly with the vertical fine motion screw until the "\*" symbol disappears.

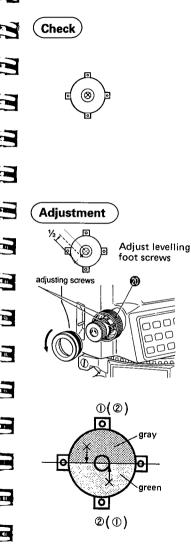


9) Press at this position (\*\*" not displayed) to return to Basic mode, then press in to go to Theodolite mode and read the vertical angle.

b = 89°54′20"

10) There is no problem if the difference of a and b against c is more than 2'30" (SET4C: 3'). The right and left directions require the same check. If any of the differences are less than 2'30", please contact your Sokkia agent.

## 3 23.5 Optical plummet



-46

- Level the SETC and exactly centre a surveying point in the reticle of the optical plummet.
- Turn the upper part 180°
   If the surveying point is still centred, no adjustment is necessary.

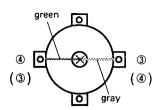
If the surveying point is offcentre, adjust as follows:

- 3) Correct half the deviation with the levelling foot screws ().
- Unscrew the optical plummet focussing ring @.
- 5) Adjust the remaining half of the displacement with the 4 adjusting screws to centre the reticle exactly on the surveying point. When surveying point is seen as a

green (gray) area:

- ① Loosen the upper (lower) screw slightly.
- ② Tighten the lower (upper) screw by the same amount.

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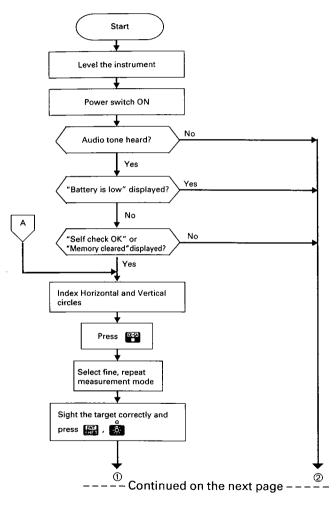
Ø

Next, if the surveying point is seen to be on the green line (gray line):

- 3 Loosen the right (left) screw slightly.
- Tighten the left (right) screw by the same amount.
- Note: Over-tightening the adjusting screws may mean that the reticle will go out of adjustment.
- 6) Check the adjustment by rotating the upper part of the instrument. The survey point should remain centred in the reticle. If necessary, repeat the adjustment.
- 7) Reattach the optical plummet focussing ring.

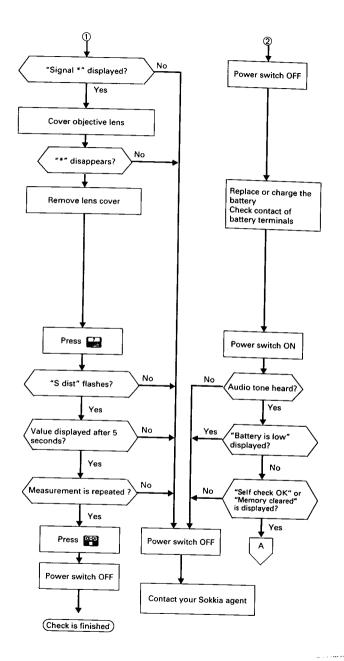
# 23.6 Distance measurement check flow chart

 If error codes EXXX are displayed, please contact your Sokkia agent.



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i 1



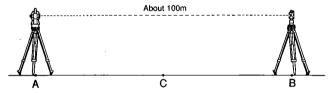
€. 4 Ê 

### 23.7 Additive distance constant

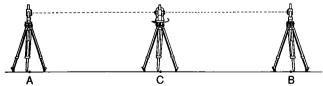
• The additive distance constant K of the SETC is adjusted to 0 before delivery. However, it may change over time and so should be determined periodically and then used to correct distances measured.

### Check

- 1) Select points A and B on flat ground about 100 m (328ft) apart, and C in the middle.
- Note: Ensure that the target height is the same as the instrument height of the SET C objective lens centre. If the ground is not flat, use an automatic level to set the correct instrument heights of all points.



- 2) Set up the SETC at A, the target at B and measure (fine measurement) the distance A-B 10 times.
- 3) Shift the SETC to C, and measure (fine measurement) the distance C-A and C-B 10 times each.

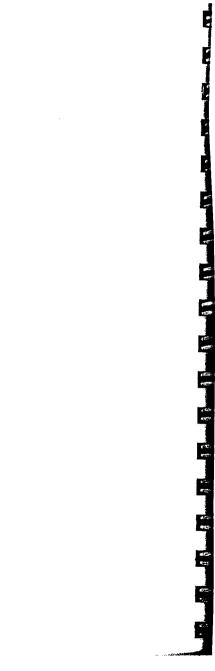


Calculate the averages of A-B, C-A and C-B.
 Compute the additive distance K using the formula:

 $K = \overline{A-B} - (\overline{C-A} + \overline{C-B})$ 

Obtain the K value several times. If all K values are greater than ±3mm (SET4C:±5mm), please contact your Sokkia agent.

Note: Errors in setting up the instrument and sighting the target will affect the determination of the additive distance constant, therefore perform these procedures as carefully as possible.



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### MEASUREMENT OPTIONS SELECTION

### 24. CHANGING INSTRUMENT PARAMETERS 3 P.201

25. POWER SUPPLIES 3 P.211

### 26. REFLECTING PRISMS AND ACCESSORIES 3 P.213

### 24. CHANGING INSTRUMENT PARAMETERS

- The instrument parameter settings can be changed by key operations to match the required measurement.
- The selected options are stored in the memory until they are changed.

The factory set options are reset when the "Configuration default set" is initialized.

No.	Parameter			Options
1	Coordinate data from			*1. Keyboard
				2. Card
2	Recording	1. Send da	ata to	*1. Card
	_			2. External device
		2. Set code		*1. Input
1				2. Non-input
		3. Set targ	jet height	*1. Input
				2. Non-input
3	Tilt correction			*1. Tilt correction applied
				2. Correction not applied
4	Coordinate format			*1. N, E, Z
				2. E, N, Z
5	5 V angle format			*1. Zenith
				2. Horizontal 0° -360° (0 - 400gon)
				3. Horizontal ±90° (±100gon)
6	Angle resolu	ition	SET2C,	*1. 1" (0.2mgon)
	_		SET3C	2. 5" (1mgon)
			05740	*1. 5" (1mgon)
		SET4C		2. 10" (2mgon)
7	BS-232C	1. Baud ra	ate	*1. 1200 baud
	format			2. 2400 baud
		2. Checksum 3. Parity bit		*1. No
				2. Yes
1				*1. No
				2. Yes (even)
8	V indexing			*1. Auto
1				2. Manual
9	H indexing			*1. Auto
1				2. Manual

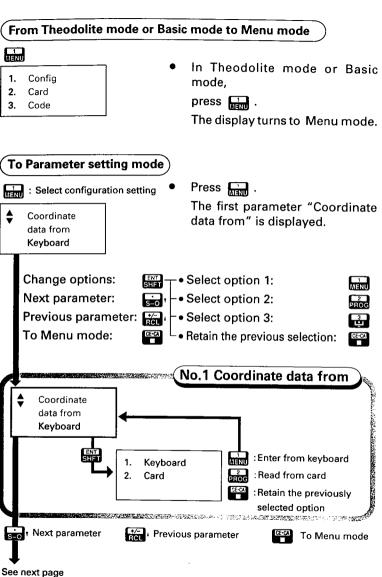
No.	Parameter		Option	Option		
10	C + R correction		1. No	1. No		
			2. Yes K=	2. Yes K=0.142		
			3. Yes K≃	3. Yes K≃0.20		
11	Units	1. Distance	*1. metre			
			2. Feet	2. Feet		
		2. Angle		1. Degree		
		3. Temperature	'1. ℃& m	bar		
		&	2. ℃& m	mHg		
		pressure	3. Next	1. °F & mbar		
				2. °F & mmHg		
		<u> </u>		3. °F & inchHg		
12	Auto power off		<u>1. 30 min</u>	* 1. 30 minutes timeout		
			2. Power	2. Power On/Off with switch		
13	Backlight control		<u>′ 1. On/Off</u>	1. On/Off by key operation		
			2. 30 seco	2. 30 seconds timeout		
14	14 Audio for return signal		1. Audio	1. Audio tone		
			2. No auc	2. No audio tone		
15	Reticle illumination			*1. Strong reticle illumination		
			2. Weak r	2. Weak reticle illumination		
16	Configuration default set		Initialize :	Initialize : Yes / No		

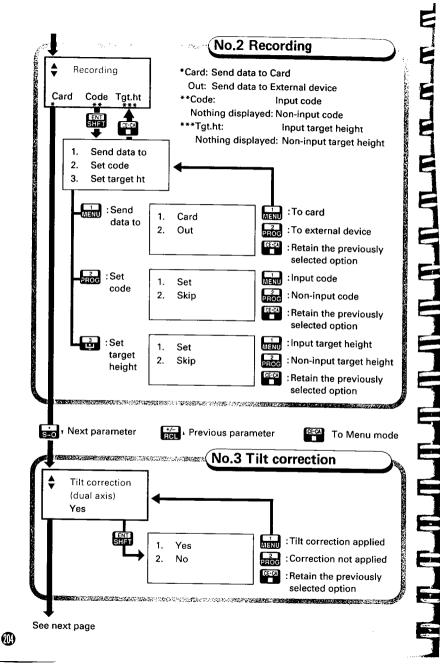
\*Parameter options set at the time the instrument left the factory.

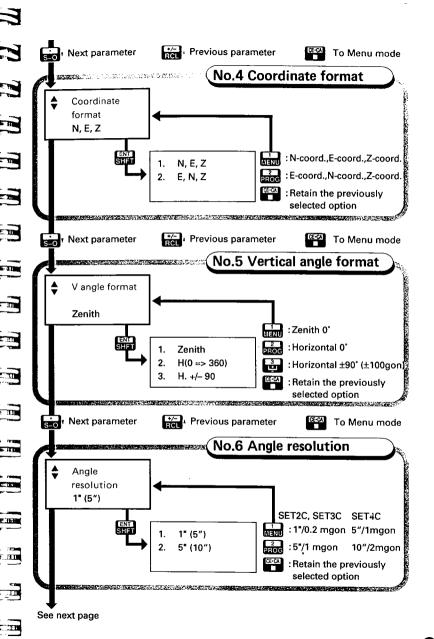
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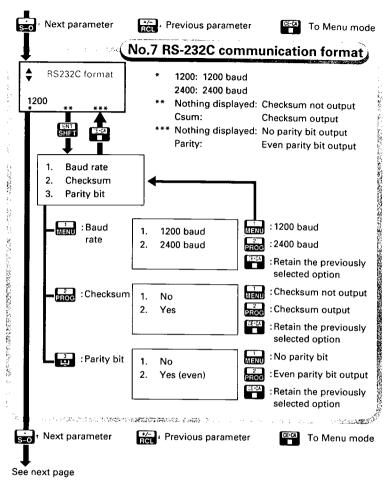
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:Transit telescope to

: Index by F.L./F.R sighting

To Menu mode

To Menu mode

THE REAL PROPERTY OF

: Retain the previously selected option

index circle

(X)-30

Rotate upper part to

: Index and 0 set at power on

: Retain the previously selected option

: No C+R correction applied

:C+R correction K=0.142

:C+R correction K=0.20

: Retain the previously selected option

index circle

CE-CA

(No.8 Vertical circle indexing

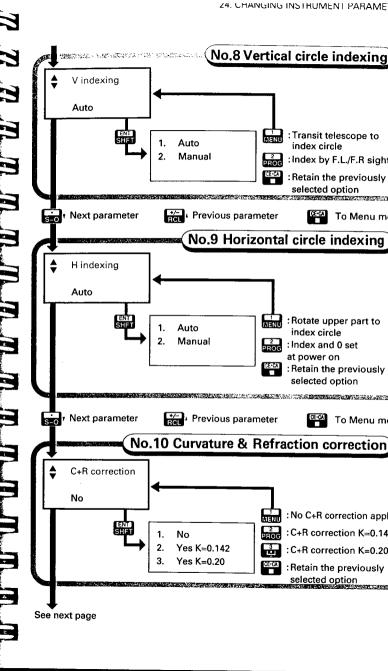
MENU

2 PROC

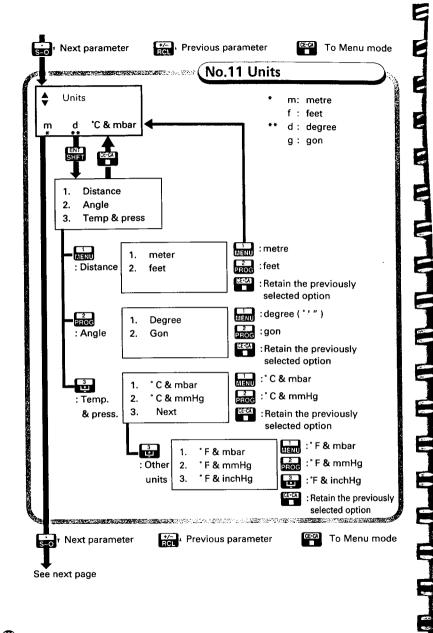
CE-C

2 PROG

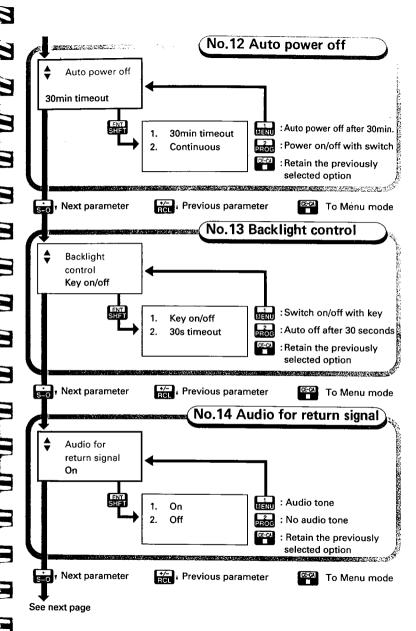
CE CA

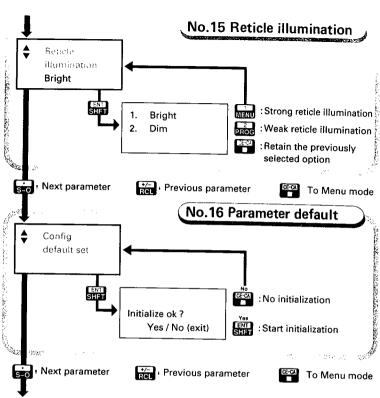






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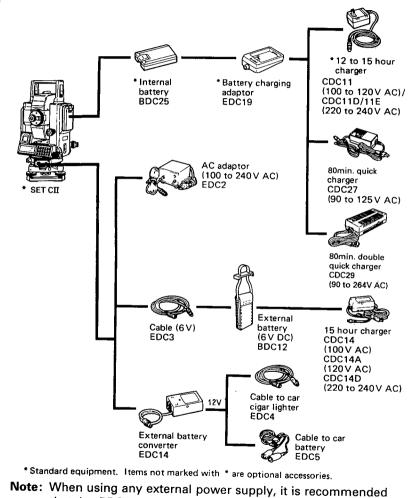
No.1 "Coordinate data from" parameter

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### 25. POWER SUPPLIES

The SET C can be operated with the following combinations.



that the BDC25 battery be left in place to balance the weight

on the axes.

Use the SET C only with the combinations shown here.

#### 1) Precautions for battery use and storage

- Charge the battery at least once a month if it is not used for a long time.
- Store the battery in a place where the temperature is between 0°C and 40°C.

#### 2) Precautions for battery charging using the standard charger

To charge the battery, use only the recommended charger.

- Charge the battery at a temperature between 10°C and 40°C.
- Do not charge the battery for longer than the specified time.
- When charging the battery, first mount it in the adapter and connect to the battery charger, then connect the charger to the power supply. Check that the charging light is on. If not, switch the power supply off and on and check that the light comes on.
- The battery charger normally becomes warm while charging.
- Battery operating life is shortened at extreme temperatures.

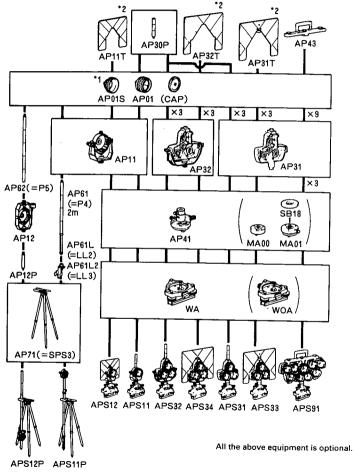
#### 3) Precautions for the use of external power supplies

- When using a car battery, make sure that the polarity is correct.
- Ensure that the car cigarette lighter has 12V output and that the negative terminal is grounded.
- Before using EDC2, set the voltage selector to the correct voltage.
- EDC14 has a breaker switch. Normally the red mark appears on the breaker. If not, set the red mark in place.

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# 26. REFLECTING PRISMS AND ACCESSORIES

• All Sokkia reflecting prisms and accessories have standardized screws (5/8" x 11 thread) for ease of use.



- \*1: To change the stored prism constant value, see P.45.
- \*2: Fluorescent target paint finishing allows clearer sighting in adverse observing conditions.

#### 1) Precautions for use of reflecting prisms

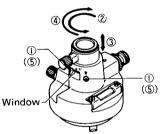
- Carefully face the reflecting prism towards the instrument; sight the prism target centre accurately.
- To use the triple prism assembly AP31 or AP32 as a single prism (e.g. for short distances), mount the single prism AP01 in the centre hole of the prism holder.

#### 2) Precautions for use of the instrument height adapter AP41

 Check the optical plummet of the AP41 as described in Section 23.5.

Check that the optical plummet of the AP41 sights the same point as that of the SET C.

• Check that **236** (the height of the SET C in mm) is displayed in the window of the instrument height adapter AP41. The height of the AP41 can be adjusted as follows:



- ① Loosen the 2 fixing screws.
- ② Turn the centre part counterclockwise to unlock it.
- ③ Move it up or down until "236" appears in the window.
- Turn the centre part clockwise to lock it.

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5 Tighten the fixing screws.

#### 3) Precautions for use of tribrach

 Use the plate level on the AP41 to adjust the tribrach circular level as described in Section 23.2.

### APPENDICES

Appendix 1:	MANUALLY INDEXING THE VERTICAL CIRCLE BY FACE LEFT, FACE RIGHT MEASUREMENTS	Ŧ	P.217
Appendix 2:	FOR ANGLE MEASUREMENT OF THE HIGHEST ACCURACY	<b>F</b>	P.218
Appendix 3:	FOR DISTANCE MEASUREMENT OF THE HIGHEST ACCURACY	Ŧ	P.223
Appendix 4:	EARTH-CURVATURE AND REFRACTION CORRECTION	F	P.225
Appendix 5:	DATA OUTPUT TO AN EXTERNAL DEVICE	<b>.</b> A	P.226
Appendix 6:	STANDARD ACCESSORIES	Ŧ	P.228
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STANDARD	EQUIPMENT	F	P.232
MAINTENAM	NCE	Ŧ	P.233
SPECIFICAT	IONS	ቆ	P.234
ATMOSPHE	RIC CORRECTION CHART	Ŧ	P.238

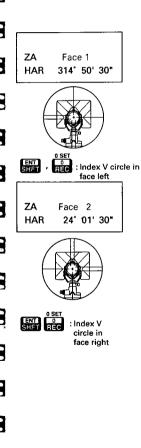


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### APPENDIX 1: MANUALLY INDEXING THE VERTICAL CIRCLE

• Like all theodolites, the SET C will have a small vertical index error. For angle measurement of the highest accuracy, the vertical index error can be removed as follows:



- In parameter setting mode, select the "V indexing" parameter and set to "2. Manual".
- In Basic mode, press after step 1), or switch off and on again.
   "ZA Face 1" is displayed.
- In face left (Face 1), accurately sight a clear target at a horizontal distance of about 30 m.



- "ZA Face 2" is displayed.
- Loosen the horizontal clamp and rotate the upper part of the SET C through 180°. In face right (Face 2), accurately sight the same target.

- The vertical circle has been indexed.
- Note: If the power switch is turned off, the vertical circle should be indexed again.

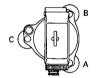
### **APPENDIX 2: FOR ANGLE MEASUREMENT OF THE HIGHEST ACCURACY**

#### <Adjusting the tilt zero point error>

- The tilt zero point error can be adjusted by the following procedures. (The "Tilt correction" parameter should be set to "Yes".)
- The range of the tilt sensor is ±3'.
- Tilt offset data storage period: Until the next adjustment is made
  - (Power-off possible)
  - Level the SET C with the plate 1) level 🕅 Tighten the vertical clamp @ with the telescope approximately horizontal.
  - Use the horizontal clamp @ to 2) turn the upper part of the SET C until the telescope is parallel to a line between levelling screws A and B.
  - In Theodolite mode, 3) press ENT , The horizontal angle is set to 0°.

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Press 2 4) for Program mode.





89°12'30"
0°00'00"



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- 1. Resection
- 2. Correction
- З. Pt. replace

2 : For Correction mode



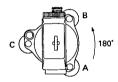
- 2. Tilt offset
- **2.** Intonset

2 : For Tilt offset mode

Tilt angle X 0° 00' 10" Y -0° 00' 10"



Tilt angle Face 2 HAR 0° 00' 00"



Tilt angle Face 2 HAR 180° 00' 00"



: Memorize tilt angle and store the tilt offset data

- 1. Resection
- 2. Correction
- 3. Pt. replace

- 5) Press **From** for Correction mode.
- Press for Tilt offset mode.
   Minimum display unit SET2C : 1" SET3C : 1" SET4C : 5"
- Wait for a few seconds until the tilt angle reading is steady.

Then press [INT], [INT], INTER .

(X and Y tilt angles will be memorized.)

 Turn the upper part of the SET C through 180°.

 Wait for a few seconds until the tilt angle reading is steady,

then press **FF**, **Fe**. The tilt zero point error has been adjusted and the display has returned to Program mode.

- Press to go to Basic mode.
- If there is no response when the key is pressed, the range in which adjustment is possible has been exceeded. Please contact your Sokkia agent and request adjustment.

#### <Adjusting the collimation error by Collimation program>

• The displayed angles are corrected automatically by the stored collimation errors.

These collimation error values can be adjusted and stored by following the relevant procedures.

The observation can be carried out up to 5 times, so if an accurate sighting can be made, increasing the number of times the observation is carried out will result in a more precise determination of the collimation error values.

- Note: In Tracking measurement mode, the displayed horizontal angle is not corrected by the stored collimation error values.
- If angle measurements are to be made in only one position (e.g. Resection measurement), it is advisable to adjust the correction values accurately.
- Collimation error values storage period: Until next adjustment (Power-off possible)
- Note: Sight the target carefully to determine the collimation error accurately.

Ensure that the target height is the same as the instrument height. If the ground is not flat, use an automatic level to set the correct instrument height of all points.



2 : For Program mode

- 1. Resection
- 2. Correction
- 3. Pt. replace

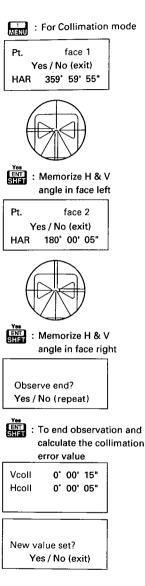


#### Select

- 1. Collimation
- 2. Tilt offset

- Set up a clear target at a horizontal distance of a bit longer than 100m from SET C.
- In Theodolite mode or Basic mode, press for Program mode.
- 3) Press From for Correction mode.





- Press for Collimation mode.
- 5) In face left (face 1), sight the target correctly and press .

A display prompts for the vertical angle and horizontal angle for the telescope face 1 to be stored in the memory.

6) In face right (face 2), sight the target correctly, and press and pres

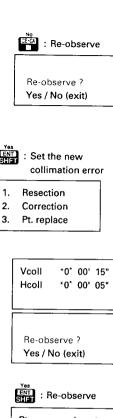
The display asks whether the observation is ended or not. (Observation can be carried out up to 5 times.)

7) To end the observation process, press

The collimation error value is calculated and displayed.

Following that, the display asks whether a new collimation error value is to be set.





- Pt. face 1 Yes / No (exit) HAR 0° 00' 00" or <sup>№</sup> E<sup>™</sup> : End
- 1. Resection
- 2. Correction
- Pt. replace

- To continue the observation, press .
   The display asks whether observation is to be continued.
   Pressing .
   Pressing .
- To set a new, collimation error value, press state
   The collimation error has been adjusted and the display has returned to Program mode.
  - Press et al.
     to go to Basic mode.
- If the range in which adjustment is possible has been exceeded, an asterisk (\*) is displayed, and a confirmation message is displayed, the display asks whether you begin observation once again, from the beginning.

To redo the observation, press . The procedure reverts to Step 5).

To end the observation process, press 🚰 . The display returns to Program mode.

If an asterisk is still displayed after repeated attempts at observation, the allowable adjustment range has been exceeded. Please contact your Sokkia agent and request adjustment.

### APPENDIX 3: FOR DISTANCE MEASUREMENT OF THE HIGHEST ACCURACY

#### 1) Atmospheric correction

• The SET C uses a beam of infrared light to measure the distance. The velocity of this light in the atmosphere varies according to the temperature and pressure.

The distance will be changed by 1 ppm by:

- a variation in temperature of 1°C
- a variation in pressure of 3.6 mb

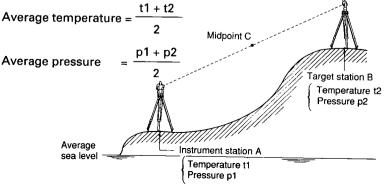
(A 1 ppm change means a 1mm difference for every 1km of measured distance).

To obtain distance measurement, of the highest accuracy, the temperature and pressure must be carefully measured by accurate equipment.

 The ppm correction should be applied when the calculated ppm value is over ±5ppm or if the slope distance is more than 200m.

## 2) Average temperature and pressure between 2 points in different atmospheric conditions:

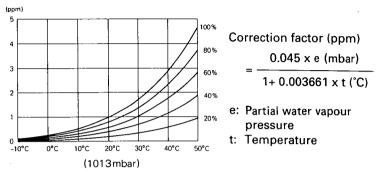
- In flat terrain: measure the temperature and pressure at the midpoint of the line as there is little variation in the values.
- In mountainous terrain: midpoint values should be used. If those values cannot be measured, take the temperature and pressure at the instrument and target stations, then calculate the average values.



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#### 3) Influence of relative humidity

• The influence of humidity is very small. It is mainly of importance in very hot and humid conditions. The graph below is for atmospheric pressure of 1013 mbar.



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- If you take the influence of relative humidity into account, please set the Correction factor (ppm) by the following method.
- ① Input the temperature and pressure values. The correction factor A is calculated and displayed on the sub display.
- ② Measure the relative humidity and read the correction factor B from above table.

For pressure between 500 mbar and 1400 mbar, if instead of the formula, the graph above is used to look up the correction factor, a difference of less than 0.1 ppm will be present.

- ③ Calculate A plus B. (C)
- ④ Input C in ppm mode. (Refer to P.48 "13.3 Atmospheric correction")
- 6 Measure the distance. The displayed distance is corrected by the correction factor C.
- e.g. Temperature: 30°C, Pressure: 1020 mbar, Relative humidity: 80% Measured distance corrected by only the correction factor A: 3000m

A=12 (sub display), B=1.4 (above table)

$$D = \frac{1 + (12 \text{ ppm} + 1.4 \text{ ppm}) \times 10^{-6}}{1 + 12 \text{ ppm} \times 10^{-6}} \times 3,000 \text{ m}$$
  
= 3.000.0042 m

A)

### APPENDIX 4: EARTH-CURVATURE AND REFRACTION CORRECTION

 When measuring the Horizontal distance and Height difference, the earth-curvature and refraction correction can be selected by the parameter "C & R correction". The Atmospheric refraction constant K can be set to either 0.142 or 0.20.

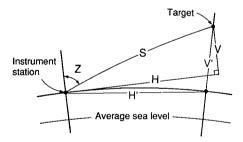
#### <No correction>

Horizontal distance:  $H = S \times sin Z$ Height difference:  $V = S \times cos Z$ 

#### <Applied correction>

Horizontal distance: H' = S x sin Z -  $\frac{1 - \frac{K}{2}}{R}$  x S<sup>2</sup> x sin Z x cos Z

Height difference:  $V' = S x \cos Z + \frac{1 - K}{2R} x S^2 x \sin^2 Z$ 



- S: Slope distance (atmospheric corrected value)
- Z: Vertical angle (0° at zenith)
- K: Atmospheric refraction constant
- R: Radius of the earth (6.372 x 10<sup>6</sup> m)

e.g. Correction value at Z=70° (K=0.142)

S (m)	500	1000	1500
H'–H (m)	- 0.012	- 0.047	- 0.105
V′–V (m)	0.015	0.059	0.134

**Note:** The horizontal distance is the distance measured at the height of the surveying point above sea level. If required, reduce this distance to the average sea level and apply the local projection correction.

### APPENDIX 5: DATA OUTPUT TO AN EXTERNAL DEVICE

Key operations allow the SET<sub>C</sub>C to output measured data via the data output connector to an external device using an interface cable.

(For more information, see the Series C 2-way communication manual)

• The contents of data which can be output are the same as that of data which can be stored on the card. See P.113 "21.1 Card features".

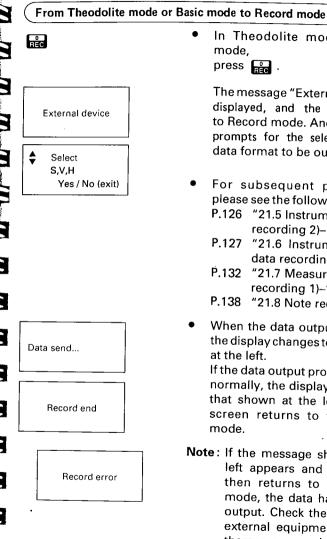
## Appendix 5–1: Changing the instrument options

- Confirm that this parameter is set according to the data output to an external device condition.
   The "Send data to" parameter should be set to "Out".
- To confirm or change the parameter option, see P.201 "24. CHANGING INSTRUMENT PARAMETERS".

No.	Parameter		Options
2	Recording	1. Send data to	Card/out
		2. Set code	Set/Skip
		3. Set target ht	Set/Skip

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### Appendix 5–2: Output of data



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In Theodolite mode or Basic mode. press 📑 .

The message "External device" is displayed, and the display goes to Record mode. And the display prompts for the selection of the data format to be output.

- For subsequent procedures, please see the following sections: P.126 "21.5 Instrument data
  - recording 2)-"
  - P.127 "21.6 Instrument station data recording 1)-"
  - P.132 "21.7 Measured data recording 1)-"
  - P.138 "21.8 Note recording 1)-"
- When the data output is started, the display changes to that shown at the left.

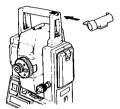
If the data output procedure ends normally, the display changes to that shown at the left, and the screen returns to the Record mode.

Note: If the message shown at the left appears and the display then returns to the Record mode, the data has not been output. Check the cables and external equipment to see if there are any abnormalities, and check the program for problems.

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### **APPENDIX 6: STANDARD ACCESSORIES**





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#### 1) Plumb bob

If the weather is calm, or for initial tripod centring, the plumb bob can be used for centring. To use, unwind the plumb bob and attach it to the hook inside the centring screw. Use the cord grip piece to adjust the cord length.

### 2) Tubular compass CP7 (accuracy $\pm 1^{\circ}$ )

To mount the CP7, slide it into the tubular compass slot **(D)**. To use, loosen the clamping screw to free the compass needle. Turn the instrument in the face left position until the compass needle bisects the index lines. The telescope is now aligned with magnetic north. After use, tighten the clamp and remove the compass from the slot. Replace it in the specified position in the carrying case.

### APPENDIX 7: OPTIONAL ACCESSORIES



#### 1) Card reader SCR2

The card reader SCR2 can be used to read data stored on the card and transfer it to a host computer. <SCR2 specifications>

AC power adapter:

AC100V
AC120V
AC220V
(Round pin plug)

Interface cable:

DOC22	NEC/EPSON
DOC23	IBM connector
DOC28	Toshiba J3100

Input/output: RS232C compatible

Operation temperature range:

0 to 50°C (32 to 122°F) 450g (1 lb)

#### 2) Interface cables DOC1, DOC25/DOC26/DOC27

Weight:

The interface cable DOC1 can be used for direct two-way communication between the SET C and a host computer.

This cable is not provided with a connector on the computer end of the cable.

Also available are:

DOC25: NEC connector DOC26: IBM connector DOC27: Toshiba J3100



SET CI

Interface cables DOC1/DOC25/DOC26/DOC27

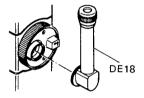


Host computer



#### 3) Memory card SDC5/SDC6

SDC5







Measured and input data can be recorded by the SET C on SDC5 or SDC6 cards.

#### SDC5: 128Kbyte

One 128Kb card can store approximately 2000 measured target points in angle and distance (S, V, H) format.

#### SDC6: 256Kbyte

One 256Kb card can store approximately 4000 measured target points in angle and distance (S, V, H) format.

#### 4) Diagonal eyepiece DE18

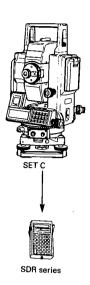
The diagonal eyepiece is convenient for near-vertical observations and in places where space around the instrument is limited. Remove the handle and the telescope eyepiece by unscrewing the mounting ring, and screw in the diagonal eyepiece.

### 5) Solar filter OF2/OF2A, OF1/OF1A

For observations made facing the sun, and where glare is present. The OF2/OF1 and OF2A/OF1A (flip-up) filters are mounted on the objective lens.

OF2, OF2A:for SET2C, SET3C OF1, OF1A:for SET4C







Host computer

### 6) Electronic field book SDR series

The SDR series collects and stores slope distance, zenith and horizontal angle data from the SET C.

Calculations can be performed on the data so that the measurements can be verified in the field. The stored data can be transmitted to a data processing system. <SDR series specifications>

Power source: "AAS" (SUM3)x4 Memory type: CMOS

RAM 32, 64 or 128 K ROM 64 K Keyboard: 33 keys Display: LCD Baud rate: 300,600,1200,

2400,4800, 9600 bps

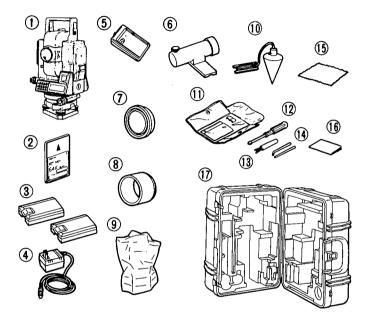
Operating temperature range:

Weight:

0 to 50°C(32 to 122°F) 450g (1 lb)

### STANDARD EQUIPMENT

• Please verify that all equipment is included.



1	Plumb bob1
1	Tool pouch1
(2)	Screwdriver1
1	Lens brush1
	Adjusting pin2
働	Cleaning cloth1
€	Operator's manual1
	2-way communication
	manual 1
	Field guide 1
ـ	Carrying case1

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### MAINTENANCE

- Wipe off moisture completely if the instrument gets wet during survey work.
- 2) Always clean the instrument before returning it to the case.

The lens requires special care. Dust it off with the lens brush first, to remove minute particles. Then, after providing a little condensation by breathing on the lens, wipe it with a soft clean cloth or lens tissue.

- Bo not wipe the displays G, G and keyboard G or carrying case with an organic solvent.
- 4) Store the SET C in a dry room where the temperature remains fairly constant.
  - 5) If the battery is discharged excessively, its life may be shortened. Store it in a charged state.
    - 6) Check the tripod for loose fit and loose screws.

    - 8) When the instrument is not used for a long time, check it at least once every 3 months.
    - 9) When removing the SETC from the carrying case, never pull it out by force. The empty carrying case should then be closed to protect it from moisture.
    - 10) Check the SET C for proper adjustment periodically to maintain the instrument accuracy.

### **SPECIFICATIONS**

#### Telescope

#### Length:

SET2C:177mm SET3C:177mm SET4C:170mm 45mm 30X 3" Erect 1'30' (26m/1000m) 1.3m (4.3 ft) Bright or dim settings (Selectable with parameter)

#### Angle measurement

Horizontal and Vertical circles type :	Incremental with 0 index
Display range:	SET2C:-1999° 59' 59" to 1999° 59' 59"
	(–1999.9998gon to 1999.9998gon)
	SET3C:1999° 59' 59" to 1999° 59' 59"
	(1999.9998gon to 1999.9998gon)
	SET4C:-1999° 59' 55" to 1999° 59' 55"
	(–1999.999gon to 1999.999gon)
Minimum display:	SET2C:1" (0.2mgon)/5" (1mgon)
	SET3C:1" (0.2mgon)/5" (1mgon)
	SET4C:5" (1mgon)/10" (2mgon)
	(Selectable with parameter)
Angle units:	Degree/Gon
	(Selectable with parameter)
Accuracy:	Standard deviation of mean of measurement taken in positions I and II (DIN18723)
	SET2C:2" (0.6mgon)
	SET3C:3" (1mgon)
	SET4C:5"(1.5mgon)
Measuring time:	Less than 0.5sec





Automatic compensator: Type: Minimum display:

Range of compensation: Measuring mode: Horizontal angle:

Vertical angle:

Selectable ON/OFF with parameter Liquid, 2-axis tilt sensor SET2C:1" (0.2mgon) SET3C:1" (0.2mgon) SET4C:5" (1mgon) ±3'

Right/Left/Repetition/Hold (Selectable with keyboard) Zenith 0° (0gon)/Horizontal 0° (0gon)/ Horizontal 0°±90° (0gon ±100gon) (Selectable with parameter)

#### Distance measurement

Measuring	range:
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SET2C:	
SET3C:	
SET4C:	

Accuracy: Fine measurement:

Coarse measurement: Minimum display: Fine measurement: Coarse measurement: Tracking measurement: Maximum slope distance: Distance unit:

- 10

(Slight haze, visibility about 20km, sunny periods, weak scintillation)
2C: Compact prism CP01:1.3m to 800m (2600ft) Standard prism APx1:1.3m to 2400m (7800ft) Standard prism APx3:1.3m to 3100m (10100ft) Standard prism APx9:1.3m to 3700m (12100ft)
3C: Compact prism CP01:1.3m to 700m (2200ft) Standard prism APx3:1.3m to 2200m (7200ft) Standard prism APx3:1.3m to 2900m (9500ft) Standard prism APx9:1.3m to 3500m(11400ft)
4C: Compact prism CP01:1.3m to 1200m(3900ft) Standard prism APx3:1.3m to 1200m(3900ft) Standard prism APx3:1.3m to 2200m(7200ft) Standard prism APx3:1.3m to 2200m(3900ft) Standard prism APx3:1.3m to 1200m(3900ft) Standard prism APx3:1.3m to 1200m(3900ft) Standard prism APx3:1.3m to 1700m(5500ft) Standard prism APx3:1.3m to 2200m(7200ft) (Standard prism APx9:1.3m to 2200m(7200ft) (S

- SET2C: 3mm+2ppm D SET3C: 3mm+3ppm • D SET4C: 5mm+3ppm • D 5mm+5ppm • D
- 1mm (0.01 ft) 1mm (0.01 ft) 10mm (0.1 ft) 9999.999m (32808.33 ft) metres/feet (Selectable with parameter) (Changeable for 5 seconds with keyboard)

Moscuring time:

weasuning time.	(when criticorrection is not being applied.)			
	Fine meas.	Coarse meas.	Tracking meas.	
Slope distance	4.7 + every 3.2s	1.7 + every 0.7s	1.6 + every 0.3s	
Horizontal distance	4.7 +	1.9 +	1.8 +	
Height difference	every 3.3s	every 0.7s	every 0.3s	
Coordinates	5.1+ every 3.3s	2.4 + every 0.7s	2.2 + every 0.7s	
REM	0.7s + every 0.5s			
Horizontal distance between two points	5.6 + every 3.3s	2.9 + every 0.7s	2.8 + every 0.7s	

Atmospheric correction:

Temperature input range:

Pressure input range:

ppm input range: Prism constant correction: Earth-curvature and refraction correction: Audio target acquisition: Signal source: Light intensity control: -30°C to 60°C (in 1°C steps)/ -22°F to 140°F (in 1°F steps) (Selectable with parameter) 500mbar to 1400mbar (in 1mbar steps) 375mmHg to 1050mmHg (in 1mmHg steps) 14.8inchHg to 41.3inchHg (in 0.1inchHg steps) (Selectable with parameter) -499 to 499ppm (in 1ppm steps) -99mm to 99mm (in 1pm steps) ON (K=0.142/K=0.20)/OFF (Selectable with parameter) ON/OFF (Selectable with parameter) Infrared LED Automatic

(When "C+B correction" is not being enalised)

#### **Power supply**

Power source: Working duration at 25°C (77°F): Ni-Cd rechargeable battery, BDC25 (6V) Distance & Angle measurement: 2.5 hours (2500 to 2600 points) (Coarse and Single measurement, Measurement interval=every 4 secs) Angle measurement only: 7.5 hours Using optional battery BDC12 Angle and distance: 10 hours

Charging time: CDC11/11D/11E: CDC27:

#### General

Display:

Sensitivity of levels: Plate level:

Circular level: Optical plummet: Image: Magnification: Minimum focus: Self-diagnostic function: Power saving cut off:

Operating temperature: Data recording: Card battery type:

Data input/output: Size:

Weight:

3

3

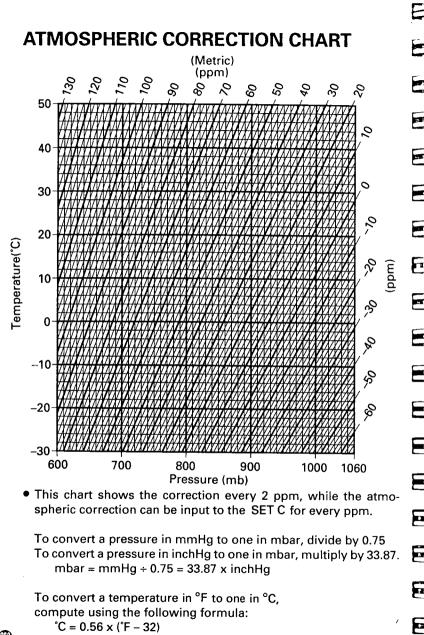
15 hours 80 minutes

2LCD dot matrix displays on each faceMain display:16 characters x 3 linesSub display:4 characters x 3 lines

SET2C:20" /2mm SET3C:30" /2mm SET4C:30" /2mm 10'/2mm

Frect 3x 0.1m (0.3ft) Provided 30minutes after operation/ ON/OFF with switch (Selectable with parameter) -20°C to 50°C (-4°F to 122°F) Non-contact Memory card, 64Kbytes Sony CR2016 lithium battery or a battery of similar quality Lifetime:2 years Asynchronous serial, RS-232C compatible 236mm (9.3inch) from tribrach bottom, 193mm (7.6inch) from tribrach dish SET2C:181(W)X177(D)X371(H)mm SET3C:181(W)X177(D)X371(H)mm SET4C:181(W)X170(D)X371(H)mm (Without handle: H:330mm) SET2C:7.5Kg SET3C:7.5Kg SET4C:7.4Kg (with internal battery and card)

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°C = 0.56 x (°F – 32)

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